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Published in:
I E E Transactions on Vehicular Technology

DOI (link to publication from Publisher):
[10.1109/TVT.2021.3134836](https://doi.org/10.1109/TVT.2021.3134836)

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Publication date:
2022

Document Version
Accepted author manuscript, peer reviewed version

[Link to publication from Aalborg University](#)

Citation for published version (APA):
Zhang, L., Zhang, J., He, Y., Mao, C., Li, W., Wong, S-W., Mei, P., & Gao, S. (2022). A Single-Layer 10-30GHz Reflectarray Antenna for the Internet of Vehicles. *I E E Transactions on Vehicular Technology*, 71(2), 1480-1490. Advance online publication. <https://doi.org/10.1109/TVT.2021.3134836>

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A Single-Layer 10-30 GHz Reflectarray Antenna for the Internet of Vehicles

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Abstract—A novel ultra-wideband (UWB) reflectarray antenna for the Internet of Vehicles (IoV) is introduced in this paper. By simply connecting the neighboring reflectarray elements, the proposed reflectarray antenna achieves a remarkable radiation pattern bandwidth of 20 GHz, ranging from 10 GHz to 30 GHz. To explain the operating principles of the proposed reflectarray antenna, the equivalent circuit (EQC) model of the unit cell is built, which also provides an efficient and rapid way to analyze the performance of the proposed reflectarray element. It is found from the EQC analysis that the connected elements can achieve better reflection phase responses than conventional separated elements, thereby improving the array bandwidth. As a proof of concept, a 503-element reflectarray antenna simultaneously covering the vehicle-to-satellite bands (12.25-12.75 GHz/14.0-14.5 GHz/19.6-21.2 GHz/29.4-31.0 GHz), the 24-GHz short-range vehicle radar band (24.25-26.65 GHz) and the 5G millimeter-wave band (27.5-28.35 GHz) is designed, fabricated, and characterized. The experimental results demonstrate that the presented reflectarray antenna can maintain undistorted beams, high antenna gain, low cross-pol level, and moderate aperture efficiency over a bandwidth of 100%, i.e., from 10 to 30 GHz. With its simple and planar aperture as well as excellent performance, the proposed reflectarray antenna can be a promising candidate for vehicles that require reliable high data-rate satellite links and 5G millimeter-wave connections simultaneously.

Index Terms—Internet of Vehicles (IoV), reflectarray antenna, ultra-wideband (UWB) arrays.

I. INTRODUCTION

INTERNET of Vehicles (IoV) has drawn great attentions from academic and industry because of its huge research values and commercial interests over the past few years [1]. The development of the IoV can effectively alleviate or solve various problems caused by the rapid growth of vehicles, and greatly improves the transportation efficiency, safety and intelligence level [2]. One of the key technologies for the

This work was supported in part by National Natural Science Foundation of China under Grants 61801299 and 62071306, in part by the Natural Science Foundation of Guangdong Province under Grant 2020A1515011037, and in part by the Shenzhen Science and Technology Program under grants JCYJ20200109113601723, and JSGG20180507183215520. (Corresponding author: Yejun He.)

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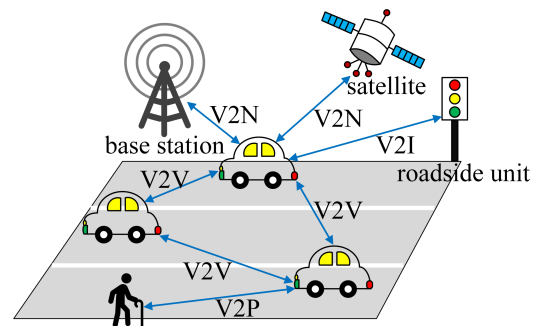


Fig. 1. Demonstration of the different communication links for the IoV.

success of the IoV is building a reliable high-speed communication system. Fig. 1 shows the different communication links for the IoV. As can be seen, IoV uses a new generation of information and communication technology to realize all-round links including the vehicle-to-network (V2N), vehicle-to-vehicle (V2V), vehicle-to-pedestrian (V2P), and vehicle-to-infrastructure (V2I) [3]. To provide a safer and more coordinated transportation network, additional communication links can be used [4]. For example, satellite communication has great potential in the application of the IoV due to the advantages of wide coverage, bandwidth flexibility, and high reliability [5]. Besides, the deployment of short-range vehicle radars, and 5G communication systems on board of vehicles also contributes to the functionality of IoV [6]. Short-range vehicle radars can provide situational awareness by detecting nearby objects in the form of distance, velocity and angle information, which benefits vehicle safety for IoV [7]. Meanwhile, to enable high data rate for IoV, the 5G communication systems play a pivotal role, which can improve the system capacity, transmission scope, and spectrum efficiency [8]. As these systems work at different frequencies, normally several separate antennas need to be utilized for transmitting and receiving signals for different systems. However, this brings about several problems such as increased antenna blockage, electromagnetic interference, and reduced system capacity [9]. To solve these problems, a broadband, high-gain, and shared aperture antenna that can work at several frequency bands simultaneously is highly desired.

Reflectarray antenna has proven to be a reliable candidate for various applications due to their low profile, high gain, low cost, and simplified feeding [10] and has already been applied to automotive vehicles [11]. However, reflectarray antennas generally have narrow bandwidth due to the inherent

narrowband property of the elements and the differential spatial phase delay. If an ultra-wideband (UWB) reflectarray antenna can be realized, it would be a good candidate for achieving multiple functions, such as short-range vehicle radar, 5G mobile communication, and satellite communication, within in one single radiating aperture [12], [13]. To improve the bandwidths of the reflectarray antennas, various methods have been proposed in recent years [14]–[17]. In [18] and [19], the sub-wavelength unit cells were employed to broaden the bandwidth of the reflectarray antennas. In [20]–[22], the single-layer multi-resonance structures were used as the unit cells to expand the gain bandwidth of the reflectarrays. The multi-resonance unit cells can generate sufficient phase shift at different frequencies, and thereby a reduced phase error was achieved, resulting in an improved bandwidth.

