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# Optimal Construction of Microgrids in a Radial Distribution System Considering System Reliability via Proposing Dominated Group Search Optimization Algorithm

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**Abstract:** In contemporary electrical networks, reliability stands as a paramount attribute. Since the introduction of distributed generation (DG) and microgrid (MG) concepts has considerably changed the structure of distribution networks, it is necessary to consider reliability aspects while going toward modern smart grids. This study introduces a novel methodology focusing on the partitioning of radial distribution systems into distinct MGs, strategically aimed at minimizing energy not supplied (ENS) to fortify overall system reliability. Two types of faults are considered including DG and busbar failures, and the impact of each kind of fault is investigated. Besides, a new Markov model is proposed to evaluate the reliability of DGs and MGs. Given the stochastic nature of the majority of DGs, the incorporation of energy storage systems (ESSs) can significantly enhance system performance. Therefore, this paper dedicates attention to exploring optimal ESS placement. To address the complex challenge of optimizing system partitioning, a modified version of the group search optimization (GSO) algorithm, named dominated GSO (DGSO) is proposed. The PG&E 69-bus distribution system is studied with two different structures to accurately investigate the effectiveness of the proposed partitioning approach on the system reliability. Moreover, the optimal number of MGs to be constructed within the intended system is determined.

**Keywords** System Partitioning; Reliability; Microgrid; Distributed Generation; Energy Storage System; Dominated Group Search Optimization Algorithm.

## Nomenclature

<b>AGSO</b>	Adaptive Group Search Optimization Algorithm	<b>num<sub>DG</sub></b>	Number of DGs in the Distribution System
<b>a</b>	Number of Boundary Lines	<b>num<sub>Bus</sub></b>	Number of Busbars in the Distribution System
<b>BG</b>	Biomass Generator	<b>num<sub>MG</sub></b>	Number of MGs in the Distribution System
<b>BL</b>	Boundary Line	<b>num<sub>Up-MG</sub></b>	Number of Upstream MGs
<b>b</b>	Number of Installed Energy Storage Systems	<b>P<sub>DG</sub></b>	Active Power Generated by DG Unit
<b>DER</b>	Distributed Energy Resources	<b>PDF</b>	Probability Distribution Function
<b>DG</b>	Distributed Generation	<b>PSO</b>	Particle Swarm Optimization
<b>DGSO</b>	Dominated Group Search Optimization Algorithm	<b>PV</b>	Photo Voltaic
<b>ENS</b>	Energy Not Supplied	<b>RES</b>	Renewable Energy Resources
<b>ENS<sub>DG</sub></b>	ENS Caused by DG Failures within a MG	<b>r</b>	Repair Time
<b>ENS<sub>MG</sub></b>	ENS Caused by Busbar Failures within a MG	<b>SAIDI</b>	System Average Interruption Duration Index
<b>ENS'<sub>MG</sub></b>	ENS Caused by Busbar Failures in Upstream MG	<b>SAIFI</b>	System Average Interruption Failure Index
<b>ESS</b>	Energy Storage System	<b>WT</b>	Wind Turbine
<b>ES<sub>Place</sub></b>	Place for Installing Energy Storage System	<b>X<sub>P</sub></b>	Position of the Producer
<b>GA</b>	Genetic Algorithm	<b>X<sub>P,R</sub></b>	Position of the Producer of Rangers
<b>GSO</b>	Group Search Optimization Algorithm	<b>X<sub>S</sub></b>	Position of the Scrounger
<b>LC</b>	Load Curtailment	<b>l</b>	Failure Rate
<b>M</b>	Number of busbars in upstream MG.	<b>m</b>	Repair Rate
<b>MG</b>	Microgrid	<b>ρ</b>	Probability of Each Generated State for Stochastic Parameters
<b>N</b>	Number of States Generated for a Stochastic Parameter to Estimate its Value		

1

## 2 1. Introduction

3 During the last two decades, distribution systems has been undergoing considerable changes due  
 4 to the vast integration of DERs. Development of DG technologies facilitates the local supply of

1 system consumers [1, 2]. Accordingly, distribution systems can be divided into smaller zones  
2 where each zone might rely either on its local production or on power exchange with surrounding  
3 zones, which gives rise to the concept of MGs. A MG is known as a cluster of loads, DERs, and  
4 ESSs with two operating modes, namely grid-connected and islanded modes [3, 4]. MGs can bring  
5 many advantages to distribution systems, but dividing a large distribution system into several  
6 smaller MGs increases the complexity of the system operation [5]. System partitioning includes  
7 determination of boundaries between MGs and allocation of DERs to each MG, which are essential  
8 requirements for power system planning. The optimal allocation of DG units within a distribution  
9 system has been comprehensively studied to improve various aspects of the system such as  
10 minimizing system losses, improving voltage stability, and reducing environmental pollution [6-  
11 10].

12 If MGs in a distribution system are optimally designed and the boundaries between them are  
13 accurately determined, superior performance and control of the smart grid will be obtained. The  
14 concept of self-adequacy is introduced in optimal MG construction studies, since increasing the  
15 internal supply capacity will result in improving the independent performance of the MG. Hence,  
16 minimizing the amount of power flows between MGs is considered as the objective of the planning  
17 optimization problem [11-14]. Although the MGs with high supply adequacy operate appropriately  
18 in the electricity markets, their power quality, reliability and stability may not be satisfactory.  
19 Moreover, the optimal number of MGs is not taken into account in the existing studies. In addition  
20 to the supply adequacy concept, the consumer-side properties are also taken into account in optimal  
21 MG construction studies. Noteworthy, improving the consumer-side properties leads to more  
22 customer satisfaction which is of high importance in the modern competitive electricity markets.  
23 To this end, increasing the load factor and decreasing the load variance of constructed MGs are

1 considered the goals of the optimal system partitioning problem in [15]. Despite the acceptable  
2 power quality which is obtained by improving the consumer-side properties, investigating the  
3 effect of the probable faults on the system operation is also of high importance. The reliable  
4 performance of the system under fault conditions, as well as the system's ability to recover from  
5 the faults and return to the stable operation, are impressive aspects that are not considered in the  
6 above-mentioned studies. Moreover, the number of MGs to be constructed is not optimized.

7 Reliability is known as a significant index for evaluating the electrical networks whereas various  
8 indices have been proposed to assess the system reliability [16, 17]. The optimal design of MGs  
9 in a distribution system improves the system reliability which is rarely taken into account in the  
10 literature. In [18], SAIFI and SAIDI as widely-used indices for measuring the system's reliability,  
11 are minimized while the optimal places for connect/disconnect switches between MGs are  
12 determined. Such objective functions are optimized in [19] by considering optimal placement of  
13 DGs, ESSs, and reactive resources in a multi-MG system. However, optimizing both DG allocation  
14 and MG construction as well as determining the optimum number of MGs are essential in  
15 reliability evaluation of smart grids. Investigating more reliability indices leads to more  
16 comprehensive studies. When it comes to smart grids, the conventional formulations for reliability  
17 indices should be revised to be applicable in MGs context. Simultaneous operation of several MGs  
18 and interactions between them besides the impacts of working in grid-connected or islanded modes  
19 should be considered. Failure occurrence in a MG can affect the normal and reliable operation of  
20 other zones which is rarely taken into account in previous investigations. DGs, as the local  
21 electricity resources, play an important role in enhancing the independency of modern distribution  
22 systems. Therefore, considering the effect of DGs interruptions on the system reliability is an

1 important issue that is missed in the existing studies. Accordingly, appropriate models are required  
2 to account for failures in the MGs and DGs in distribution systems reliability analysis.

