Modulation Schemes for Single-Phase B6 Converters With Two Asymmetrical Terminal Voltages

Qin, Zian; Loh, Poh Chiang; Blåbjerg, Frede

Published in:
IEEE Transactions on Industrial Electronics

DOI (link to publication from Publisher):
10.1109/TIE.2015.2464296

Publication date:
2016

Document Version
Accepted author manuscript, peer reviewed version

Link to publication from Aalborg University

Citation for published version (APA):
Modulation Schemes for Single-Phase B6 Converters with Two Asymmetrical Terminal Voltages

Zian Qin, Student Member, IEEE, Poh Chiang Loh, and Frede Blaabjerg, Fellow, IEEE

Abstract—B6 converter uses six switches divided equally among three phase-legs. It has commonly been used as a three-phase rectifier or inverter, mostly under balanced conditions. Three-phase conversion is however not the only area, where B6 converter has been used. The same topology has been tried for single-phase power decoupling and single-phase ac-dc-ac conversion, where comparably lesser switches are needed. Although the basic modulation principle is still reliant on three modulating references for the three phase-legs, requirements imposed on the modulating references are different and usually asymmetrical. How these asymmetrical references should be formulated to meet various performance specifications of a single-phase B6 converter is the theme of this paper. Simulation and experimental results have been obtained for verifying the modulation schemes proposed.

Index Terms—Single phase, ac-dc-ac converter, B6 converter, reduced switch converter, modulations.

I. INTRODUCTION

Although many power converter topologies have been developed over the years, the voltage-source B6 converter has retained its importance to the industry. One of the reasons is its topological simplicity, which as indicated in Fig. 1(a), is simply three phase-legs connected in parallel, sharing a common dc-link capacitor. Each phase-leg has two switches with accompanied anti-parallel diodes. These switches cannot be turned on simultaneously to avoid shorting the dc capacitor. They should therefore be switched in complement (e.g. \( S_1 = S_2 \)) except during dead-time when both switches are intentionally turned off for a short duration. This requirement and many operating issues of the B6 converter are presently well-understood, and hence less costly to adopt, as compared with a brand new topology. It is thus attractive to the industry, mostly as a three-phase converter found in motor drives [1], [2], grid interfacing converters [3], [4] and power quality conditioners [5], [6].

As a three-phase converter, the B6 converter is usually not tied to the star-point of the load or source, which in turn, allows it to be modulated differently by adding a common triplen offset to its three modulating references. The offset, when sized properly, gives rise to significant performance boosting in terms of better spectral quality, higher modulation index, lesser power losses or a combination of them [7-13]. Popular examples include offsets used with continuous centered modulation, 60°-discontinuous modulation and 30°-discontinuous modulation reviewed in [9]. The addition of offset has subsequently been demonstrated in [10] to be equivalent to the explicit space vector modulation, which certainly, is expected since it is still the switching of the same B6 converter. It is therefore possible to derive the other as long as one of them is defined.

Regardless of which method is chosen, modulation of three-phase B6 converter is presently well-established, especially under balanced terminal voltage condition. It should however be noted that B6 converter is not only used as a three-phase converter. It can also operate as a reduced-switch single-phase ac-dc-ac converter [14-16] or a single-phase converter with power ripple decoupling [17-22]. The reduced-switch ac-dc-ac B6 converter was, in fact, proposed in year 2000 for replacing two full-bridges with four phase-legs connected back-to-back. It has since been commonly cited for comparison with other reduced-switch converters proposed in [23-26], where the main concerns mentioned with the B6 converter are its more restrictive input-output frequency selection and higher dc-link voltage demanded. These concerns have limited the scope of the B6 converter as a single-phase ac-dc-ac converter, but it is still suitable for use with an uninterruptible power supply (UPS) or a power conditioner [14-16], where input and output frequencies are the same.