As the bandwidths of the conventional reflectarray antennas rarely exceed one octave, an alternative way to meet the system requirement of multi-band operation is to employ the multi-band reflectarray antennas [23]–[26]. There are several methods that can be used to achieve a multi-band reflectarray antenna, such as the adoption of sub-wavelength rectangular grids at two bands [27], the Phoenix elements [28], the FSS design techniques [29], and the unit cell with two equilateral triangular patches of different sizes [11].

To date, there are few reported works focusing on reflectarrays that can support a multi-octave bandwidth. The concept of tightly coupled dipole array (TCDA) was introduced in the design of the reflectarray antenna in [30], which demonstrated a breakthrough of 3:1 bandwidth for reflectarray design. However, non-planar array aperture and interleaved substrates are used to implement the design concept, which results in rather bulky and unreliable array configuration. In order to restore the features of the planar array aperture, robust and reliable array configuration, and low fabrication cost of the reflectarray, it is highly desirable that the multi-octave bandwidth can be achieved with a fully planar reflectarray aperture.

This paper proposes a fully planar, single-layer, linearly polarized UWB reflectarray antenna that can cover the vehicle-to-satellite bands (12.25-12.75 GHz/14.0-14.5 GHz/19.6-21.2 GHz/29.4-31.0 GHz), the 24-GHz short-range vehicle radar band (24.25-26.65 GHz) and the 5G millimeter-wave band (27.5-28.35 GHz), simultaneously. The proposed antenna can be placed on the roof of the vehicles, similar to the scenario introduced in [11]. To the best knowledge of the authors, this is the first time that a single-layer reflectarray antenna can provide continuous bandwidth coverage from the X-band to the Ka-band with a single planar array aperture. Connected dipole elements are used to constitute the proposed reflectarray, which maintains undistorted beams and high antenna gain from 10 GHz to 30 GHz. In addition, the equivalent circuit (EQC) model of the unit cell is constructed to predict the element performance quantitatively, which provides an in-depth understanding of the antenna operating principles. Furthermore, the phase errors caused by the phase center variation of the feed horn and the differential spatial phase delay are elaborately compensated to keep a good array performance. With the merits of ultra-wide bandwidth, high antenna gain, single-layer planar aperture, and low fabrication

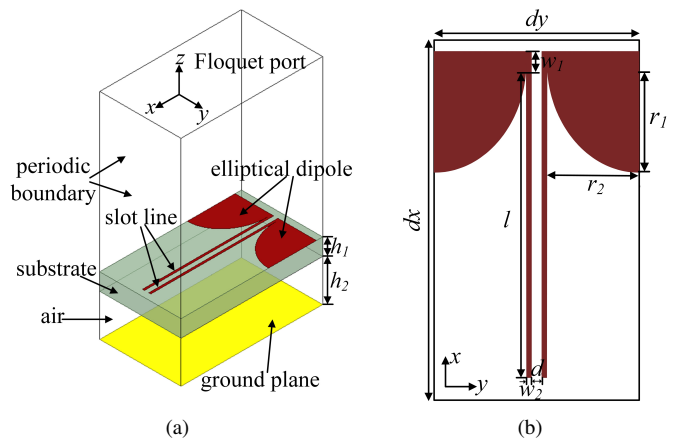


Fig. 2. Geometry of the proposed reflectarray unit cell. (a) Perspective view. (b) Top view.

TABLE I
GEOMETRICAL PARAMETERS OF THE REFLECTARRAY UNIT CELL (UNIT: MM)

w_1	w_2	r_1	r_2	dx	dy	h_1	h_2	d
0.2	0.1	2.1	1.75	6.8	3.9	0.813	2	0.2

cost, the proposed reflectarray antenna can be a promising candidate for IoV application and 5G millimeter-wave connections simultaneously. In this way, the vehicles can always maintain a reliable link with the satellite, the 5G base stations, and other vehicles.

The rest of this paper is organized as follows. The unit cell design and analysis are presented in Section II. Section III presents the design and analysis of the proposed reflectarray. Simulated and measured results and comparisons with other reported wideband reflectarrays are presented and discussed in Section IV. Finally, a conclusion is drawn in Section V.

II. UNIT CELL DESIGN AND ANALYSIS

A. Geometry of the Reflectarray Unit Cell

The geometry of the proposed reflectarray unit cell is illustrated in Fig. 2, which consists of an elliptical dipole, a slot line, and a ground plane. The elliptical dipole and slot line are printed on a 0.813 mm Rogers RO4003C substrate with the relative permittivity and loss tangent of 3.55 and 0.0027, respectively. By adjusting the length l of the slot line, different phase shifts can be achieved. An air layer with a height of h_2 is introduced between the substrate and the ground plane to improve the bandwidth performance of the reflectarray. The size of the unit cell is denoted by $dx \times dy$. Good reflection performance of the unit cell can be obtained within a wide operating band by choosing an appropriate dy and h_2 . Notice that there is no gap between the dipole end and the edge of the substrate, the adjacent dipole elements of the proposed reflectarray are thus directly connected with each other. With this arrangement, the proposed reflectarray can achieve an ultra-wide bandwidth, which will be discussed subsequently.

The geometrical parameters of the dipole unit cell are shown in Table I. It is noted that the value of dy is chosen to be 3.9

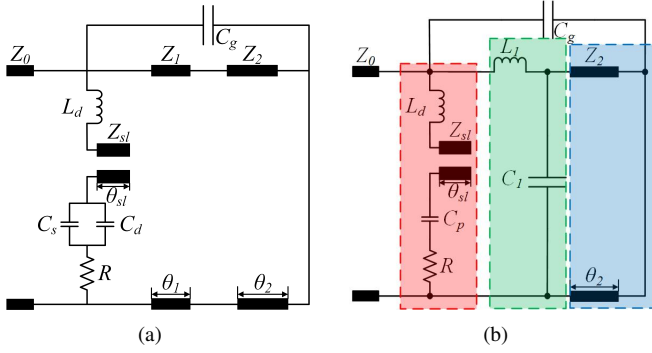


Fig. 3. EQC models of the proposed reflectarray unit cell. (a) General EQC model. (b) Simplified EQC model.