3 In this paper, optimal MG construction is studied to improve system reliability. To this end, the  
4 total amount of ENS is minimized by the optimal placement of interconnection switches between  
5 MGs. ENS is the amount of energy that is not delivered to the customers when a failure happens  
6 in the system [20]. It is worthy to evaluate system ENS as a measure that indicates the ability of a  
7 system in supplying loads during fault conditions. Two types of failures are considered in this  
8 paper: DG failures and busbar failures. The impact of each failure on the whole system is  
9 investigated and the total ENS is calculated. The optimal ESS placement is also carried out which  
10 results in improved utilization of DG capacities and enhanced system performance. Further, a new  
11 Markov model is used to assess the reliability of installed stochastic DG units. As the reliable  
12 performance of the upstream MG(s) would considerably influence the downstream zones, it is  
13 important to assign suitable reliability indices for upstream MGs. To this end, a new Markov model  
14 is proposed to assess the reliability of upstream zones and evaluate the whole distribution system  
15 reliability. Since the interactions between MGs extremely affect the system reliability, the  
16 optimum number of MGs to be constructed in the distribution system is also determined in this  
17 paper. Noteworthy, the impacts of probable external failures (such as storms) on the system  
18 reliability are not taken into account in this paper.

19 Due to the existence of redundant connections in power systems and complexity of the required  
20 calculations, heuristic optimization algorithms are proposed to find the solution [21, 22]. GSO is  
21 a robust heuristic algorithm that operates based on animals group living manner, especially group  
22 searching behavior [23]. Various improved versions of GSO algorithm have been proposed and  
23 implemented in power system studies representing appropriate performance in finding solutions

1 [24-27]. A novel improved version of GSO algorithm named as DGSO algorithm is used in this  
2 paper. Comprehensive search, appropriate convergence speed, and reaching satisfactory solutions  
3 are the main properties of the applied DGSO approach [15]. According to the obtained results for  
4 optimal placement of switches and ESSs, DGSO algorithm represents reasonable performance.  
5 The rest of this paper is organized as follows; In Section 2, the problem formulation is presented  
6 and, the proposed DGSO algorithm is described comprehensively in Section 3. The  
7 implementation procedure of optimization method is provided in Section 4. Simulation results are  
8 reported in Section 5 alongside the analysis and evaluations. Ultimately, conclusions are presented  
9 in Section 6.

10

## 11 **2. Problem Formulation and Reliability Evaluation**

12 Two types of failures are considered in a MG, namely DG and busbar failures. From a MG's point  
13 of view, each fault can cause ENS within the damaged MG or other neighboring zones. Therefore,  
14 a new Markov model is proposed in this paper in order to appropriately model each system  
15 component and facilitate the reliability evaluations. This section is dedicated to explain the  
16 proposed Markov models, reliability evaluations, and ENS formulations.

### 17 **2.1. ENS Caused by DG Failures**

18 The generated power of DG units can be stochastic or constant. The injected power by DGs is  
19 consumed by the local loads and the surplus power is absorbed by the installed ESSs to be released  
20 during peak load times. When a DG unit fails, it is disconnected from the rest of the system to  
21 prevent fault propagation. Therefore, the amount of ENS caused by a failure in a DG unit is equal  
22 to its generated energy. Considering the stochastic generation, the ENS value due to DG failures  
23 in a distribution system is calculated as [29]:

$$1 \quad ENS_{DG} = \sum_{i=1}^{num_{DG}} ENS_{DG_i} = \sum_{i=1}^{num_{DG}} \lambda_{DG_i} * r_{DG_i} * \left( \sum_{n=1}^N \rho_n * P_{DG_i,n} \right) \quad (1)$$

2 It is noteworthy that the probabilistic studies should be carried out to calculate the generated power  
3 of DGs with stochastic nature. These investigations involve the assignment of an appropriate PDF  
4 to each stochastic parameter. The selected PDF, in conjunction with available historical data,  
5 facilitates the derivation of several estimated values and their associated probabilities for future  
6 occurrences. Furthermore, the determination of failure rates and repair times of DG units is  
7 essential. To achieve this, a Markov model, as introduced in prior works [28, 29], is employed,  
8 where it is assumed that each DG unit consists of several components operating in series. Thus,  
9 any failure within a component results in the overall failure of the DG unit. Considering the  
10 normal/failure states for DG components and determining their failure rates and repair times, a  
11 Markov model is formulated, encompassing diverse probable states. Subsequently, the failure rate  
12 and repair time corresponding to each DG unit are obtained. The requisite formulations are  
13 expounded in the appendix.

## 14 **2.2. ENS Caused by Busbar Failure in a MG**

15 According to the structure of radial distribution networks, failure in a busbar leads to disconnection  
16 of all downstream parts from the grid. When it comes to smart grid studies, if a busbar in a MG  
17 fails, all the downstream parts will be separated from each other and the MG goes to islanded  
18 mode. Such MG is divided into two parts. The upstream parts of the failed busbar remain connected  
19 to the rest of the grid whereas the DG units installed in the downstream part are disconnected from  
20 the network to prevent any damage. Accordingly, the loads in the downstream part of the islanded  
21 MG experience a lack of power supply. The ENS caused by busbar failures within a MG is  
22 calculated as:



$$1 \quad ENS_{MG} = \sum_{j=1}^{num_{MG}} ENS_{MG_j} = \sum_{j=1}^{num_{MG}} \sum_{i=1}^{num_{bus,j}} \lambda_i * r_i * LC_{i,j} \quad (2)$$

2 Besides,  $LC_{i,j}$  represents the amount of load curtailment in the  $j^{th}$  MG due to the outage of the  $i^{th}$   
3 busbar. Moreover,  $num_{bus,j}$  is the number of busbars located in the  $j^{th}$  MG.

### 4 **2.3. ENS Caused by Busbar Failure in Upstream MGs**

5 When a busbar fails, all the downstream MGs are separated from each other and start operating in  
6 islanded mode. Thus, the DG units installed in downstream MGs should supply the consumers.  
7 Hence, if the involved DGs are capable of supplying the total loads, there will be no ENS in such  
8 zones. Otherwise, the load curtailment will be inevitable. The amount of ENS is equal to the energy  
9 demand which cannot be supplied by the installed DGs. Therefore, ENS in a MG caused by the  
10 busbar failures in upstream zones is equal to:

$$11 \quad ENS'_{MG} = \sum_{j=1}^{num_{MG}} ENS'_{MG_j} = \sum_{j=1}^{num_{MG}} (1 - \eta_j) \sum_{i=1}^{num_{UP-MG,j}} \lambda_i * r_i * LC_j \quad (3)$$

12 where  $\eta_j$  is a probability index to show the ability of the  $j^{th}$  MG to supply the total installed loads.  
13 It is noteworthy that  $\eta_j$  is derived by dividing the count of states where the power generated by  
14 DGs in  $MG_j$  surpasses the load demand, by the total number of states during a year.  $\lambda_i$  and  $r_i$  denote  
15 the failure rate and repair time attributed to busbar failures in the  $i^{th}$  upstream MG, respectively.  
16 The calculations for  $\lambda_i$  and  $r_i$ , are facilitated by an efficient Markov model proposed in this paper.  
17 When it comes to reliability evaluations of a downstream MG, the structure of distribution system  
18 and the placement of MGs should be considered. This paper explores two distinct structural  
19 possibilities: single branch and multi-branch radial distribution systems. The requisite  
20 formulations are provided in the appendix. It is worth mentioning that for the inclusion of line

1 failures in the reliability analysis, a parallel procedure to that of busbar failure can be followed.  
 2 However, in the sake of brevity of the paper, it is not further discussed in this study.