Another usage of the B6 converter is as a single-phase converter with power ripple decoupling [17-22]. The three phase-legs in this case are divided such that one of them is connected to the intended single-phase ac system, and another is connected to a small film capacitor. The last phase-leg is shared between the ac system and film capacitor as their common return path. Any double-line-frequency power ripple contributed by the ac system can then be diverted to the film capacitor, rather than disturbing the dc side of the converter. Placing the film capacitor in this manner has the advantage of requiring only ac fundamental voltage across the capacitor, which in general, demands a smaller capacitance and simpler control. Recent work in [22] has also shown that with proper modulation, the dc-link voltage required by the B6 converter for power ripple decoupling can be reduced, which although is important, is only one requirement out of a few that can be optimized.
It is therefore clear that the B6 converter is not only a three-phase converter. It can be used as a single-phase converter with mostly asymmetrical terminal voltage and modulation requirements. These requirements are comparatively less studied, and are hence studied here to explore schemes that can minimize dc-link voltage, selected current ripple, total power loss, differences in switch thermal stresses or a combination of them. Simulation and experimental results have been obtained for validating the modulation schemes presented, before concluding the challenges resolved by them.

II. B6 CONVERTER

The B6 converter is shown in Fig. 1(a), configured as a single-phase converter with two sets of ac terminals. The terminals can be connected to an ac source and an ac load, or a small film capacitor for power ripple decoupling. If the single-phase ac source and load are replaced by a three-phase source or load, the B6 converter then operates as a three-phase converter widely used in the industry. Whether as a source or load, the B6 converter then operates as a three-phase source and load are replaced by a three-phase small film capacitor for power ripple decoupling. If the terminals can be connected to an ac source and an ac load, or a single-phase converter under unbalanced single-phase converter with two sets of ac terminals. The terminals can be connected to an ac source and an ac load, or a small film capacitor for power ripple decoupling. If the single-phase ac source and load are replaced by a three-phase source or load, the B6 converter then operates as a three-phase converter widely used in the industry. Whether as a source or load, the B6 converter then operates as a three-phase source and load are replaced by a three-phase small film capacitor for power ripple decoupling. If the terminals can be connected to an ac source and an ac load, or a single-phase converter under unbalanced condition, terminal voltages of the B6 converter will usually be asymmetrical even though some differences still exist between them. To illustrate, the single-phase B6 converter shown in Fig. 1(a) is considered, where a shared phase-leg between the source and load can clearly be seen. Current flowing through this phase-leg is given by the sum of return currents from the source and load, which in most cases, cancel each other prominently. This cancellation is an advantage of the B6 converter, which must usually be present before the B6 converter will be considered for single-phase applications.

As a single-phase converter, the B6 converter must be modulated accordingly. The simplest reference-carrier arrangement that can be used by it is probably shown in Fig. 1(b). Expressions for the references ($Ref_a$, $Ref_b$ and $Ref_c$) and their generated voltages ($v_{ab}$ and $v_{cb}$) at the converter terminals are given in (1), where $M_{ab}$ and $M_{cb}$ are modulation indexes, $\omega_1$ is the angular fundamental frequency, and $\varphi_1$ is the phase between the two generated voltages.

\[
\begin{align*}
Ref_a &= M_{ab}\sin(\omega_1 t) \\
Ref_b &= 0 \\
Ref_c &= M_{cb}\sin(\omega_1 t + \varphi_1) \\
v_{ab} &= 0.5V_{dc} \times M_{ab}\sin(\omega_1 t) \\
v_{cb} &= 0.5V_{dc} \times M_{cb}\sin(\omega_1 t + \varphi_1)
\end{align*}
\] (1)

The main feature of the arrangement is a simple zero reference assigned to the shared phase-leg, which will certainly help if the input and output frequencies are different. The zero reference will however burden the converter unnecessarily if the two frequencies are similar like assumed in (1). More specifically, the dc-link voltage needed by the B6 converter will be doubled that needed by two full-bridges connected back-to-back, if the arrangement shown in Fig. 1(b) is used for modulation. This doubled dc-link voltage and its accompanied higher stresses will usually render the B6 converter as unattractive even though it uses two lesser switches than the two full-bridges. The reference-carrier arrangement shown in Fig. 1(b) is therefore not recommended if the B6 converter operates with a single common frequency.