TABLE II
VALUES OF THE LUMPED CIRCUIT ELEMENTS

L_d	Z_{sl}	C_d	C_s	R	C_g
1.5451nH	175ohm	0.0112pF	0.0143pF	16ohm	0.01pF

mm for optimum unit cell performance, which is only 0.13λ at 10 GHz.

B. Equivalent Circuit Analysis of the Unit Cell

In order to better understand the operating principles of the proposed unit cell, an EQC model of the unit cell is established and shown in Fig. 3(a). In the EQC model, the inductor L_d and capacitor C_d in series are used to characterize the elliptical dipole, where L_d is caused by the induced current on the surface of the elliptical dipole. When the influence of the supporting dielectric substrate is considered, a shunt capacitor C_s is included to compensate the self-capacitance C_d [31]. The slot line is represented by an open-circuit transmission line with the characteristic impedance Z_{sl} and electrical length θ_{sl} . In the EQC model, the resistor R is included to represent the copper loss of the elliptical dipole and the dielectric loss of the substrate. The numerical values of L_d , C_d , C_s , and R in the equivalent circuit are individually calculated using the cascaded transmission matrices approach reported in [32] and [33]. It should be noted that the metallic ground plane is not considered when determining the values of the components in the EQC. In order to build a more accurate EQC model, the capacitance effect between the elliptical dipole and the metallic ground plane must be taken into consideration and thus a shunt capacitor C_g is included. Besides, the Rogers RO4003C substrate and the air layer are modeled by two transmission lines, and their characteristic impedance Z_d and electric length θ_d can be calculated through the following formulas.

$$Z_d = \frac{Z_0}{\sqrt{\epsilon_{rd}}} \quad (1)$$

$$\beta_d = k_0 \sqrt{\epsilon_{rd}} \quad (2)$$

$$\theta_d = h_d \beta_d \quad (3)$$

where the subscript d is replaced by 1 and 2 to represent the substrate and the air layer, respectively. The characteristic

impedance of the free space is denoted by Z_0 , while k_0 is the free space wave number. The detailed values of each EQC component are listed in Table II.

Based on the telegrapher's equation [34], the EQC model in Fig. 3(a) can be further simplified by replacing the transmission line (Z_1, θ_1) with a series inductor $L_1 = \mu_0 \mu_r h_1$ and a shunt capacitor $C_1 = \epsilon_0 \epsilon_r h_1 / 2$ [35]. Notice that the transmission line (Z_2, θ_2) is shorted by the ground plane, its input impedance can be directly calculated and thus is not replaced by inductors and capacitors for simplicity.

According to the transmission line theory [34], the input impedance of the open-circuit slot line Z_s and the grounded air layer Z_{ga} can be individually expressed by

$$Z_s = -jZ_{sl} \cot \beta l \quad (4)$$

$$Z_{ga} = jZ_2 \tan \beta_2 h_2 \quad (5)$$

Fig. 3(b) shows the simplified EQC model, where $C_p = C_s \parallel C_d$. As shown in Fig. 3(b), the EQC model of the unit cell is mainly composed of three parts which are enclosed in the three colored box. The circuit components in the red, green, blue box are used to describe the characteristics of the elliptical dipole and the slot line, the Rogers RO4003C substrate, and the grounded air layer, respectively. According to the circuit topology, the input impedance of the red colored part can be calculated by

$$Z_{Dipole} = R + j\omega L_d + Z_s + \frac{1}{j\omega C_p} \quad (6)$$

By connecting the input impedances of the three parts together, the input impedance of the proposed unit cell can be calculated as

$$Z_{RA} = \left\{ \left[\left(R + j\omega L_d + Z_s + \frac{1}{j\omega C_p} \right) \parallel \frac{1}{j\omega C_g} \right] + j\omega L_1 \right\} \parallel \frac{1}{j\omega C_1} \parallel Z_{ga} \quad (7)$$

By denoting the input impedance in the complex form as $Z_{RA} = R_{RA} + jX_{RA}$, the reflection coefficient of the unit cell can then be calculated by

$$\Gamma = |\Gamma| e^{j\angle \Gamma} = \frac{Z_{RA} - Z_0}{Z_{RA} + Z_0} \quad (8)$$

$$r(\omega, l) = 20 \lg |\Gamma|$$

$$\angle \Gamma = \varphi(\omega, l) = \arctan \left(\frac{2X_{RA}Z_0}{R_{RA}^2 + X_{RA}^2 - Z_0^2} \right)$$

where r is the magnitude of the reflection coefficient, φ is the phase of the reflection coefficient, ω is the angular frequency. It is observed from (8) that both the magnitude and the phase of the reflection coefficient depend on ω and l .

To explain why the connected element configuration is selected in this work, Fig. 4 shows the reflection phase of the unit cell with different element gaps (equals to $2d_1$). As shown by the inset of Fig. 4, the distance between the dipole tip and the unit cell boundary is denoted by d_1 . From Fig. 4, it

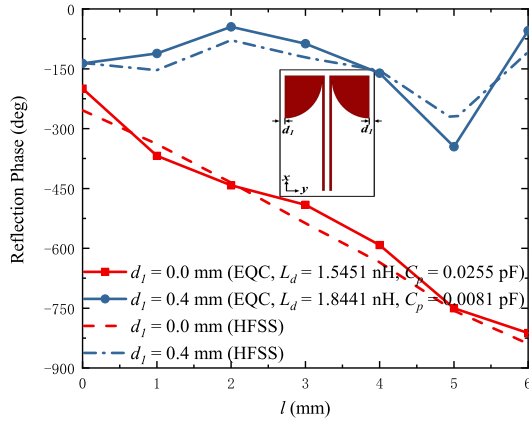


Fig. 4. Calculated results of the reflection phase versus the slot line lengths l at 28 GHz for different d_1 of the element by the EQC model and the full-wave simulation.

