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A Comprehensive Review and Comparative Analysis

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Heating and Cooling Loads Forecasting for Residential Buildings Based on Hybrid Machine Learning Applications: A Comprehensive Review and Comparative Analysis

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ABSTRACT Prediction of building energy consumption plays an important role in energy conservation, management, and planning. Continuously improving and enhancing the performance of forecasting models is the key to ensuring the performance sustainability of energy systems. In this connection, the current paper presented a new improved hybrid model of machine learning application for forecasting the cooling load (CL) and the heating load (HL) of residential buildings after studying and analyzing various types of CL and HL forecasting models. The proposed hybrid model, called group support vector regression (GSVR), is a combination of group method of data handling (GMDH) and support vector regression (SVR) models. To forecast CL and HL, this study also made use of base methods such as back-propagation neural network (BPNN), elastic-net regression (ENR), general regression neural network (GRNN), k-nearest neighbors (kNN), partial least squares regression (PLSR), GMDH, and SVR. The technical parameters of the building were utilized as input variables of the forecasting models, and the CL and HL were adopted as the output variables of each network. All models were saved in the form of black box after training and initial testing. Finally, comparative analysis was performed to assess the predictive performance of the suggested model and the well-known basic models. Based on the results, the proposed hybrid method with high correlation coefficient (R) and minimal statistical error values provided the most optimal prediction performance.

INDEX TERMS Heating load (HL), cooling load (CL), forecasting, machine learning, artificial neural network (ANN), regression

ABBREVIATIONS

HVAC	Heating ventilation and air conditioning	GPR	Gaussian process regression
EBP	Performance of buildings	MPMR	Minimax probability machine regression
HL	Heating load	MLR	Multiple linear regression
CL	Cooling load	ELN	Elastic net
WSHP	Water source heat pump	RF	Random forests
GSVR	Group support vector regression	XGB	Extreme gradient boosting trees
GMDH	Group method of data handling	RNN	Recurrent neural networks
SVR	Support vector regression	GRU	Gated recurrent units
BPNN	Back propagation neural network	LSTM	Long short-term memory

ENR	Elastic-net regression	SLFF-ANN	Single layered feed-forward artificial neural network
GRNN	General regression neural network	CART	Classification and regression tree
kNN	k-nearest neighbor	CHAID	Chi-squared automatic interaction detector
PLSR	Partial least squares regression	GLR	General linear regression
ELM	Extreme learning machine	AR	Auto regressive
SVM	Support vector machine	GA-SVR	Genetic algorithm support vector regression
DT	Decision tree	GA-WD-SVR	Genetic algorithm wavelet decomposition support vector regression
MILP	Mixed-integer linear program	EDL	Extreme deep learning
OSELM	Online sequential extreme learning machine	LR	Linear regression
MARS	Multivariate adaptive regression splines	ETR	Extra tree regressor
ANN	Artificial neural network	RC	Resistance Capacitance
LS-SVM	Least square support vector machine	GBDT	Gradient Boosted Decision Tree
DNN	Deep neural network	XGBoost	Extreme Gradient Boosting
FFNN	Feed forward neural network	TB	Tree bagger
RBFNN	Radial basis function neural network	BoostedT	Boosted tree
MLP	Multilayer perceptron	BaggedT	Bagged tree
ANFIS	Adaptive neuro-fuzzy interference system	VAF	Variance accounted for
WDSVR	Wavelet decomposition support vector regression	CV	Coefficient of variation
PCA	Principal component analysis	R	Correlation coefficient
KPCA	Kernel principal component analysis	R^2	Accuracy
ARX	Autoregressive with exogenous	MSE	Mean square error
MNR	Multiple nonlinear regression	RMSE	Root mean square error
PENN	Probabilistic entropy-based neural	MAE	Mean absolute error
LSVM	Least square support vector machine	MAPE	Mean absolute percentage error
GBM	Gradient boosted machine	MRE	Mean relative error
NN	Neural network	APNN	Multi-layer hybrid