### 3 **2.4. ENS Calculation and Objective Function Formulation**

4 As previously stated, the failure of a DG unit within a MG results in its disconnection  
 5 from the entire grid, allowing the remaining components of the system to proceed with  
 6 normal operations. Hence, DG failure is regarded as an internal failure. On the other  
 7 hand, a busbar failure leads to its disconnection from the upstream grid. This implies  
 8 that each MG suffers from its internal busbar failures and also from the faults occurring  
 9 in upstream busbars. Accordingly, the total system ENS is calculated as follows.

$$\begin{cases}
 \text{Internal ENS} = \sum_{i=1}^{num_{DG}} ENS_{DG_i} + \sum_{j=1}^{num_{MG}} ENS_{MG_j} \\
 \text{External ENS} = \sum_{i=1}^{num_{MG}} ENS'_{MG_i} \\
 \text{Objective Function} = \text{Total ENS} = \text{Internal ENS} + \text{External ENS}
 \end{cases} \quad (4)$$

11

### 12 **3. Optimization Algorithm**

13 Since recent decades, heuristic optimization algorithms are developed in all kinds of  
 14 forms [30, 31]. Heuristic algorithms operate based on searching strategies. The more  
 15 efficiency of the searching method, the more authority of reaching global optima.  
 16 Hence, various heuristic optimization algorithms are proposed, improved, and used for  
 17 optimization problems [32, 33].

18 This study employs a modified version of GSO algorithm, designated as DGSO  
 19 algorithm. The GSO algorithm, recognized for its robustness, has shown commendable  
 20 performance in addressing non-linear, non-convex, and complex problems of power  
 21 systems. Operating within the GSO framework, members are categorized into three  
 22 groups: a producer, scroungers, and rangers. At each iteration, the GSO member with

1 the best fitness value is selected as the producer, utilizing its vision ability to explore  
 2 neighboring points for potential better solutions. Scroungers are directed towards the  
 3 producer, because it is more probable to find better solutions in the producer vicinity.  
 4 Rangers, on the other hand, undertake random walks across the search space to ensure  
 5 a comprehensive search.

6 AGSO algorithm, a recent proposed version of GSO [25], elects the ranger member  
 7 with the best position as the “Producer of Rangers” and equipped it with vision ability  
 8 as well as the main “Producer”. Hence, the probability of finding better opportunities is  
 9 increased. According to the conventional AGSO algorithm, the decision for each  
 10 scrounger to follow a specific producer is random, potentially leading to missed  
 11 opportunities within the closer producer’s vicinity. Addressing this issue, DGSO  
 12 algorithm is proposed which is equipped with smart scroungers. The scroungers of  
 13 DGSO can decide whether to follow the producer or the producer of rangers according  
 14 to their distances. Therefore, the distance of each scrounger from available producers is  
 15 calculated. If the mentioned scrounger is closer to the main producer, it should follow  
 16 the same producer. Otherwise, it should walk through the producer of rangers. To find  
 17 the nearest producer and joining it, a scrounger should move as follows [15]:

$$18 \quad \begin{cases} X_{S,i}^{k+1} = X_{S,i}^k + r \circ \left( \left| X_P^k - X_{S,i}^k \right| \right) & \left| X_P^k - X_{S,i}^k \right| < \left| X_{PR}^k - X_{S,i}^k \right| \\ X_{S,i}^{k+1} = X_{S,i}^k + r \circ \left( \left| X_{PR}^k - X_{S,i}^k \right| \right) & \left| X_{PR}^k - X_{S,i}^k \right| < \left| X_P^k - X_{S,i}^k \right| \end{cases} \quad (5)$$

19 where  $k$  is representative for the iteration number.

20

#### 21 **4. Implementation of the Proposed Method**

22 In this section, the implementation procedure of the proposed methods and

1 mathematical formulations for the reliability evaluations are elaborated. According to  
2 the proposed DGSO method, each member of the optimization algorithm is a vector of  
3 decision variables including the potential boundary lines between the MGs and places  
4 for installing ESSs. The group members of DGSO algorithm can be formed as  
5  $[BL_1, BL_2, \dots, BL_a, ES_{place,1}, ES_{place,2}, \dots, ES_{place,b}]$ . Moreover, the number of  
6 scroungers, rangers, and iterations are set to 25, 25, and 100, respectively. The  
7 implementation process of the proposed method for the system partitioning is depicted  
8 in the flowchart shown in Fig.1.