III. CONTINUOUS MODULATION

A. Centered Modulation

Referring to (1) and Fig. 1(b), the relative placement of the three references, treated as a whole, within the carrier band does not have to be fixed so long as their vertical spacing and sequence produce the desired ac voltages $v_{ab}$ and $v_{cb}$ in (1). Their relative placement can hence be varied to create different performance advantages for the B6 converter. This is similar to the addition of triplen offset to a three-phase converter, but with asymmetry introduced. The modulation objectives expected from a single-phase B6 converter may therefore differ, even though some like keeping the converter dc-link voltage low remains unchanged. The converter dc-link voltage can indeed be minimized by centering the three references, treated as a whole, along the horizontal axis. In other words, it means the maximum and minimum references must have the same absolute magnitude, but of opposite
polarity. Such placement can be realized by adding a common offset $M_{off,c1}$ to (1), to give those modified references $Ref_a^c$, $Ref_b^c$ and $Ref_c^c$ in (2).

$$
\begin{align*}
Ref_a^c &= Ref_a + M_{off,c1} \\
Ref_b^c &= Ref_b + M_{off,c1} \\
Ref_c^c &= Ref_c + M_{off,c1} \\
M_{off,c1} &= -\frac{\max(Ref_a, Ref_b, Ref_c) + \min(Ref_a, Ref_b, Ref_c)}{2} \\
\end{align*}
$$

(2)

Although $M_{off,c1}$ in (2) is similar to that used for three-phase balanced modulation, its significance is more prominent here in terms of determining the minimum dc-link voltage needed. This is unlike three-phase balanced modulation, where the minimum dc-link voltage needed is pretty obvious. To illustrate how the minimum dc-link voltage needed by the single-phase B6 converter can be determined, variations of (2) are drawn in Fig. 2, where the largest peak among the three modified references is noted as $M_{PK,max}$. Value for $M_{PK,max}$ can generally be determined using (3).

$$
M_{PK,max} = \max(M_{ab}, M_{cb}, M_{ac})/2
$$

(3)

where $0.5V_{dc} \times M_{ac}$ is the magnitude of $v_{ac} = v_{ab} - v_{cb}$ computed using ac terminal voltages defined in (1). Value of $M_{ac}$ can further be computed using (4) based on simple geometry.

$$
M_{ac} = \sqrt{M_{ab}^2 + M_{cb}^2 - 2M_{ab}M_{cb}\cos\phi}
$$

(4)

To retain its linear characteristics, the carrier $M_{tri}$ used for comparison with the references in (2) must hence be either equal or larger than $M_{PK,max}$, which in terms of expression, is given in (5).

$$
M_{tri} \geq M_{tri,min} = M_{PK,max} = \max(M_{ab}, M_{cb}, M_{ac})/2
$$

(5)

where $M_{tri,min}$ is the smallest carrier peak necessary, which in terms of basic modulation principle, is also the smallest normalized dc-link voltage needed without causing over-modulation. Centering of all three references therefore has the advantage of identifying the smallest dc-link voltage easily.

From Fig. 1(b), it is also obvious that the reduction of carrier peak achievable is the least when maximum of one reference ($Ref_a$ or $Ref_c$) coincides with minimum of the other. This happens when both references in Fig. 1(b) are $180^\circ$ out of phase or when they have unsynchronized frequencies (e.g. $\omega_a > \omega_c$ and $\omega_a/\omega_c \neq k$, where $k$ is an integer, and $\omega_a$ and $\omega_c$ are different frequencies of $Ref_a$ and $Ref_c$, respectively). A higher dc-link voltage is thus needed in those cases, which may shadow the reduced-switch feature of the B6 converter when used as a single-phase converter. The B6 converter is thus more likely to be used for applications with a common terminal frequency and a phase shift that permits a much smaller dc-link voltage to be used. Some possibilities are UPS, power conditioner [14-16], and converter with power ripple decoupling [17-22], as also mentioned in Section I.