I. INTRODUCTION

Today, the need for energy has increased in many folds, and the significant energy consumption worldwide is mainly related to residential and commercial sectors. Therefore, managing industries such as transportation and construction and saving energy can be challenging tasks [1], [2]. Recent research has indicated that residential buildings have a significant share of energy consumption because of the increased population [3], [4]. It is highly necessary to have complete information concerning the performance of buildings in order to manage and optimize their energy consumption. Initially, this requires identifying the energy sources and end-uses of the building [1]. District heating supply, electricity, and natural gas are the important energy resources in a building; however, the main end-use applications include heating ventilation and air conditioning (HVAC), lighting, elevators, domestic hot water, and kitchen equipment. Of note, among the aforementioned energy resources and major end-uses of buildings, HVAC operation scheduling and indoor and outdoor conditions are two effective factors in building performance assessment [5], [6]. Considered as a fundamental infrastructure in a building, HVAC plays a major role by either adding or removing the cooling load (CL) and heating load (HL) to/from the indoor climate of residential buildings. A major concern is that these systems consume approximately 40% of the total energy, particularly in office buildings [7], [8]. Nonetheless, very few

fundamental solutions have been developed to improve the performance and management of HVAC systems. Due to the significant impact of meteorological factors on HL and CL, the performance of HVAC systems cannot be adapted to external climate change; on the other hand, improper performance of these systems can augment the energy consumption and reduce convenience in terms of cooling and heating [9], [10]. Improving the energy efficiency of buildings through sustainable construction management in urban environments and accurate dynamic load forecasting can be key steps to ameliorating the performance of HVAC systems and saving energy in residential buildings [11], [12].

Improper design and structure of buildings lead to the overuse of these technologies, high energy consumption, and an increase in the emission of carbon dioxide by about 40 %. Accordingly, widespread concerns regarding energy loss and its negative impacts on the environment have made the energy performance of buildings (EPB) the subject of more recent research around the globe [13]–[15]. Designing energy-efficient buildings with enhanced energy conservation properties are among the most important approaches to energy management in order to decrease energy demand and save energy. This can be achieved by initial forecasts of HL and CL in residential buildings. To forecast the required cooling and heating capacity, construction designers need information concerning building specifications and weather conditions in the area [16], [17]. Temperature, solar radiation, wind speed,

humidity, and pressure are among the most influential climatic factors in forecasting the CL and HL of buildings. When considering the CL and HL of a building, the following should be taken into account: the relative compactness of buildings, the roof size, the wall surface, the glazing area, height of the roof, the number of walls, and area [18], [19].

Currently, building energy simulation tools are widely utilized in various fields to facilitate an efficient design, optimal performance of energy-efficient buildings, and comparison of buildings with identical scales, where the effect of a single modified parameter is observed over a range of values. The simulation results regarding the design and comparison in some work have often been able to accurately represent the actual measurements [20], [21].

Generally, using building energy simulation software can be a good solution for analyzing the impact of building design indicators; however, this method is time-consuming and requires expert users to perform the simulations, and sometimes there is inconsistency in the accuracy of the estimated results in various building simulation software packages [20]. Hence, in some studies, modern methods such as statistical analysis, artificial neural networks, and machine learning are implemented to forecast the CL and HL of buildings and analyze the effect of various building parameters [15, 16]. The advantage of these methods is that after sufficiently training the model, an exact and reliable response can be obtained even by changing certain design parameters of the building. Furthermore, methods such as statistical analysis reinforce our understanding concerning the impact of quantities that are differently focused by designers or architects.

Various data mining techniques such as principal component analysis (PCA) [24], extreme learning machine (ELM) [10], [25], support vector machine (SVM) applications [26]–[32], k-means [33], deep learning techniques [31], [32], [34]–[40], decision tree (DT) [13], diverse regression approaches and artificial neural networks [16], [20], [29], [41]–[64], and hybrid methods based on regression models [32], [65]–[67] have been used in EPB and forecasting the required energy of residential buildings. A valuable study [68], examines facade retrofitting measures to minimize the demand for heating and cooling in residential and commercial buildings.