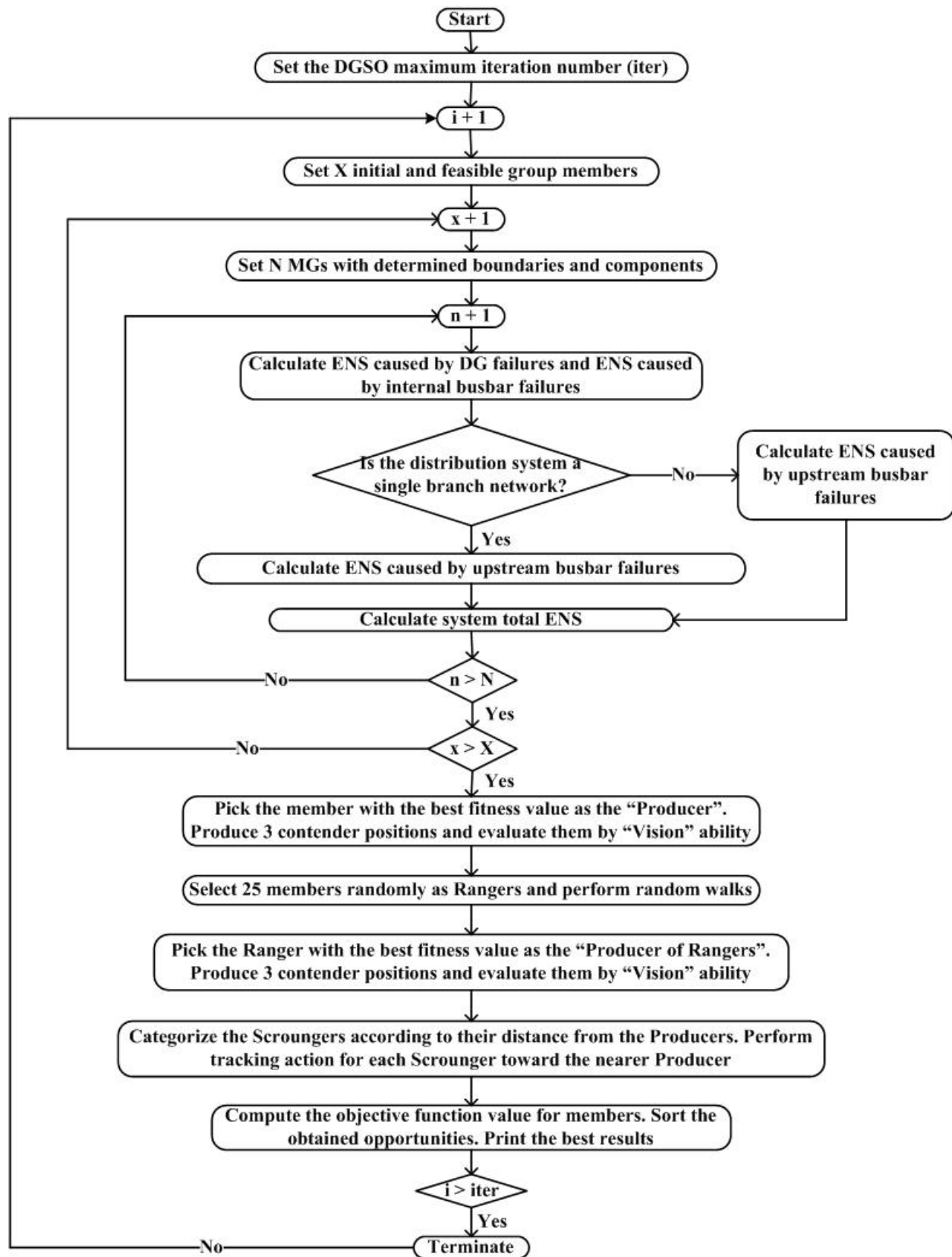


Fig.1. Proposed method for system partitioning.

## 1    **5.    Simulation Results and Numerical Analysis**

2    This section presents the simulation results and assesses the effect of implementing the  
3    proposed partitioning method on system reliability. Initially, the analysis assumes a  
4    distribution system comprising a single branch, followed by the consideration of a  
5    distribution network with multiple branches. The PG&E 69-bus distribution system is  
6    selected as the test system. The required data including the system structure, connected  
7    loads, and impedances of lines are provided in [34]. The siting and sizing of installed  
8    DGs are illustrated in the appendix as Table.B.1. WTs and PV modules are the  
9    stochastic DGs whereas BGs are the constant ones. The calculations of generated  
10    power by the DGs and consumed power by the loads are sourced from [12]. Besides,  
11    the relevant reliability information including failure rate and repair time of system  
12    busbars and installed DGs are available in [28, 35]. On the other hand, the mentioned  
13    test system is considered with a different structure where all busbars are linearly  
14    arranged within a single branch. Notably, the analysis of the single branch structure is  
15    pursued to ensure a more precise evaluation. It is assumed that the clustered zones must  
16    encompass a minimum of three busbars and a single DG unit to qualify as a MG.  
17    Within each MG, the installed DGs/ESSs are mandated to supply a minimum of 20%  
18    of the internal load demand during the normal operational conditions, ensuring an  
19    acceptable level of supply adequacy within the partitioned zones. The ESS  
20    configuration comprises two batteries, each with the maximum power limit of 200 kW.  
21    Furthermore, an Indian high order radial distribution system with 85 busbars is taken  
22    into account in the third case to more distinctly illustrate the impact of optimal MG  
23    partitioning on the system reliability. The required data including the connections

1 between busbars, involved loads, etc. is available in [36]. The rated values of operating  
 2 DGs and the installing places of DERs are also represented in [37].

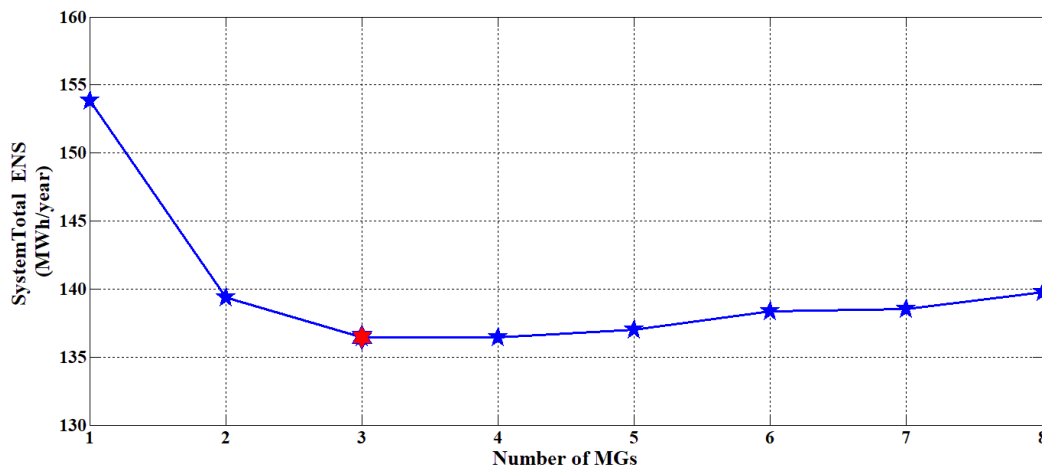
### 3 **5.1. Case.1**

4 In this case, a single branch form of the considered radial distribution system is  
 5 studied. The obtained results including the virtual cut set lines between MGs, optimal  
 6 places for ESSs in addition to calculated values for ENS are reported in Table.1.  
 7 Moreover, the calculated amounts of ENS caused by internal and upstream failures are  
 8 depicted in Fig.B.1, and Fig.B.2, respectively. Consequently, Fig.2 represents the  
 9 obtained values for the system total ENS.

10 **Table.1:** Optimization results corresponding to Case.1

MG Num	Boundary Lines	ESS Places	ENS - Internal Failures (MWh/year)	ENS - External Failures (MWh/year)	Total ENS (MWh/year)
2	52	10, 47	128.8064	10.5476	139.354
<b>3</b>	<b>18, 52</b>	<b>34, 54</b>	<b>88.577</b>	<b>47.7746</b>	<b>136.3516</b>
4	8, 30, 52	54, 60	61.5159	74.9305	136.4464
5	8, 23, 38, 52	14, 17	49.6902	87.3342	137.0244
6	8, 17, 30, 41, 52	22, 27	44.8056	93.5519	138.3575
7	7, 17, 21, 37, 52, 57	56, 61	44.4347	94.0934	138.5281
8	8, 17, 21, 34, 42, 51, 57	40, 50	39.4643	100.2912	139.7555