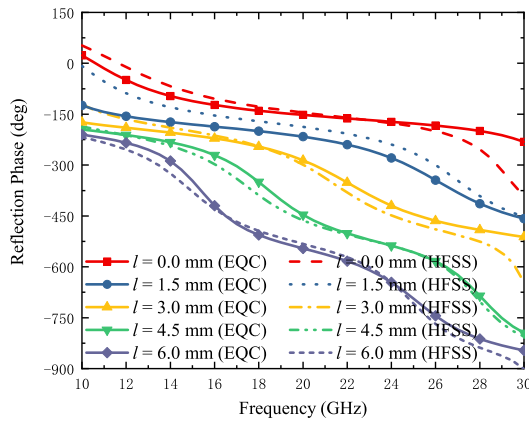


Fig. 5. Calculated reflection phases against frequency for different slot line lengths l by the EQC model and the full-wave simulation.

is observed that the decrease of d_1 results in better reflection phase response. When $d_1 = 0$, the slope of the reflected phase curve $p = \frac{\partial \varphi(\omega, l)}{\partial l}$ tends to be a nonzero constant, indicating that the reflected phase curve becomes rather linear with the increase of the slot line length l . The calculated results are validated by the full-wave simulation, demonstrating that the connected element arrangement ($d_1 = 0$) can achieve a better reflection phase response. It can be concluded from the EQC analysis that the connected element decreases the element self-inductance and increases the element self-capacitance. Consequently, good element reflection performance is maintained within an ultra-wide bandwidth.

C. Performance of the Reflectarray Unit Cell

The performance of the unit cell is evaluated by the EQC model and then verified by the full-wave simulation using the ANSYS HFSS. With the aid of the EQC model, the reflection performance of the unit cell can be optimized efficiently. To demonstrate the performance of the reflectarray unit cell, the reflection phases of the unit cell against frequency for different slot line lengths l are plotted in Fig. 5. As shown, the EQC results agree well with the full-wave simulation results, which

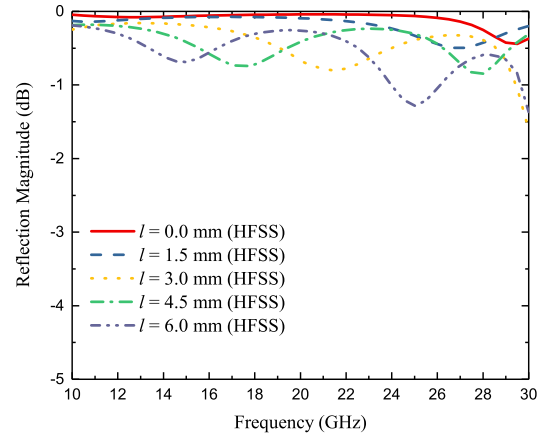


Fig. 6. Reflection magnitudes of the unit cell with different l .

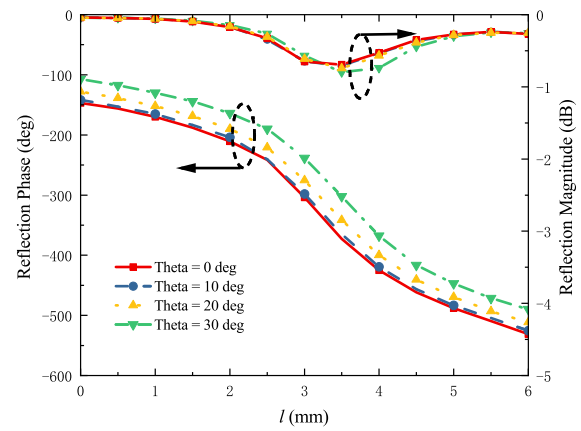


Fig. 7. Reflection magnitudes and phases of the unit cell under different oblique incident angles at 20 GHz.

verify the validity and accuracy of the proposed EQC model. Both the EQC results and the full-wave results demonstrate that the unit cell can provide sufficient phase shift over a wide frequency range. Fig.6 shows the reflection magnitudes of the unit cell with different slot line length l . As shown in this figure, the reflection loss is smaller than 0.5 dB over the whole bandwidth when l is smaller than 1.5 mm. In other cases, the average loss of the proposed unit cell is smaller than 1 dB.

Fig.7 shows the reflection magnitude and phase responses of the unit cell under different oblique incident angles. As shown in Fig. 7, the reflection magnitude variations are rather small under oblique incidence with the incidence angle up to 30°. Considering that the maximum incident angle from the horn to the aperture edge is smaller than 30°, the variation of the reflection phase under oblique incidence is still acceptable for most of the array elements.

III. REFLECTARRAY DESIGN AND ANALYSIS

A. Design of the Feed Antenna

To realize an UWB reflectarray, an UWB feed antenna with stable phase center is required. In this work, a double-ridged horn antenna (DRHA) is designed as the feed. The configuration of the proposed DRHA is shown in Fig. 8. As

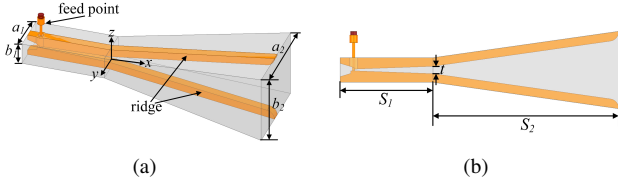


Fig. 8. Configuration of the DRHA. (a) Perspective view. (b) Side view.