A mixed-integer linear program (MILP) in [69] has also been applied to an integrated model prediction for optimal operation of the HVAC in large-scale buildings. The relationship between the design and structural features of a building with HL and CL using new ELM-based methods and its variants in online sequential ELM (OSELM) was studied to forecast the HL and CL in [18]. The CL and HL of a residential building in [25] were forecasted via multivariate adaptive regression splines (MARS), ELM, and hybrid model, where the structural parameters of the building were considered as network inputs. In another study [70], to design an energy-efficient building, ELM method was employed to

forecast the CL and HL of residential buildings. In [26], the energy consumption of a building in a tropical region was predicted by accounting for three samples of weather data as input characteristics for the support vector machine. In [27], the CL of an office building was forecasted using artificial neural network (ANN) and SVM methods; their results were ultimately compared to specify the impact of input variables on the prediction accuracy. CL was predicted to optimize an HVAC system [28] by considering the meteorological information for the least square support vector machine (LS-SVM). In [37], a deep neural network (DNN) was employed along with the structural features of the building as inputs to predict CL and HL. A short-term CL prediction in an educational building in Hong Kong was performed in [34] by the deep neural network. In their work, time variables and temperature data were considered as input variables. Another study in Hong Kong [34] carried out a short-term CL prediction of an educational building via deep recurrent neural network-based strategies; they considered two types of time variables and indoor/outdoor ambient temperature data as network input variables. In [36], a deep learning application, called long short-term memory (LSTM) network, was implemented to predict the lighting loads, miscellaneous electrical loads, number of occupants, and internal heat gains in two office buildings. In [13], the energy demand forecasting model of a residential building was expanded using the DT method. [58] employed a feed-forward neural network (FFNN) for thermal comfort and saved 36.5% of the energy in the building. [59] predicted the HL of a building for above-normal energy consumption detection in a university campus with ANN techniques such as FFNN, radial basis function network (RBFN), and adaptive neuro-fuzzy interference system (ANFIS); in this regard, the heating consumption of the previous day, temperature data, and day of the week were selected as input variables for networks. CL and HL prediction of a building in [12, 44] was performed through the use of ANN in order to manage the HVAC system; in these studies, 11 air-handling units and meteorological data were utilized as input variables, respectively. Using back propagation neural network (BPNN), [61] forecasted the cooling demand in a building for operational planning of stable energy supply and energy savings. This work considered air temperature and relative humidity as additional inputs to the network. The CL of a building was predicted in [62] so as to determine the daily operation of the building, and it was optimized using ANN method. In their approach, the network input variables were water temperature of indoor equipment, outdoor humidity/temperature, chilled water prepared in ice tanks or elsewhere, electric current used by chiller, on/off status of compressors, and date data. [63] forecasted the HL of a building by use of the MLP method and considering the meteorological data as network input variables. In another work [64], the MLP method was employed to forecast the CL and HL of a building in order to design an energy-efficient building, in which the

meteorological and date data were considered as input variables. In [41], prediction of the CL of a building was done using an artificial neural network model called multilayer perceptron, and climatic data inputs were considered as parameters. In [16], the energy performance of a building was examined by forecasting the CL and HL via machine learning applications such as general linear regression, ANN, DT, support vector regression (SVR), and ensemble inference model. [42] forecasted the CL and HL of a building to discover the peak load of water source heat pump (WSHP) in the building environment and supply the heating and cooling demand; in this connection, six regression models of data mining methods were used, in which the meteorological data, previous load consumption, and time and date information were taken as the input variables of the network. For increasing the building energy efficiency, four regression applications, namely chaos-SVR, wavelet decomposition (WD)-SVR, SVR, and BP were utilized to forecast the CL of the building in [71]. In some studies [28, 29], CL prediction was performed in a non-residential building to enhance the operation of the HVAC system using a combination of PCA, kernel (k)-PCA, and SVR methods. In [57], autoregressive with exogenous (ARX) method was employed to predict the CL and HL of a building so as to manage supply and demand of energy; the meteorological data were considered as network input variables. The CL of a building in [45] was forecasted via general regression neural network (GRNN), in which the network input variable was the external hourly temperature for a 24 h period obtained from the Kuwait Institute for Scientific Research over the five years of data collection. In [46], to predict the hourly CL of a building, four methods (traditional BPNN, radial basis function neural network (RBFNN), GRNN and SVM) were used; finally, after comparing the results, SVM and GRNN were proven to have a better performance accuracy. [47] investigated the influence of the structural conditions of the building and its interior design on the cooling load of residential and office buildings. By developing different regression models, [48] predicted the HVAC system energy demand from the CL and HL demand of building. [34, 35] forecasted the CL and electric demand of commercial buildings in short-term and ultra-short-term models to manage the energy demand and improve the energy efficiency of HVAC systems via hybrid SVR. In [51], using the SVR method, the CL of a large office building in a coastal town of China was forecasted, and a new model of vector-based SVR was presented to increase the robustness and forecasting accuracy. Via a multiple nonlinear regression (MNR) model, [52] predicted the optimal operation of HVAC systems and short-term cooling loads; in their study, the network inputs were the physical characteristics of the building, meteorological information, and HVAC operational variables. [53] forecasted the CL of a building using a probabilistic entropy-based neural (PENNN) model. In [54], the HL of a building was predicted through the use of a multiple