11



12  
13

**Fig.2.** Calculated system total ENS for Case.1.

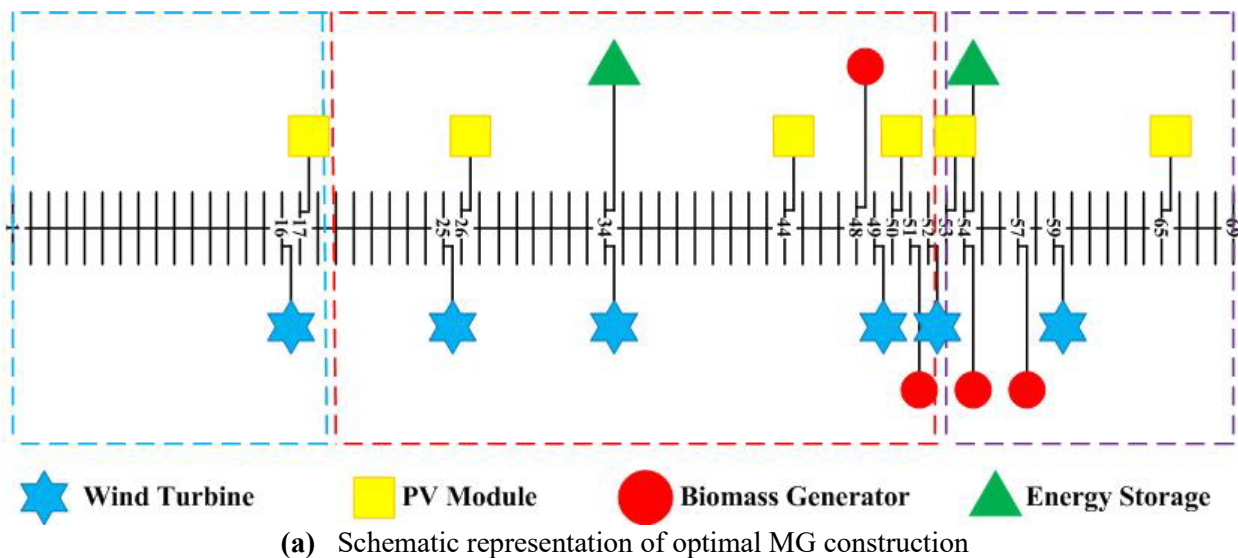
1 Increasing the number of MGs in a single branch radial distribution system, the size of  
2 constructed zones decreases and, the number of upstream MGs increases. According to  
3 Fig.B.1, the number of components located in each zone decreases which means that  
4 the amount of ENS caused by internal failures reduces. Besides, the number of  
5 constructed MGs in the upstream part increases which enhances the ENS caused by the  
6 upstream failures as depicted in Fig.B.2. Hence, an optimal number of MGs could be  
7 determined, aiming to minimize the total system ENS. Fig.2 indicates that constructing  
8 three MGs represents the optimal design for the considered distribution system. A  
9 schematic representation of the system, featuring three optimally clustered MGs and  
10 the strategically located ESSs, is depicted in Fig.3 (a). Noteworthy, assuming the  
11 absence of MGs results in a total ENS of 153.835 MWh/year due to system failures.  
12 System partitioning prevents fault propagation, resulting in 10% reduction in the ENS.  
13 Further, optimal ESS placement significantly enhances the system performance. Since,  
14 installed ESSs absorb the surplus energy during non-peak hours, and release it when  
15 the system power demand increases. To indicate the superior performance of the  
16 proposed DGSO algorithm, the obtained results for constructing three MGs by using  
17 GA, PSO, conventional GSO, AGSO and DGSO algorithms are compared, as provided  
18 in Table.2. The convergence procedures corresponding to various optimization  
19 techniques are illustrated in Fig.3 (b). Evidently, the convergence rate of the proposed  
20 DGSO algorithm markedly surpasses that of alternative algorithms. The DGSO  
21 algorithm, as proposed, demonstrates superior performance relative to alternative  
22 methods. Its notable strengths lie in the reaching to more appropriate solutions, the  
23 execution of a comprehensive search, and a commendable optimization speed.



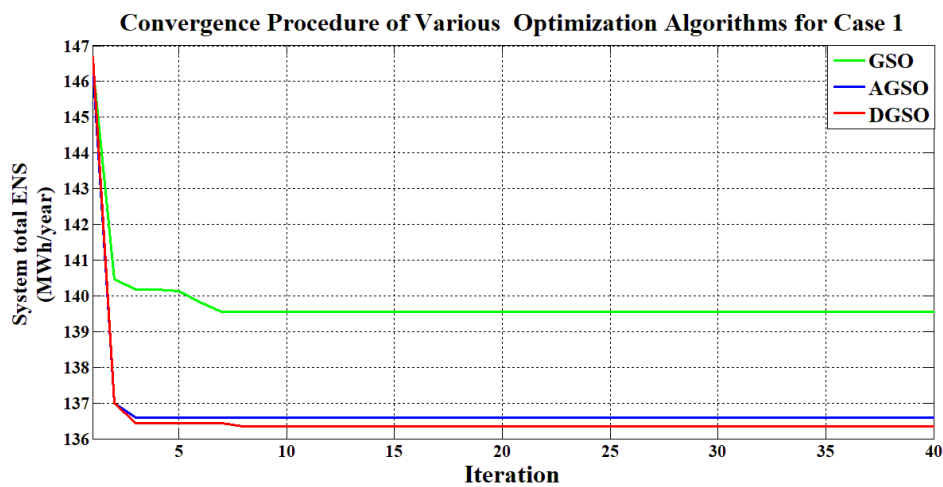
1 **Table.2:** Comparison of obtained results for Case.1 by various optimization algorithms

Optimization Algorithm	Internal ENS (MWh/year)	External ENS (MWh/year)	Total ENS (MWh/year)	time (sec)
GA	89.8811	48.3447	138.2258	19
PSO	90.7694	48.7774	139.5468	21
GSO	90.7688	48.7824	139.5512	17
AGSO	88.7627	47.8211	136.5838	14
<b>DGSO</b>	<b>88.577</b>	<b>47.7746</b>	<b>136.3516</b>	<b>14</b>

2



5



8

**Fig.3.** Schematic results corresponding to Case.1

1

## 2 5.2. Case.2

3 In this case, the PG&E 69-bus distribution test system is studied. After implementing  
4 the optimization procedure, optimal values for control variables are obtained, as  
5 provided in Table.3.

6 To indicate the performance of proposed DGSO algorithm, the MG partitioning  
7 problem is solved by other optimization techniques including PSO, GSO, and AGSO  
8 algorithms, too. The obtained results for constructing 5 MGs in the considered multi-  
9 branch distribution system are reported in Table.4. Noteworthy, constructing more than  
10 8 MGs is impossible due to solution infeasibility and the violation of operational  
11 constraints.

12 **Table.3:** Optimization results corresponding to Case.2.

MG Num	Boundary Lines	ESS Places	ENS - Internal Failures (MWh/year)	ENS - External Failures (MWh/year)	Total ENS (MWh/year)
2	61	41, 44	59.8226	0.6518	60.4744
3	10, 61	32, 46	53.7537	4.3248	58.0785
4	10, 15, 61	47, 63	52.196	5.1855	57.3815
5	10, 15, 20, 61	39, 44	51.3971	5.6047	57.0018
6	10, 12, 20, 29, 61	14, 32	51.6792	5.3830	57.0622
7	9, 11, 15, 20, 55, 61	34, 50	37.6845	19.2477	56.9323
8	6, 10, 14, 20, 31, 57, 61	41, 45	34.1664	22.5760	56.7424

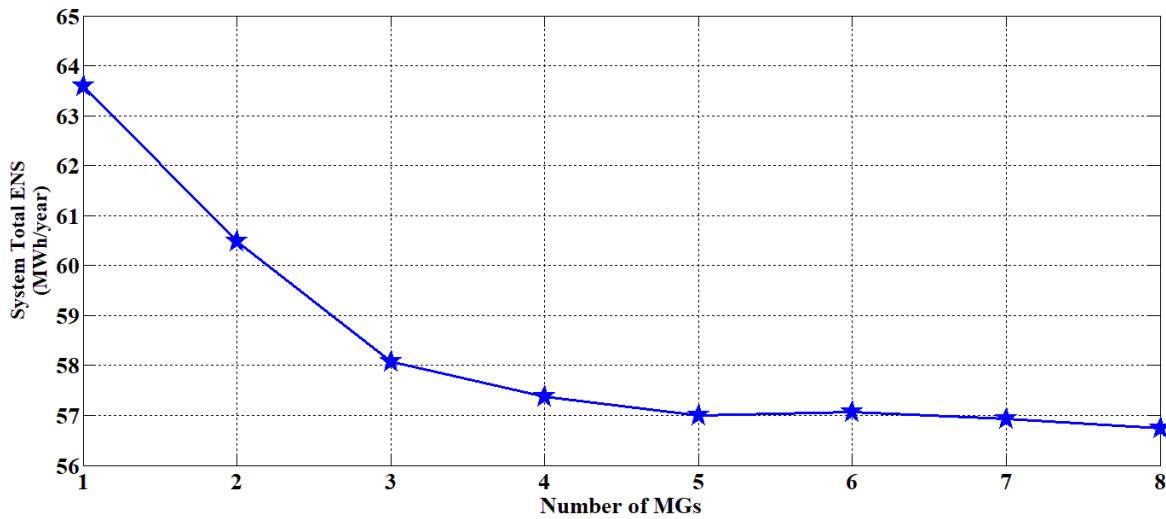
13

14 **Table.4:** Comparison of obtained results for Case.2 by various optimization algorithms.