TABLE III
PARAMETERS OF THE DRHA (UNIT: MM)

a_1	b_1	a_2	b_2	S_1	S_2	t
12.64	6.54	26.7	20.6	25	50	1.96

shown, two ridges are introduced to reduce the cut-off frequency of the TE_{10} mode, thereby improving the bandwidth of the horn antenna. By gradually increasing the ridge gap, a broadband impedance matching is achieved. The detailed geometry parameters of the DRHA are listed in Table III. Using the computer numerical control (CNC) machining, the DRHA is fabricated. The simulated and measured $|S_{11}|$ and realized gains of the DRHA are shown in Fig. 9. As shown, the feed horn can maintain $|S_{11}| < -15$ dB from 10 GHz to 30 GHz. The measured realized gains are ranged from 10.14 to 17.16 dBi, which is reasonably consistent with the simulated results.

Another issue to be concerned is the DRHA's phase center, which is changed with the frequency. To minimize the phase errors, the position of the phase center $p(x, y, z)$ of the feed antenna is calculated using the following equation.

$$p(x, y, z) = \sum_{f=f_1}^{f_2} \frac{p_f(x, y, z)}{N} \quad (9)$$

where $p_f(x, y, z)$ denotes the position of the phase center at the frequency f and N is the number of sampling frequency points from f_1 to f_2 . By using the information of $p_f(x, y, z)$ shown in Table IV, the phase center of the feed antenna can be finally determined.

B. Equivalent Distance Delay for Ultra-wideband Phase Compensation

The concept of equivalent distance delay has been proposed in [30] and [36], which explains that the differential spatial phase delay can be compensated appropriately in a certain band if the calculated equivalent distance delay keeps unchanged within the band. For a typical reflectarray, the following equation can be used to calculate the required phase distribution over the array aperture:

$$\Phi(x_i, y_i) = -k_0 \sin \theta_b (x_i \cos \theta_b + y_i \sin \varphi_b) + R_i k_0 \quad (10)$$

where $\Phi(x_i, y_i)$ is the required phase shift of each reflectarray unit cell, k_0 is the wave number in free space, and (θ_b, φ_b) is the beam direction of the reflectarray. The position of the i th reflectarray element on the array aperture is denoted by (x_i, y_i) , and the distance between the element and the phase

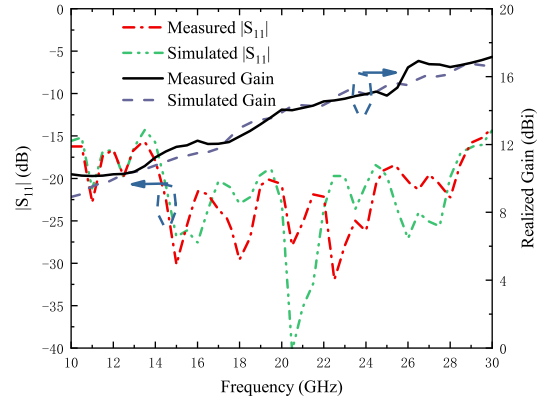
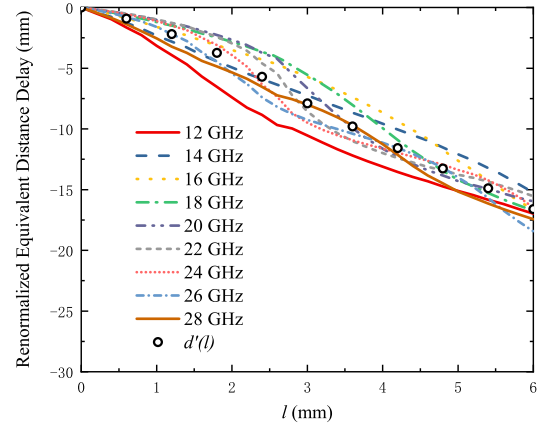
Fig. 9. Simulated and measured S_{11} and realized gains of the DRHA.

Fig. 10. Calculated renormalized equivalent distance delay of the proposed unit cell.

center of the feed antenna is R_i . In order to eliminate the effects of the frequency, the equation (10) is divided by k_0 and rewritten as

$$\Phi(x_i, y_i) / k_0 = -\sin \theta_b (x_i \cos \theta_b + y_i \sin \varphi_b) + R_i \quad (11)$$

Let

$$d(x_i, y_i) = \Phi(x_i, y_i) / k_0 \quad (12)$$

$$d'(x_i, y_i) = d(x_i, y_i) - d(x_1, y_1) \quad (13)$$

We could obtain

$$d'(x_i, y_i) = -\sin \theta_b [(x_i - x_1) \cos \theta_b + (y_i - y_1) \sin \varphi_b] + (R_i - R_1) \quad (14)$$

Here $d(x_i, y_i)$ is named as the required equivalent distance delay of the i th element, and $d'(x_i, y_i)$ is the renormalized equivalent distance delay to the corner element. As $d'(x_i, y_i)$ is independent of frequency, it can be used to compensate the differential spatial phase delay of an UWB reflectarray antenna.

The renormalized equivalent distance delay $d'(l, f)$ produced by the proposed reflectarray unit cell at different frequencies is also calculated according to (12) and (13), and demonstrated in Fig. 10, where $d'(l, f) = d(l, f) - d(l_1, f)$, $l_1 = 0$ mm. Although the renormalized equivalent distance

TABLE IV
POSITIONS OF THE DRHA PHASE CENTER AT DIFFERENT FREQUENCIES (UNIT: MM)

Frequency (GHz)	10	12	14	16	18	20	22	24	26	28	30
$p_f(x, y, z)$	(48.7,0,0)	(48.3,0,0)	(47.5,0,0)	(47.0,0,0)	(48.6,0,0)	(47.9,0,0)	(46.9,0,0)	(44.6,0,0)	(44.7,0,0)	(44.8,0,0)	(40.7,0,0)

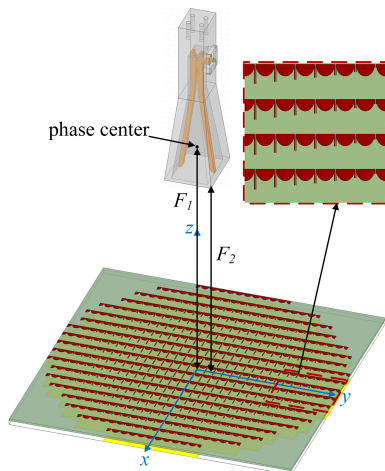


Fig. 11. Configuration of the proposed reflectarray antenna.