regression method and considering certain climatic conditions such as sol-air temperature, thermal resistance, and surface-to-volume ratio as network inputs. In [55], CL and HL were predicted using neural networks and extraction of a black box model, which was the trained network. In their method, climate data include temperature, humidity, wind speed, and sunlight were used as input data. The prediction of HL and CL associated with residential building has been performed based on existing historical data and using different machine learning techniques called SVM, RF, FFNN, Gradient Boosted Regression Trees, XGBoost in [72]. In another study, indoor temperature was predicted using a network (called nonlinear autoregressive) based on back-propagation neural networks; the considered network inputs were meteorological parameters and HVAC equipment parameters [56]. In [65], a hybrid regression model of ANN and SVM applications was used to forecast the thermal load of 10 residential buildings located in Rottne, Sweden, in order to control district cooling and heating systems. In [73], a multi-layer hybrid model (APNN) has been proposed to forecast HL and CL of a residential building by considering the technical specifications of the building and climatic data as the input of the network. In this paper, the suggested hybrid technique is based on combination an ARX and a particle swarm optimization neural network. [66] presented a hybrid solution comprised of a gray box and a black box containing certain machine learning methods based on regression using internal heat gain and weather data as inputs in order to predict the mean indoor air temperatures. In another study [67], for energy planning, management, and conservation, a novel enhanced integration model (stacking model) was proposed to forecast the HL of two educational buildings in Tianjin, China. The heating demand estimating of buildings in [74] has been done by considering the weather conditions and presenting a Global Forecast System sflux model. In a valuable study [75], considering the two energy flexibility indicators called the efficiency of active demand response events and the available heat storage capacity, the thermal inertia potential of the three apartments have been analyzed to correct their heat load pattern. In this study, user behavior, the effects of building envelopes, and weather conditions are selected as three effective indicators in evaluations.

Based on the above literature, the CL and HL of buildings were mainly predicted by implementing various methods on different data. These methods are categorized according to the type of datasets and utilized them to predict the CL and HL of buildings. In the end, the accuracy of the presented methods was assessed for similar data. Table 1 classifies the studies performed based on various data. In this classification, the datasets were divided into four clusters, namely real measurements, simulated (Ecotect), simulated (Energy plus), and simulated (DeST). Real-world measurement data were specific to each study.

TABLE 1. Reviewing and categorizing the conducted research based on the various datasets

Type of dataset	References	Types of input variables in dataset	Building type	Purpose of prediction
Simulated (Ecotect)	[16], [18], [25], [37]	Relative compactness, surface area, wall area, roof area, orientation, glazing area, overall height, and glazing area distribution	Residential	Estimating energy consumption and energy-efficient building design
Simulated (Energy plus)	[48], [57], [64], [69], [70]	Daily average dry-bulb and wet-bulb temperatures, solar radiation and aperture, daylight aperture, overhang, side-fins projections, daily average clearness index, and date data	Residential and non-residential	Energy-efficient building design
Simulated (DeST)	[28]	Dry-bulb temperature, solar radiation, humidity	Non-residential	HVAC system optimization
Real measurement datasets	[13], [20], [26], [27], [33]–[35], [40], [40]–[45], [48], [50]–[52], [57]–[62], [64]–[66], [70], [72]	Different in various datasets	Residential and non-residential	Different in various studies

As mentioned in the literature above, different studies have used different algorithms of ANNs, machine learning, deep learning, ELM, and a variety of hybrid solutions to forecast the CL and HL of buildings. In order to easily access the analysis provided in each of these studies, they were reviewed and categorized in Table 2 based on the type of algorithm used.