Optimization Algorithm	ENS - Internal Failures (MWh/year)	ENS - External Failures (MWh/year)	Total ENS (MWh/year)
PSO	52.7432	6.1114	58.8546
GSO	53.566	6.3332	59.8992
AGSO	51.6171	6.002	57.6191
<b>DGSO</b>	<b>51.3971</b>	<b>5.6047</b>	<b>57.0018</b>

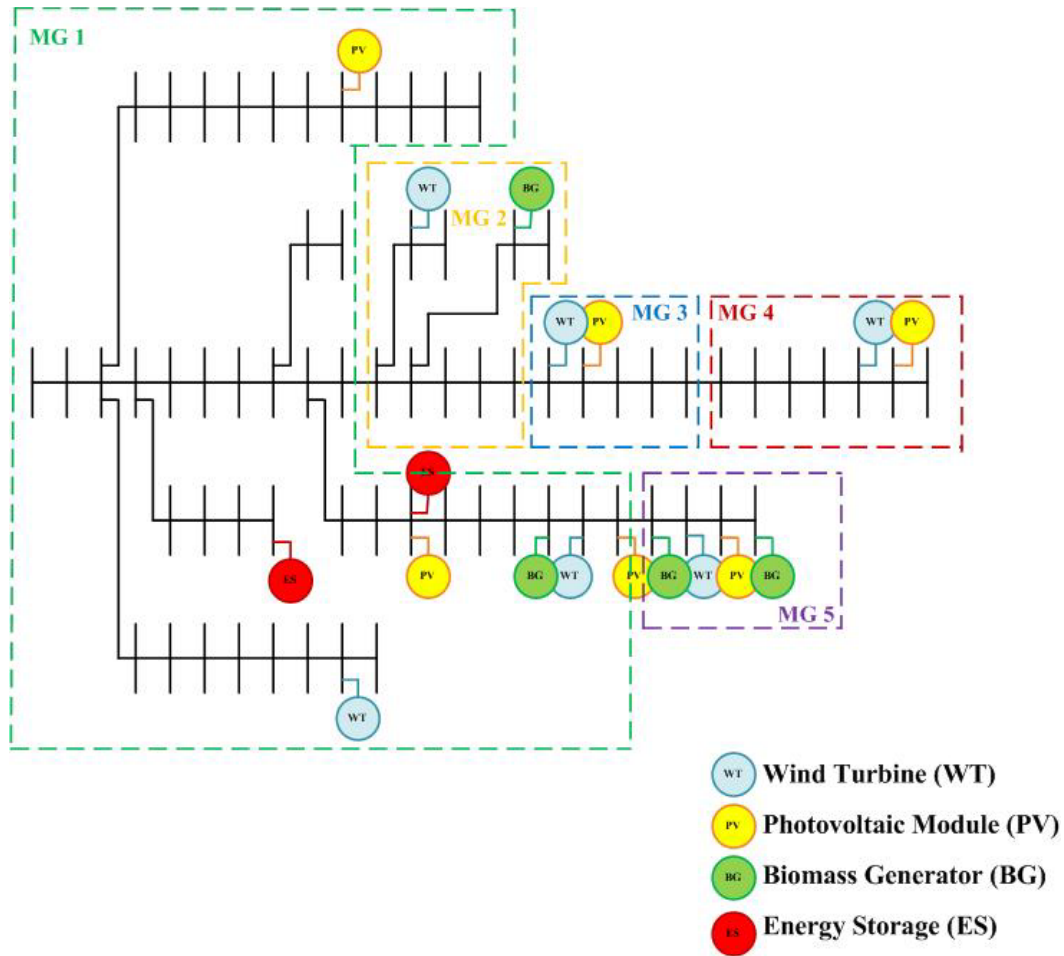
15

1 Fig.4 (a) illustrates the system's total ENS corresponding to various number of MGs. According  
2 to the results, increasing the number of MGs in such distribution system reduces the ENS caused  
3 by internal faults, because the number of components in each zone decreases. In a multi-branch  
4 distribution system, where the constructed zones are dispersed across different branches rather  
5 than linearly arranged, the impact of increasing the number of MGs on ENS resulting from  
6 upstream failures can either elevate or remain constant. According to Fig.4 (a), total amount of the  
7 system ENS has a downward trend and then, it remains constant. Consequently, multiple optimal  
8 numbers of MGs may exist, indicating that the optimal count for the studied distribution system is  
9 equal to 5 or more. However, the definitive determination of the optimal number of MGs  
10 necessitates the consideration of additional criteria such as construction cost, required  
11 infrastructures and etc. Fig.4 (b) presents a schematic representation of the considered distribution  
12 system, optimally partitioned into five MGs with the best reliability indices.



(a) System total ENS

13  
14  
15



(b) Schematic representation of optimal MG construction

Fig.4. Schematic results corresponding to Case.2

### 5.3. Case.3

This case is dedicated to optimal partitioning of an 85-bus radial distribution system to increase the reliability aspects. Implementing the proposed method in a high-order system leads to more accurate investigations and more explicit analysis. The considered network is a multi-branch radial distribution system including several loads and DG units which can inject only real power. It is assumed that DGs are previously installed in suitable places considering the system performance. By implementing the optimization procedure, optimal boundaries between MGs are obtained. The total amount of ENS corresponding to various number of MGs is depicted in the appendix as Fig.B.3.

1 From the reliability point of view, partitioning of a large distribution system into several smaller  
2 zones leads to a notable reduction in the total ENS and an enhancement in system reliability. As  
3 depicted in Fig.B.3, the increase in the number of MGs up to 7 significantly influences the system's  
4 ENS. However, beyond 7 MGs, the total ENS exhibits a near-constant trend. Therefore, it could  
5 be claimed that constructing 7 or more MGs would be suitable for the studied 85-bus distribution  
6 system considering reliability features. Noteworthy to mention, constructing more than 10 MGs is  
7 considered impractical based on the assumed operational constraints.

8

## 9 **6. Conclusions**

10 This research presents a novel methodology aimed at partitioning extensive distribution systems  
11 into multiple MGs to enhance system reliability by minimizing ENS resulting from DGs and  
12 busbar failures. The conventional ENS formulations were modified to account for failure impact  
13 within individual MG components and their influence on neighboring MGs. Additionally, optimal  
14 placement of energy storages was considered to maximize the utilization of installed DGs. The  
15 study introduced the DGSO algorithm, an enhanced version of the group search optimization  
16 algorithm, utilizing intelligent scroungers to facilitate an exhaustive search, yielding superior  
17 solutions. The proposed approach's efficacy was evaluated across three distinct case studies: a  
18 single-branch radial distribution system, the PG&E 69-bus system, and an Indian 85-bus test  
19 system. The results identified an optimal number of MGs for the single-branch distribution system,  
20 while the multi-branch radial system indicated multiple potential values for MG count. The  
21 promising outcomes observed in implementing the partitioning strategy within the Indian 85-bus  
22 radial distribution system underscore its practical applicability. This study primarily focuses on  
23 mitigating ENS resulting from two specific system failures during network partitioning into MGs.