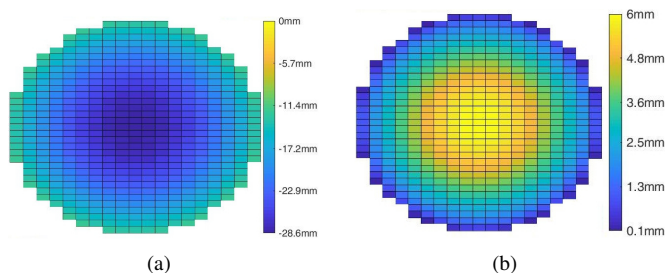


Fig. 12. Calculated element information across the array aperture. (a) equivalent distance delay for each element. (b) length of the slot line for each element.

delay of the proposed unit cell are not completely overlapped at different frequencies, the deviation is very small, indicating that the proposed element can satisfy (14) within an ultra-wide frequency range.

To minimize the phase errors over an ultra-wide frequency band, second-degree polynomial curve fitting in a least-squares sense is used to determine the design function of $d'(l)$ for the reflectarray, which is derived as follows:

$$d'(l) = -0.0648 \times l^2 - 2.5379 \times l + 0.5572 \quad (15)$$

The curve of $d'(l)$ versus l is also included in Fig. 10 and denoted by hollow dots. By using the $d'(l)$ to design the reflectarray, reduced phase error can be obtained over an ultra-wide bandwidth. Therefore, the function $d'(l)$ is used to calculate the length l of the slot line of each reflectarray unit cell.

C. Design of the Reflectarray Antenna

As a proof of concept, a primary-fed reflectarray antenna with a diameter of 129 mm is designed by using the pro-

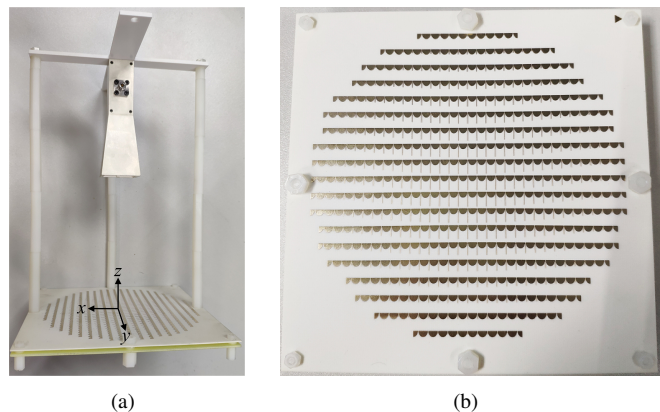


Fig. 13. Prototype of the proposed reflectarray. (a) Perspective view. (b) top view of the array aperture.

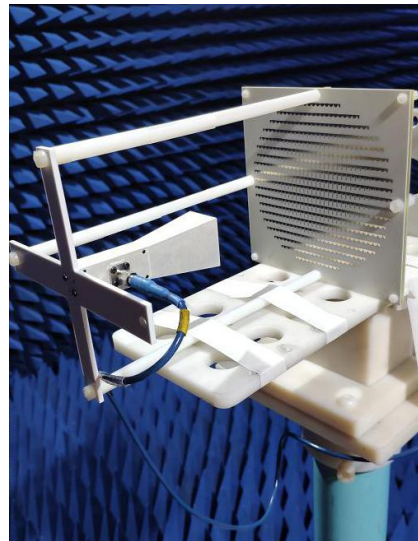


Fig. 14. Measurement setup of the proposed reflectarray.

posed reflectarray unit cell. The configuration of the proposed reflectarray antenna is shown in Fig. 11. As shown, 503 connected dipole elements are printed on the top-layer of the supporting substrate. An inset of the array aperture details the connection of neighboring elements. The distance between the array aperture and the DRHA aperture (denoted by F_2) is 115.5 mm, while the distance between the phase center of the DRHA and the array aperture (denoted by F_1) is 119 mm, leading to a focus/diameter (F/D) ratio of 0.92. With this F/D ratio, a proper illumination is realized and the average aperture efficiency (AE) can be improved.

The required renormalized equivalent distance delays of all reflectarray elements are calculated according to (14) and shown in Fig. 12(a). Accordingly, the required lengths of the