TABLE 2. Reviewing and categorizing the conducted research based on the employed algorithm

Method	Algorithm	References
ANN	MLP	[16], [18], [20], [25], [27], [37], [41], [42], [48], [59], [60], [62]–[65], [72]
	BPNN	[28], [46], [51], [57], [61], [71]
	RBFNN	[46], [59]
	GRNN	[45], [46]
	ANFIS	[59]
	PENN	[53]
Machine learning	SVM	[26], [27], [43], [44], [46], [65], [72]
	SVR	[16], [34], [48], [51], [67], [71]
	GPR	[37], [42]
	GPM	[37]
	MLR	[34], [42], [51], [52], [57]
	XGB	[34], [42], [67]
	GBM	[34]
	DT	[13]
	AR	[52], [57]
	ARX	[52], [57], [73]
	MNR	[52]
	KNN	[67]
Deep learning	DNN	[34], [37]
	RNN	[28], [35]
	LSTM	[31], [35], [36]
ELM	-	[18], [25], [70]
MILP	-	[69]
Hybrid models	-	[16], [18], [25], [43], [44], [49], [54], [58], [66], [67], [71], [73]

As observed in Table 2, most studies typically used MLP, SVM, and SVR algorithms to forecast the CL and HL of buildings. However, a review of recent studies shows that researchers are increasingly turning to the idea of combining models to improve the prediction of CL and HL. The methods used to predict CL and HL have their own unique accuracy coefficient and error. In different studies, various types of statistical performance metrics have been utilized to evaluate the performance of each algorithm. Table 3 categorizes and reviews the conducted research according to the statistical performance metrics of each algorithm.

This paper reviewed most of the studies performed to predict the CL and HL of buildings based on different criteria. Table 4 depicts a comparative approach to assessing the effectiveness of each of the methods employed in the studies. Given that the comparison of results should be made for the same data used for each algorithm, these comparisons are made for the same datasets used in several studies.

TABLE 3. Reviewing and categorizing the conducted research based on the statistical performance metrics

Performance	References
MAE	[18], [34], [66], [73]
MAPE	[25], [42], [59], [65], [71], [73]
MSE	[26], [63]
RMSE	[16], [27], [28], [35], [43], [44], [46], [64], [70], [72], [73]
MRE	[60]
R^2	[45], [48], [49], [52], [54], [58], [67]
R	[41], [51], [53]
CV	[57], [62]
VAF	[37]

TABLE 4. Performance comparison of various algorithms implemented for the same data in predicting the CL and HL of buildings