B. Partially Centered Modulation

The centered modulation scheme in Section III(A) places the three references centrally within the carrier band, which for a three-phase balanced converter, is attractive since current ripples from all three phases are reduced uniformly. However,
for an asymmetrical single-phase B6 converter, reducing the current ripples uniformly may not be necessary. For example, with the ac load of the single-phase B6 converter shown in Fig. 1(a) replaced by a film capacitor for power ripple decoupling, current flowing through the ac source may demand lower ripple than current flowing through the film capacitor. In that case, references for the two phase-legs tied to the source should be centered, rather than centering all three references. Such two-reference centering can be implemented by dividing the source voltage $v_{ab}$ equally between the two references. The modified references $Ref_a^{C^r}$, $Ref_b^{C^r}$ and $Ref_c^{C^r}$ then become (6), after adding the common offset $M_{off,c2}$ to (1).

\[
\begin{align*}
Ref_a^{C^r} &= Ref_a + M_{off,c2} \\
Ref_b^{C^r} &= Ref_b + M_{off,c2} \\
Ref_c^{C^r} &= Ref_c + M_{off,c2} \\
M_{off,c2} &= -0.5 \times (Ref_a + Ref_b)
\end{align*}
\]

For the considered example, $M_{off,c2} = -0.5Ref_a = -0.5M_{ab}sin(\omega_1 t)$, which when substituted to (6), results in those two possible reference-carrier arrangements shown in Fig. 3(a) and (b). In both figures, the carrier peak is marked as $M_{Tri}$, which in theory, will have the same minimum value $M_{Tri,min}$ given in (5). In practice, a small safety margin may however be added to $M_{Tri,min}$ for avoiding over-modulation. This is strictly a recommendation rather than a necessary requirement.

The eventual carrier peak chosen is found to be large enough in Fig. 3(a) for confining all references within the carrier band. Fig. 3(a) therefore does not require further modification. On the other hand, the left diagram in Fig. 3(b) has a reference $Ref_c^{C^r}$ exceeding the carrier band during $T_1$ and $T_2$. It is therefore not immediately applicable. Instead, the three references during $T_1$ must be shifted down equally until the modified $Ref_c^{C^r}$ clamps to the carrier peak like shown in the right diagram of Fig. 3(b). Further downward shifting is also possible, but will worsen the centering of the modified $Ref_a^{C^r}$ and $Ref_b^{C^r}$ within the carrier band. It is therefore not encouraged if the objective is to minimize current ripple from those phase-legs modulated by $Ref_a^{C^r}$ and $Ref_b^{C^r}$. The same shifting must be applied during $T_2$, but instead of shifting down, the references must be shifted up until $Ref_c^{C^r}$ clamps to the carrier trough. With the shifting included, (6) changes to (7), where the additional offset introduced for shifting is notated as $M_{off,c3}$.

\[
\begin{align*}
Ref_a^{C^r} &= Ref_a + M_{off,c3} \\
Ref_b^{C^r} &= Ref_b + M_{off,c3} \\
Ref_c^{C^r} &= Ref_c + M_{off,c3}
\end{align*}
\]

\[
M_{off,c3} = \begin{cases} 
0, & \text{if } (Ref_a^{C^r},Ref_c^{C^r},Ref_b^{C^r}) \leq M_{Tri} \\
sgn(Ref_c^{C^r}) \times M_{Tri} - Ref_c^{C^r}, & \text{if } |Ref_c^{C^r}| > M_{Tri} \\
M_{Tri} \geq M_{Tri,min}
\end{cases}
\]

where $sgn()$ is a function for returning the polarity of parameter enclosed by its parentheses.

To demonstrate the reduction of current ripple, mathematical formulation can be derived from those terminal...
Fig. 6. Reference-carrier arrangements obtained with the discontinuous scheme when (a) \( \varphi_1 \) and \( \varphi_2 \) are close in magnitude and phase, and (b) \( \varphi_1 = \pi/4 \).

pulse voltage and current waveforms shown in Fig. 4(a) and (b) for the assumed example. In those figures, \( \text{Ref}_1 \) and \( \text{Ref}_2 \) are for representing either \( \text{Ref}_a^{\text{Cr}} \) or \( \text{Ref}_b^{\text{Cr}} \), depending on which is higher at the instant of consideration. They are shifted up like in Fig. 4(a) when in interval \( T_2 \), and shifted down like in Fig. 4(b) when in interval \( T_1 \). Their respective peak current ripple \( \Delta i \) expressions can then be derived as (8) and (9), where \( T \) and \( L \) represent the half carrier period and ac filter inductance, respectively.

\[
L \times 2|\Delta i| = \frac{\text{Ref}_2 + 1}{2} \times 2T \times |v_{ab}| \quad (8)
\]

\[
L \times 2|\Delta i| = \frac{1 - \text{Ref}_2}{2} \times 2T \times |v_{ab}| \quad (9)
\]