1 While the research acknowledges the importance of examining additional potential system failures  
2 and their impact on system performance through the assessment of diverse reliability indices or  
3 the introduction of new measures, it emphasizes the relevance of this work primarily to radial  
4 distribution systems. Furthermore, as future research, investigating the influence of MG  
5 construction on the reliability of circular systems is suggested.

## 6 **Acknowledgement**

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## Appendix A

### ✓ ENS Caused by Failures of WTs and PV modules

In this paper, the reliability of installed WTs and PVs is taken into account and the ENS caused by their failure is calculated. To do so, it is assumed that a WT consists of three main components including WT generator, AC/DC rectifier, and DC/AC inverter and, other parts of the WT are assumed to operate completely reliable [28]. On the other hand, a PV module consists of PV array, DC/DC converter, and DC/AC inverter. By considering normal/failure operation of DG components, knowing the failure rate and repair time of each component, and extracting an appropriate Markov model, the reliability indexes of WTs and PVs are calculated as follows [29]:

$$\lambda_{WT} = \lambda_{WG} + \lambda_{Rec} + \lambda_{Inv} \quad (A.1)$$

$$\mu_{WT} = \frac{1}{r_{WT}} = \frac{\lambda_{WG} + \lambda_{Rec} + \lambda_{Inv}}{\left[ \left( 1 + \frac{\lambda_{WG}}{\mu_{WG}} \right) * \left( 1 + \frac{\lambda_{Rec}}{\mu_{Rec}} \right) * \left( 1 + \frac{\lambda_{Inv}}{\mu_{Inv}} \right) - 1 \right]} \quad (A.2)$$

$$\lambda_{PV} = \lambda_{Array} + \lambda_{Conv} + \lambda_{Inv} \quad (A.3)$$

$$\mu_{PV} = \frac{1}{r_{PV}} = \frac{\lambda_{Array} + \lambda_{Conv} + \lambda_{Inv}}{\left[ \left( 1 + \frac{\lambda_{Array}}{\mu_{Array}} \right) * \left( 1 + \frac{\lambda_{Conv}}{\mu_{Conv}} \right) * \left( 1 + \frac{\lambda_{Inv}}{\mu_{Inv}} \right) - 1 \right]} \quad (A.4)$$

### ✓ Single-Branch Radial Distribution System

Assuming that the radial distribution network consists of only one branch, the system busbars are allocated tandem. The schematic of this structure is illustrated in Fig.A.1 (a). For partitioning such systems, MGs would be sited one after the other. If a busbar failure occurs in upstream MGs, all the downstream MGs will be disconnected from the grid. From the reliability point of view, each

upstream MG could be considered as a component consisting of several busbars operating in series with each other. By using the proposed Markov model and assuming the equal failure rates and repair times for all distribution system busbars, the required parameters are calculated as follows:

$$\lambda_{UP-MG} = \lambda_1 + \lambda_2 + \dots + \lambda_M = M * \lambda \quad (A.5)$$

$$\mu_{UP-MG} = \frac{1}{r_{UP-MG}} = \frac{\lambda_1 + \lambda_2 + \dots + \lambda_M}{\left[ \left(1 + \frac{\lambda_1}{\mu_1}\right) * \left(1 + \frac{\lambda_2}{\mu_2}\right) * \dots * \left(1 + \frac{\lambda_M}{\mu_M}\right) - 1 \right]} \quad (A.6)$$

$$\mu_{UP-MG} = \frac{1}{r_{UP-MG}} = \frac{M * \lambda}{\left[ \left(1 + \frac{\lambda}{\mu}\right)^M - 1 \right]} \quad (A.7)$$

where  $\lambda_{Up-MG}$  ,  $\mu_{Up-MG}$  , and  $r_{Up-MG}$  indicate the failure rate, repair rate, and repair time corresponding to the busbar failures in an upstream MG, respectively.

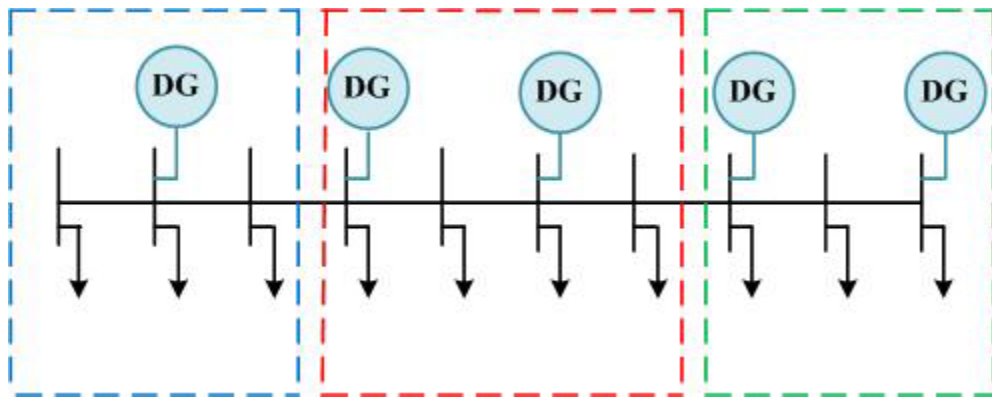
### ✓ Multi-Branch Radial Distribution System

If a multi-branch radial distribution system is studied, the impact of busbar failures in upstream MGs on the downstream zones will be different. When the amount of ENS caused by the upstream-side failures is calculated, the upstream busbars will be in the same path connecting the main grid and downstream zone or not. The branches located in the same path are considered as components that are operating in series which means failure occurrence in one of such busbars leads to disconnection of the downstream zone from the main grid. Fig.A.1 (b) shows the schematic of a radial distribution system with two MGs. MG2 is located in downstream part of MG1. Since MG1 consists of several branches, failure occurrence in some busbars (buses 1-6) will lead to islanded operation of MG2. Then,  $\lambda_{Up-MG}$ ,  $\mu_{Up-MG}$  , and  $r_{Up-MG}$  indices are calculated as follows, where  $M_{Path}$  is the number of busbars located in the path connecting the MG to the main grid.