Simulated (Energy plus)					Simulated (Ecotect)			
Ref.	Method	Performance	Type of energy consumption forecasted	Building type	Ref.	Method	Performance	Type of energy consumption forecasted
[70]	ELM	RMSE=74.02 kWh	Cooling and Heating	Residential	[37]	DNN	VAF=99.76%	Cooling
[64]	MLP	RMSE=752-1410 kWh	Cooling	Residential		GBM	VAF=98.53%	
		RMSE=607-785 kWh	Heating			GPR	VAF=99.13%	
		RMSE=607-785 kWh	Lighting			MPMR	VAF=89.55%	
		RMSE=607-785 kWh	Overall			DNN	VAF=98.05%	Heating
[57]	MLR	CV=173.2% - 249.8%	Heating	Non-residential		GBM	VAF=96.54%	
		CV=47.5% - 48.5%	Cooling			GPR	VAF=99.84%	
	AR	CV=124.6% - 185.9%	Heating			MPMR	VAF=88.022%	
		CV=32.4% - 37.6%	Cooling					
	ARX	CV=49.6% - 178.8%	Heating		[16]	ANN	RMSE=1.678 kW	Cooling
		CV=8.8% - 34%	Cooling			SVR	RMSE=1.647 kW	
	BPNN	CV=121.2% - 174.9%	Heating			CART	RMSE=1.841 kW	
		CV=25.3% - 30.6%	Cooling			CHAID	RMSE=1.859 kW	
	MLR	CV=58.5% - 70.7%	Heating	Residential		GLR	RMSE=1.74 kW	
		CV=17.9% - 25.9%	Cooling			SVR+ANN	RMSE=1.566 kW	
	AR	CV=14.7% - 23.7%	Heating			ANN	RMSE=0.61 kW	Heating
		CV=8.3% - 8.6%	Cooling			SVR	RMSE=0.346 kW	
	ARX	CV=10.8% - 22%	Heating			CART	RMSE=0.8 kW	
		CV=5% - 6.9%	Cooling			CHAID	RMSE=0.909 kW	
	BPNN	CV=23% - 23.3%	Heating			GLR	RMSE=1.039 kW	
		CV=6.4% - 7.1%	Cooling			SVR+ANN	RMSE=0.428 kW	
[48]	Regression (Linear model)	$R^2=96.31\%$	Cooling (VAV)	Non-residential	[18]	ELM(RBF)	MAE=0.0454 kW	Cooling
		$R^2=95.18\%$	Cooling (CAV)			ELM(Hardlim)	MAE=0.037 kW	
		$R^2=99.76\%$	Cooling (FC)			ELM(Sig)	MAE=0.0348 kW	
		$R^2=97.08\%$	Cooling (EMB)			OSELM(RBF)	MAE=0.369 kW	
		$R^2=96.70\%$	Cooling (ALU)			OSELM(Hardlim)	MAE=0.4008 kW	
		$R^2=97.59\%$	Heating (VAV)			OSELM (Sig)	MAE=0.3229 kW	
		$R^2=97.48\%$	Heating (CAV)			ELM(RBF)	MAE=0.0596 kW	Heating
		$R^2=99.02\%$	Heating (FC)			ELM(Hardlim)	MAE=0.0566 kW	
		$R^2=98.21\%$	Heating (EMB)			ELM(Sig)	MAE=0.0389 kW	
		$R^2=98.13\%$	Heating (ALU)			OSELM(RBF)	MAE=0.313 kW	
	Regression (Multivariate model)	$R^2=99.39\%$	Cooling (VAV)			OSELM(Hardlim)	MAE=0.3964 kW	
						OSELM (Sig)	MAE=0.2755 kW	

		$R^2=98.39\%$	Cooling (CAV)	
		$R^2=99.89\%$	Cooling (FC)	
		$R^2=98.44\%$	Cooling (EMB)	
		$R^2=98.23\%$	Cooling (ALU)	
		$R^2=98.32\%$	Heating (VAV)	
		$R^2=99.69\%$	Heating (CAV)	
		$R^2=99.05\%$	Heating (FC)	
		$R^2=98.38\%$	Heating (EMB)	
		$R^2=98.34\%$	Heating (ALU)	
[69]	MILP	Overall cost = 136.64 €	Cooling and heating	Residential and non-residential

[25]	MARS	MAPE=19.2319	Cooling
	ELM	MAPE=27.7105	
	Hybrid Model	MAPE =19.5096	
	MARS	MAPE =2.2043	Heating
	ELM	MAPE =17.739	
	Hybrid Model	MAPE =2.2835	

[73]	Hybrid Model	MAPE=8.5600 RMSE=0.367 MAE=0.284 MAPE=11.1490 RMSE=0.7640 MAE=0.611	Heating Cooling
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Most of the above-mentioned methods were studied and considered as a conventional method for forecasting and controlling the CL and HL of residential buildings. However, some of the work showed that building specifications could have a significant impact on the CL and HL of a building [37], [76]. To forecast the CL and HL of buildings with high accuracy coefficient and least prediction error by regression-based methods, it is necessary to establish a linear mapping between the input variables (building characteristics) and output variables (CL and HL). In this paper, a hybrid model called group support vector regression (GSVR) is proposed by combining the group method of data handling (GMDH) and SVR models in order to estimate the relationship between input and output data and improve the CL and HL prediction results. GMDH and SVM have already been combined in several areas with significant improvements in predictive accuracy over other neural networks, machine learning, and other statistical models; these studies have also shown that combining these two models can improve the efficiency and robustness in the prediction operation [55, 56]. To present a comparative analysis approach to evaluating the results of CL and HL forecasting, in addition to the proposed hybrid model, other artificial neural network and machine learning applications, including BPNN, elastic-net regression (ENR), GRNN, k-nearest neighbors (kNN), partial least squares regression (PLSR), GMDH, and SVR are implemented. Technical specifications and structural characteristics of a building influence its energy; therefore, structural characteristics are used such as relative compactness, surface area, overall height, roof area, orientation, wall area, glazing area distribution, and glazing area as inputs for the proposed methods to determine the output variables: CL and HL of residential buildings. CL and HL were considered as the output variables of the networks in this study. The energy forecasting framework is shown in Fig. 1.