Noting further that \( \text{Ref}_1 \geq \text{Ref}_2 \), (8) and (9) can be combined to give the general current ripple expression in (10).

\[
|\Delta i| = \max \left( \min \left( \text{Ref}_a^{\text{Cr}}, \text{Ref}_b^{\text{Cr}} \right) + 1, 1 - \max \left( \text{Ref}_a^{\text{Cr}}, \text{Ref}_b^{\text{Cr}} \right) \right) \times \frac{T}{2L} \times |v_{ab}| \quad (10)
\]

References from (7) can subsequently be substituted to (10) for computing the peak current ripple expected from the partially centered scheme. The same expression in (10) can also be used for computing current ripple expected from the centered scheme by simply replacing \( \text{Ref}_a^{\text{Cr}} \) and \( \text{Ref}_b^{\text{Cr}} \) with \( \text{Ref}_a^{\text{C}} \) and \( \text{Ref}_b^{\text{C}} \) from (2). The obtained current ripples are plotted in Fig. 5, together with ripple expected from a full-bridge converter, operating under the same ac and dc conditions. Comparison with the full-bridge converter is meaningful since the single-phase B6 converter has always been cited as the reduced-switch version of two full-bridges connected back-to-back. It ripple value is therefore included in Fig. 5, which is clearly the lowest since condition like \( \text{Ref}_c^{\text{C}} \) exceeding the carrier in Fig. 3(b) will not occur.

The condition in Fig. 3(b) must however be rectified when used with the partially centered B6 converter. Its current ripple drawn from the ac source is therefore higher than the full-bridge converter during \( T_1 \) and \( T_2 \) of the fundamental cycle. Length of \( T_1 \) and \( T_2 \), and the difference in ripple magnitude depend on the relative magnitude \( (M_{ab}, M_{cb}) \) and phase-shift \( \varphi_1 \) of the two ac voltages \( v_{ab} \) and \( v_{cb} \). For example, in Fig. 5(a) and (c), where a comparably small \( \varphi_1 = \pi/4 \) is used, both partially centered B6 and full-bridge converters are noted to have the same ripple throughout the fundamental cycle. The same observation applies to Fig. 5(d), where a larger \( M_{ab} \) than \( M_{cb} \) has been used. Current ripple of the partially centered B6 converter will, in fact, only be higher when \( \varphi_1, M_{cb} \) or both are comparably high like in Fig. 5(b). As explained, the higher ripple is attributed to the lengthened \( T_1 \) and \( T_2 \) in Fig. 3(b) as \( \varphi_1 \) and \( M_{cb} \) increase. Regardless of that, ripple from the partially centered scheme is still smaller than that of the centered scheme discussed in Section III(A). The centered scheme will, in fact, match the partially centered scheme only when both \( \varphi_1 \) and \( M_{cb} \) are small like in Fig. 5(c).

IV. DISCONTINUOUS MODULATION

Discontinuous modulation has been proposed for the B6 converter when it is used as a three-phase converter. Under balanced conditions, all three phases share the clamping equally, which means each phase will be clamped to either the upper or lower dc rail for 120°. Reduction in losses will then be spread among the three phases evenly. Such even spreading may however not be necessary when the B6 converter is used.
as an asymmetrical single-phase converter with a shared phase-leg. This phase-leg carries the return currents of the other two non-shared phase-legs, which preferably, should cancel each other significantly. Else, the B6 converter may not be as attractive as two back-to-back full-bridges even though it uses two lesser switches. It is therefore reasonable to assume that current flowing through the shared phase-leg is much smaller with significantly lower losses generated. The clamping objective should hence tilt towards reducing losses smaller with significantly lower losses generated. The current flowing through the shared phase-leg is much less than the other two non-shared phase-legs, which preferably, should be expressed as (12).