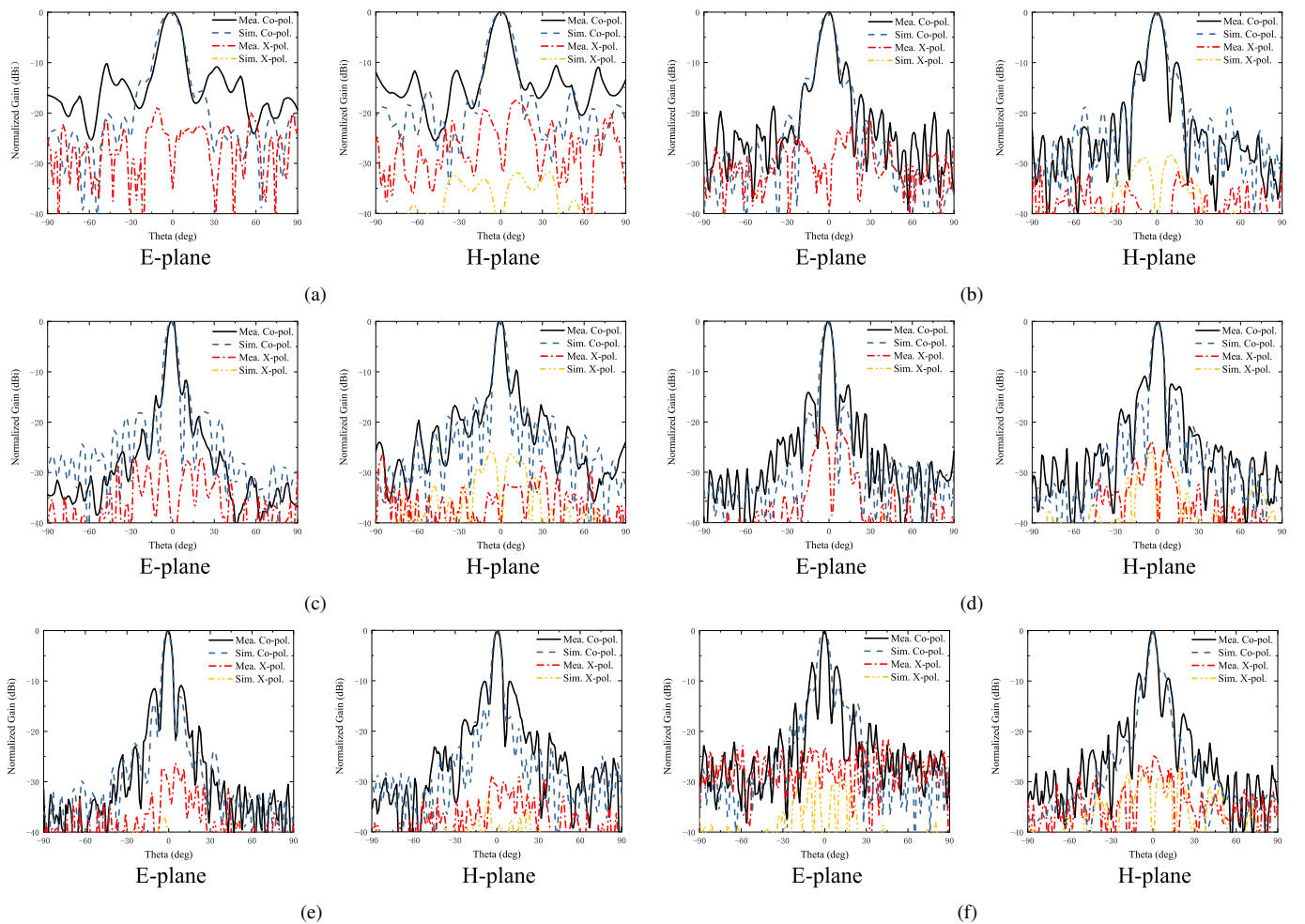


Fig. 15. Simulated and measured normalized radiation patterns of the proposed reflectarray antenna. (a) 10 GHz. (b) 14 GHz. (c) 18 GHz. (d) 22 GHz. (e) 26 GHz. (f) 30 GHz.

slot lines are calculated via (15) and shown in Fig. 12(b). With this information, the array can be finalized.

IV. RESULTS AND DISCUSSION

To verify the design concept, the proposed reflectarray antenna is prototyped and fabricated, as shown in Fig. 13. A CNC machined DRHA is placed above the array aperture with the support of three plastic pillars. The radiation performance of the reflectarray is measured in an anechoic chamber, with the measurement setup shown in Fig. 14.

A. Radiation Patterns

The simulated and measured normalized radiation patterns are shown in Fig. 15. To fully demonstrate the UWB performance of the proposed reflectarray, the radiation patterns are provided with a frequency step of 4 GHz. As shown, a linearly polarized well-shaped pencil beam directed in the broadside direction is obtained from 10 to 30 GHz. Within this frequency range, the radiation patterns are not distorted and good cross-pol performance is achieved. Although the proposed antenna is linearly polarized, a circularly polarized counterpart may be realized with increased complexity and cost.

The measured cross-pol levels are around -25 dB over most of the operating bands except for the low frequency region (10 GHz). It is also noted that the simulated cross-pol levels in the E-plane are rather low (<-40 dB) and thus are not shown in most of the figures. The reason for the low cross-pol levels in the E-plane is mainly attributed to the pure reflected electric fields along the direction of dipole elements (y -direction), which is caused by the connected-element configuration. This kind of element arrangement imitates the Munk's current sheet array [37], and thus continuous current is maintained along y -direction, leading to a pure radiation in y -direction. As the element is separately placed along x -direction, discrete current distribution occurs along this direction and higher cross-pol level than that in the E-plane is resulted in the H-plane (xz -plane). The rise of the measured cross-pol levels is due to the fabrication errors of the feed horn and the scattering of the cables.

The sidelobe level (SLL) is around -10 dB over majority of the bandwidth and reaches -15 dB in the middle of the band. The relatively high sidelobe level is mainly due to the phase errors over the array aperture, measurement errors, fabrication errors of the feed horn, and the scattering from the feed horn fixture and the measurement cables. With focusing on the