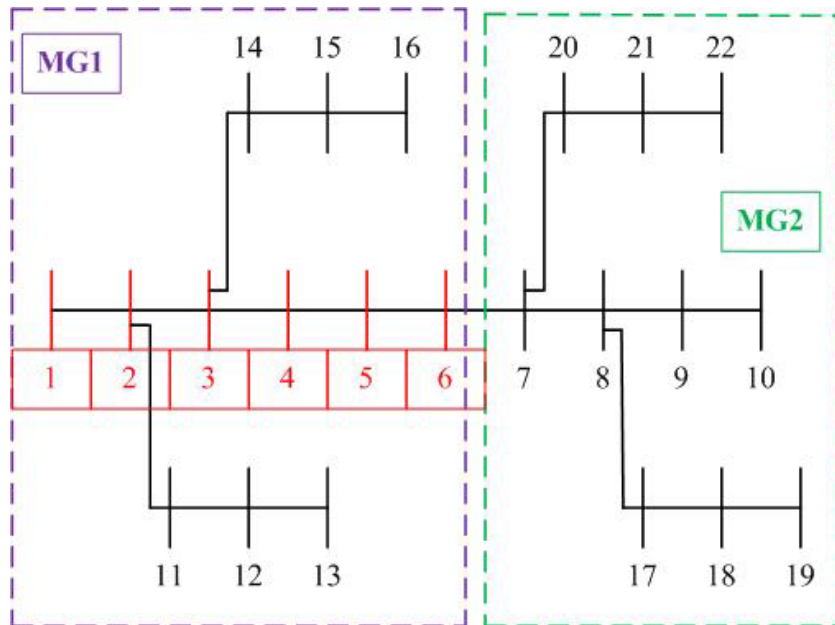
$$\lambda_{UP-MG} = \lambda_1 + \lambda_2 + \dots + \lambda_{M_{Path}} = M_{Path} * \lambda \quad (A.8)$$

$$\mu_{UP-MG} = \frac{1}{r_{UP-MG}} = \frac{\lambda_1 + \lambda_2 + \dots + \lambda_{M_{Path}}}{\left[ \left( 1 + \frac{\lambda_1}{\mu_1} \right) * \left( 1 + \frac{\lambda_2}{\mu_2} \right) * \dots * \left( 1 + \frac{\lambda_{M_{Path}}}{\mu_{M_{Path}}} \right) - 1 \right]} \quad (A.9)$$

$$\mu_{UP-MG} = \frac{1}{r_{UP-MG}} = \frac{M_{Path} * \lambda}{\left[ \left( 1 + \frac{\lambda}{\mu} \right)^{M_{Path}} - 1 \right]} \quad (A.10)$$



(a) Single branch



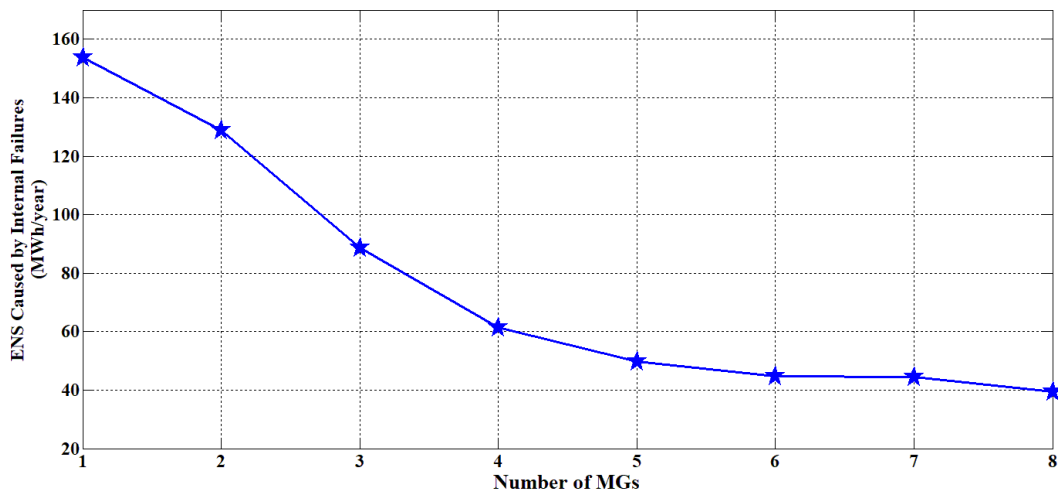
(b) Multi-branch

**Fig.A.1.** Schematic representation of a radial distribution system

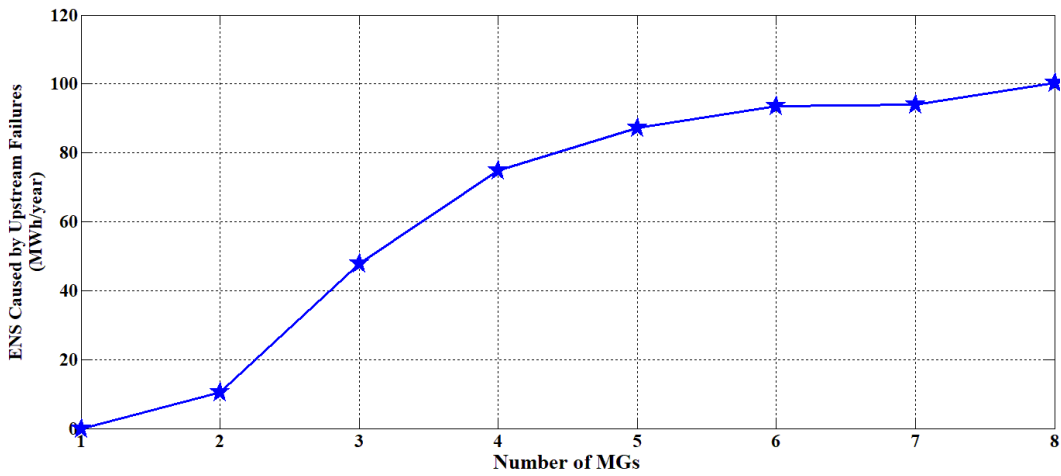
## Appendix B

**Table.B.1: Specifications of installed DGs for Case.1 and Case.2 [15].**

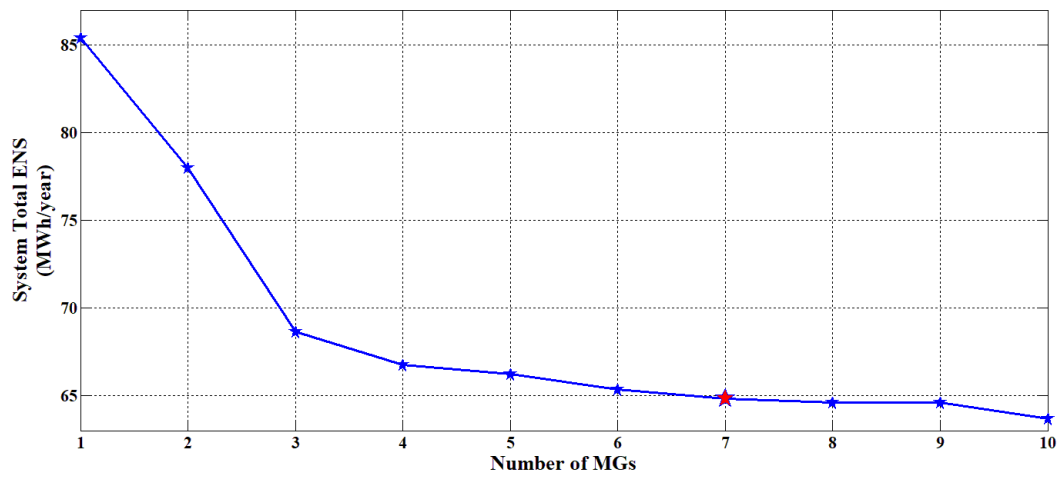
DG Type	Installing Places	Ratings (kW)
WT	16, 25, 34, 49, 52, 55	50, 50, 50, 50, 75, 75
PV Modules	17, 26, 44, 50, 53, 65	25, 50, 25, 25, 25, 25
BG	48, 51, 54, 57	150, 150, 150, 100



**Fig.B.1** ENS caused by internal failures for Case.1



**Fig.B.2** ENS caused by upstream failures for Case.1



**Fig.B.3.** System total ENS for Case.3