\[
\begin{align*}
M_{ab} \sin(\omega_t t_1) & = -M_{cb} \sin(\omega_t t_1 + \varphi_1) \\
\Rightarrow \omega_t t_1 & = \tan^{-1}\left(\frac{-M_{cb} \sin\varphi_1}{M_{ab} + M_{cb} \cos\varphi_1}\right) \\
M_{ab} \sin(\omega_t t_2) & = M_{cb} \sin(\omega_t t_2 + \varphi_1) \\
\Rightarrow \omega_t t_2 & = \tan^{-1}\left(\frac{M_{cb} \sin\varphi_1}{M_{ab} - M_{cb} \cos\varphi_1}\right)
\end{align*}
\]  

Considered an UPS with very close \(v_{ab}\) and \(v_{cb}\) [11], and a power ripple decoupling converter with \(v_{ab}\) and \(v_{cb}\) shifted by \(\pi/4\) [16], applying (11) to them then results in Fig. 6(a) and (b), respectively. These figures clearly exhibit positive and negative clamping by the two non-shared phase-legs only, which certainly, is anticipated. Their intervals of clamping are also not always evenly distributed, and will vary with magnitude ratio \((M_{ab}:M_{cb})\) and phase-shift \(\varphi_1\) between \(v_{ab}\) and \(v_{cb}\). Expressions for computing them can be derived after determining \(t_1\) and \(t_2\), which according to Fig. 6(a) and (b), can be expressed as (12). 

Total positive and negative clamping time for the non-shared phase-leg linked to \(v_{ab}\) is then given by \(\Delta T_{ab}\) in (13), which when subtracted from the fundamental period, gives the total clamping time \(\Delta T_{cb}\) for the other non-shared phase-leg linked to \(v_{cb}\).

\[
\Delta T_{ab} = \frac{2(t_1 - t_2)}{\omega_1}, \quad \text{if } t_1 \geq t_2 \\
\Delta T_{ab} = \frac{2(t_1 - t_2) + \frac{2\pi}{\omega_1}}{\omega_1}, \quad \text{if } t_1 < t_2 \\
\Delta T_{cb} = \frac{2}{\omega_1} \left(\tan^{-1}\left(\frac{-M_{cb} \sin\varphi_1}{M_{ab} + M_{cb} \cos\varphi_1}\right) - \tan^{-1}\left(\frac{M_{cb} \sin\varphi_1}{M_{ab} - M_{cb} \cos\varphi_1}\right)\right), \\
\text{if } M_{ab} \leq M_{cb} |\cos\varphi_1|, \varphi_1 \in [0, \pi] \\
\Delta T_{cb} = \frac{2}{\omega_1} \left(\tan^{-1}\left(\frac{-M_{cb} \sin\varphi_1}{M_{ab} + M_{cb} \cos\varphi_1}\right) - \tan^{-1}\left(\frac{M_{cb} \sin\varphi_1}{M_{ab} - M_{cb} \cos\varphi_1}\right)\right) + \frac{2\pi}{\omega_1}, \\
\text{if } M_{ab} > M_{cb} |\cos\varphi_1|, \varphi_1 \in [0, \pi] \\
\]  

(13) 

Variations of \(\Delta T_{ab}\) and \(\Delta T_{cb}\) are plotted in Fig. 7 by varying \((M_{ab}:M_{cb})\) and \(\varphi_1\), where \(1pu = \frac{2\pi}{\omega_1}\). They will mostly be different except when \(M_{ab} \approx M_{cb}\), at which, \(\Delta T_{ab}\) and \(\Delta T_{cb}\) are approximately equal regardless of how \(\varphi_1\) varies.

V. SIMULATION AND EXPERIMENTAL RESULTS

Simulations and experiments have been performed with the B6 converter functioning as a simple single-phase ac-dc-ac converter shown in Fig. 8. At its input terminal is an ac source of \(v_{ab} = 110\) V (RMS), which when rectified and controlled appropriately, provides a dc-link voltage of \(V_{dc} = 190\) V. This dc-link voltage is, in turn, inverted to give an output voltage of \(v_{cb} = 110\) V (RMS), but with a phase-shift of \(\varphi_1 = \pi/4\) introduced for better illustrating the intended voltage clamping. The output voltage is then applied to an ac filter and load combination consisting of \(L = 4.1\) mH and \(R = 15\) \(\Omega\), which in general, is fine for testing modulation concepts.