TABLE V
COMPARISON OF THE PROPOSED REFLECTARRAY WITH OTHER REPORTED WIDEBAND REFLECTARRAY DESIGNS

Reference No.	Bandwidth	Aperture Size (mm)(electrical size at center freq.) and Shape	Aperture Profile (mm) (electrical size at center freq.)	Fabrication and Assembling Difficulty	Measured Peak Gain (dBi)	Measured Peak AE (%)	Average AE (%)	Average Cross-Pol Level (dB)	Bandwidth Improvement Method
[15]	1-dB gain: 12.94% (39.5-45 GHz)	$\Phi 140.4(19.89\lambda)$, Circular	1.016(0.14 λ)	Moderate	32.83	51.18	44	-30.1	Using substrate integrated coaxial true-time delay lines
[16]	3-dB gain: 38.5% (9.24-13.64 GHz)	$\Phi 266(8.87\lambda)$, Octagonal	2.8(0.11 λ)	Simple	26	50	-	-26	Spiral-shaped phase delay lines
[17]	3-dB gain: 37.4% (8.7-12.7 GHz)	288 \times 288(9.6 λ \times 9.6 λ), Square	5.1(0.18 λ)	Simple	24.2	20	17	-20	Exploiting the polarization rotating unit cell
[24]*	3-dB gain: 33% (6.85-9.55 GHz)/30% (11.22-15.18 GHz)	$\Phi 250(9.6\lambda/11\lambda)$, Circular	6.813(0.19 λ /0.3 λ)	Simple	23.4/25.7	46.7/33	-	-25	Multi-resonance element
[27]*	1.5-dB gain: 24% (10.7-12.7 GHz)/21% (12.7-14.7 GHz)	408 \times 399(15.91 λ \times 15.56 λ /18.63 λ \times 18.22 λ), Rectangular	2.2(0.09 λ /0.1 λ)	Simple	31.8/32.1	48/38	-	-27	Using the subwavelength patch element
[30]	Stable radiation pattern: 103% (3.4-10.6 GHz)	210 \times 210(4.9 λ \times 4.9 λ), Square	34.8(0.812 λ)	Complex	22.6	38	25	-20	Tightly coupled element
This work	Stable radiation pattern: 100% (10-30 GHz)	$\Phi 129(8.6\lambda)$, Circular	2.813(0.187 λ)	Simple	27.51	43.8	32	-25	Connected planar dipole element

*Dual-band reflectarray.

main beam performance and the cross-pol levels, the proposed reflectarray antenna can generally maintain a stable radiation pattern and achieve an average cross-pol level of -25 dB within a 3:1 bandwidth.

B. Realized Gain and Aperture Efficiency

The simulated and measured realized gains and aperture efficiencies of the proposed reflectarray are shown in Fig. 16. It is observed that the simulated and measured realized gains generally enhance with the increase of frequency. The simulated gain varies from 15.65 to 27.12 dBi, while the measured gain ranges from 14.11 to 27.51 dBi in the operating band. The measured peak gain of 27.51 dBi is achieved at the frequency of 26 GHz.

As shown in Fig. 16, the maximum AE is 43.8% at 26 GHz based on the measurement result and 49.8% at 22 GHz according to the simulation result. By averaging the measured AE with a frequency step of 1 GHz, the measured average AE of the proposed reflectarray is about 32% from 10 to 30 GHz. It is noticed that the AE is relatively low at the lower and upper band. Generally, there are two reasons for this phenomenon. The first one is that the phase errors over the aperture at these two frequency bands are larger than that of the middle frequency band. Another factor rests on the spillover and inefficient illumination effect occurred at the edge frequencies, which is caused by the varied beamwidth feature of the feed horn over the ultra-wide bandwidth. The discrepancies between the simulation results and measurement

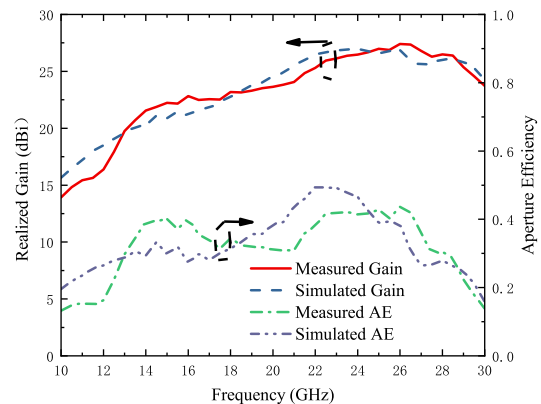


Fig. 16. Simulated and measured realized gains and aperture efficiencies of the proposed reflectarray.

results are due to the fabrication errors of the DRHA, the assembly errors of the antenna, and measurement errors.

C. Comparison With Other Wideband Reflectarrays

To demonstrate the merits of our work, Table V provides a comprehensive comparison between our work and other latest reported wideband reflectarray antennas in terms of array bandwidth, aperture size, aperture height, fabrication and assembly difficulty, peak gain, peak aperture efficiency, average aperture efficiency, average cross-pol level, and the bandwidth improvement method. It should be mentioned that the bandwidth definitions used in these works are not exactly

the same. From the Table V, it is noted that the fractional bandwidth of the proposed reflectarray is 100%, i.e., from 10 to 30 GHz, which is much wider than other works except for [30]. Compared with the design in [30], this work shows higher aperture efficiency and antenna gain, lower cross-pol level, and much simpler configuration. In addition, the aperture profile of the presented work is only about one fifth ($0.187\lambda/0.812\lambda$) of that in [30]. Moreover, the single-layer fully planar array aperture not only greatly reduces the fabrication difficulty and cost but also notably improves the reliability and robustness of the whole reflectarray system.

V. CONCLUSION

In this paper, a novel UWB reflectarray antenna for IoV application has been presented. **The presented reflectarray works from 10 GHz to 30 GHz with stable radiation pattern and high antenna gain, thus can cover the vehicle-to-satellite bands (12.25-12.75 GHz/14.0-14.5 GHz/19.6-21.2 GHz/29.4-31.0 GHz), the 24-GHz short-range vehicle radar band (24.25-26.65 GHz), and the 5G millimeter-wave band (27.5-28.35 GHz), simultaneously.** Moreover, the proposed reflectarray can also achieve an average aperture efficiency around 32% and a cross-pol level of -25 dB across the whole bandwidth. All these merits are achieved by a single-layer fully planar aperture which is comparable to conventional reflectarrays in terms of fabrication complexity and cost. In addition, the equivalent circuit method is proposed to predict the element performance quantitatively, which helps reveal the antenna operating principles and facilitates the array design. With its ultra-wide bandwidth, high antenna gain, low cross-pol level, and low fabrication complexity and cost, the proposed reflectarray antenna would be a promising candidate for IoV application and 5G millimeter-wave connections simultaneously.

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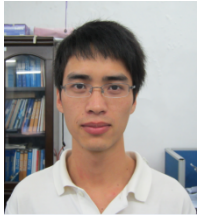
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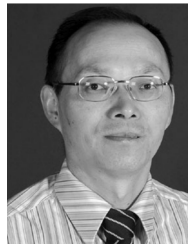
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