Frequencies of both input and output are also set to the same value of \(\omega = 2\pi \times 50\) rad/s, which as explained earlier, permits a much smaller dc-link voltage to be used. This can be illustrated by referring to (1) and Fig. 1(b), which when implemented, requires a dc-link voltage of at least...
2 \times 110\sqrt{2} = 311 V. On the other hand, the minimum dc-link voltage required by the proposed modulation schemes is 155.5 V, based on \( M_{\text{Tri}, \text{min}} \) computed from (5). Inclusion of a safety margin to avoid over-modulation then results in the value of \( V_{dc} = 190 V \) chosen for testing. This value is still much smaller than that demanded by the scheme from (1). The setup is then operated with the three proposed modulation schemes applied in turn. Results obtained from them are described as follows:

A. Continuous Modulation

Results obtained with the centered scheme from (2) and partially centered scheme from (7) are presented in Fig. 9 and Fig. 10, respectively. The centered scheme obviously switches all phase-legs continuously since its three modulating references are always centered within the carrier band without any clamping. Its accompanied current spectrum for \( i_a \) is plotted at the bottom of Fig. 9(b), which clearly, has a prominent harmonic cluster centered at the carrier frequency of 15.2 kHz. This cluster leads to a total harmonic distortion (THD) value of 2.9 % computed for \( i_a \) when modulated by the centered scheme from (2). On the other hand, the partially centered scheme has its harmonic cluster at 15.2 kHz reduced, which in terms of THD for \( i_a \), gives a smaller value of 2.5 %. As explained, this improvement is introduced by centering the two preferred references rather than all three references.

Such centering may however lead to discontinuous clamping of the phase-leg modulated by the non-centered reference, which in Fig. 3(b), is \( \text{Ref}_{c}^{\text{ot}} \). This clamping can clearly be seen in Fig. 10(a) and (b), which according to the loss distribution plots in Fig. 11, has helped to reduce switching losses from the clamped phase-leg. Loss distribution here is experimentally computed by measuring the individual switch currents and voltages at a high sampling rate, before multiplying them to obtain the switch losses offline. It should however be noted that clamping is not always introduced, and will, in fact, reduce to zero when magnitude of \( \text{Ref}_{c}^{\text{ot}} \) in Fig. 3(b) falls below the carrier peak. When that happens, the first harmonic cluster in Fig. 10(b) will also reduce to zero since the two preferred references are now always centered.

This expectation can also be deduced from Fig. 5(c) and (d), where the magnitude of \( v_{cb} \) is comparably smaller than that of
Fig. 9. Waveforms of the B6 converter in Fig. 1(a) obtained with the centered scheme from (2) and $\varphi_1 = \pi/4$.

(a) Simulated

(b) Experimental

Fig. 10. Waveforms of the B6 converter in Fig. 1(a) obtained with the partially centered scheme from (7) and $\varphi_1 = \pi/4$.

(a) Simulated

(b) Experimental

Fig. 11. Experimental per-switch loss distributions of B6 converter when modulated by the (a) centered scheme from (2) and (b) partially centered scheme from (7).
Fig. 5(a) and (b). With their smaller $v_{cb}$, performance of the partially centered B6 converter in Fig. 5(c) and (d) is found to match exactly with that of a full-bridge converter implemented with four phase-legs for ac-dc-ac conversion. Since the spectrum of a full-bridge converter does not have a harmonic cluster at the carrier frequency of 15.2 kHz, the partially centered B6 converter will also not have component at the same frequency. It is therefore appropriate to say that the first harmonic cluster in Fig. 10(b) will eventually reduce to zero when $Ref_c^{cer}$ in Fig. 3(b) falls below the carrier peak.

B. Discontinuous Modulation

For easier comparison, simulation and experiment with the discontinuous scheme expressed in (11) are performed with the same parameters indicated in Fig. 8. Its captured results are shown in Fig. 12, where clamping of only the two non-shared phase-legs can clearly be seen. Such clamping shifts the modulating references away from the center of the carrier band, and hence a poorer THD of 3.9 % computed for $i_a$. The poorer current quality can also be seen from the larger first harmonic cluster at 15.2 kHz plotted at the bottom of Fig. 12(b). The discontinuous scheme however leads to the improved loss distribution shown in Fig. 13, which like Fig. 11 for the continuous schemes, is computed offline from experimentally measured switch voltages and currents sampled at a fast rate. In contrast, unlike Fig. 11, the distribution in Fig. 13 is obviously more uniform. The poorer $i_a$ spectrum is therefore a tradeoff introduced by the lower total loss and improved loss distribution brought by the proposed discontinuous scheme.

C. Percentage Loss Comparison

Percentage loss generated by the B6 converter only without including the passive components can be computed by adding losses of all three phase-legs in either Fig. 11 or Fig. 13, and then dividing the sum by the nominal power of 800 W, as indicated in Fig. 8. The values computed are approximately 5.05 % ($= \frac{2 \times (6 + 4.2 + 4.4)}{800} \times 100\%$) for the centered modulation scheme, 4.95 % for the partially centered scheme and 4.55 % for the discontinuous scheme. Efficiency of the B6 converter is then computed by subtracting the percentage loss from 100 %, which is close to 95 % for all three modulation schemes. A Voltech PM3000A meter is also used for measuring efficiency of the full experimental system including passive components indicated in Fig. 8. The values read are 89.3 % for the centered scheme, 89.6 % for the partially centered scheme and 90.1 % for the discontinuous scheme. These values are reasonable considering that the passive inductors have not been optimized.

In addition, it should be noted from Fig. 9, 10 and 12 that the return current $i_b$ through the shared phase-leg is relatively significant for the system and parameters tested in Fig. 8. In cases where the return current can be reduced further, the converter efficiency will be raised further. This is especially true when $i_c$ and $i_a$ are close, which will then give a return current that is close to zero ($i_b = i_c - i_a \approx 0$). The B6 converter under those conditions will therefore likely be more efficient than two single-phase full-bridges connected back-to-back with the same dc-link voltage. The latter uses one additional phase-leg, and carries significant currents in all its phase-legs. It is therefore likely to be less efficient.

Fig. 12. Waveforms of the B6 converter in Fig. 1(a) obtained with the discontinuous scheme from (11) and $\varphi_a = \pi/4$. ($v_{oa}$, $v_{ob}$, $v_{oc}$: 200 V/div; $i_a$, $i_b$, $i_c$: 5 A/div; Spectrum: 10 dB/div, 10 kHz/div)

Fig. 13. Experimental per-switch loss distribution of B6 converter when modulated by the discontinuous scheme from (11).
VI. CONCLUSIONS

Continuous and discontinuous modulation schemes have been proposed for the B6 converter when used as a single-phase converter with two sets of ac terminals. The continuous centered scheme, in particular, helps to identify the minimum carrier peak needed for linear modulation, and hence the minimum dc-link voltage needed by the converter. The same minimum dc-link voltage can be ensured by the partially centered scheme, which instead of all references, centers only the two chosen references. Current flowing through phase-legs modulated by these two references will then have better spectral quality. The discontinuous scheme, on the other hand, has its loss distribution improved by clamping only the two non-shared phase-legs with higher losses. Losses of the three phase-legs are therefore brought closer at the expense of a poorer current quality when compared with the other two schemes. These different performance features have been observed in simulations and experiments, which indirectly, mean that the scheme chosen should be the one that better matches requirements of the application.

REFERENCES

Fredé Blaabjerg (S’86–M’88–SM’97–F’03) was with ABB-Scandia, Randers, Denmark, from 1987 to 1988. From 1988 to 1992, he was a Ph.D. Student with Aalborg University, Aalborg, Denmark. He became an Assistant Professor in 1992, an Associate Professor in 1996, and a Full Professor of power electronics and drives in 1998. His current research interests include power electronics and its applications such as in wind turbines, PV systems, reliability, harmonics and adjustable speed drives.

He has received 15 IEEE Prize Paper Awards, the IEEE PELS Distinguished Service Award in 2009, the EPE-PEMC Council Award in 2010, the IEEE William E. Newell Power Electronics Award 2014 and the Villum Kann Rasmussen Research Award 2014. He was an Editor-in-Chief of the IEEE TRANSACTIONS ON POWER ELECTRONICS from 2006 to 2012. He has been Distinguished Lecturer for the IEEE Power Electronics Society from 2005 to 2007 and for the IEEE Industry Applications Society from 2010 to 2011.