The remainder of this paper is organized as follows: Section 2 introduces the case study. The proposed methods are

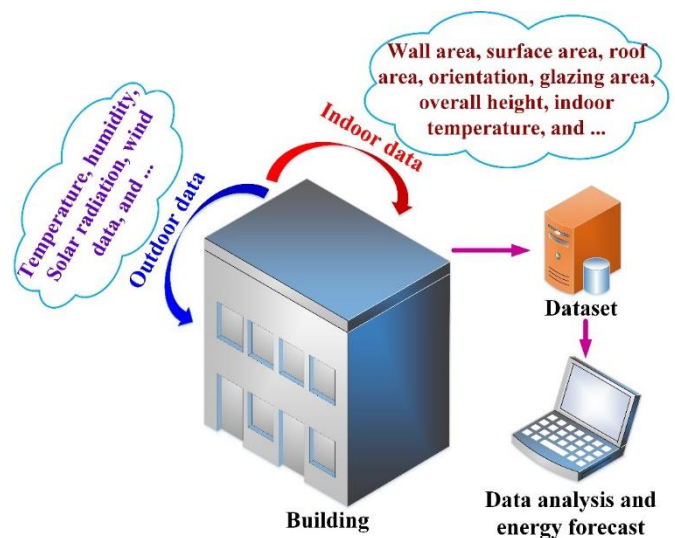


Figure 1. Energy forecasting framework

described in Section 3. Section 4 presents the CL and HL forecasting results using the suggested methods. In Section 5, the results and performance analysis of the suggested solutions are compared. Finally, Section 6 concludes the paper.

II. CASE STUDY

A dataset comprising 12 different building shapes is used, which is simulated by Tsanas and Xifara (2012) in Ecotect software [76]. Regarding the simulations, it was assumed that the buildings were located in Greece, Athens. The shapes of the buildings were created through considering the initial cubes ($3.5 \times 3.5 \times 3.5$), each with 18 elements. All buildings were constructed with the same materials and a volume of 771.75 m³. The simulated buildings differed in orientation, glaze area, interior dimensions, glaze area distribution, and certain other parameters. The envelope U-values of these buildings were considered as the ceiling (0.500), walls (1.780), window (2.260), and floor (0.860). U-values indicated the

overall performance in retaining heat and preventing it from escaping to the outside. The interior design of a building can have a major impact on its energy. In the simulation, the values of air speed: 0.30 m/s, clothing: 0.6, humidity: 60%, lighting level: 300 Lux were considered as interior design conditions. The internal gains were set to rational: 5 and latent: 2 W/m² while the infiltration rate was set to 0.5 for the rate of air change with the wind sensitivity being 0.25 air changer per hour. 95% of the complex state was assumed for thermal properties, and a temperature range of 19-24° C was considered for the thermostat range. 15-20 hours of weekdays and 10-20 hours of weekends were set for thermostat operation hours [1, 11].

The dataset consisted of 768 simulated buildings, each with eight characteristic properties (considered as input variables and represented in the data by X) and two actual valuable responses (CL and HL intended as output variables and marked with Y). Table 5 lists the input and output variables with the mathematical delegation for each variable and shows the number of conceivable values for these data [76].

The data used in this study were obtained by simulating and modeling different aspects of building energy and can be contrasted with real-world data; nevertheless, according to the literature cited by the producers of this dataset, recent works have shown that no inconsistency in real-world data and simulated data can affect the results of the used methods.

III. METHODOLOGIES

This section briefly describes artificial neural network algorithms and regression techniques used to analyze the data for predicting the CL and HL of buildings and finally evaluate the results.

A. Artificial neural networks and regression techniques

Artificial neural networks are a suitable means of modeling and estimation purposes. They are capable of learning from data and show generalized behavior after the learning process. Alongside artificial neural networks, regression applications can be used as statistical tools for analyzing or understanding a binary or multivariate relationship [29], [79].

TABLE 5. The input and output variables with mathematical symbols for each variable

Mathematical symbols	Variable names	Number of values
$X1$	Relative compactness	12
$X2$	Surface area	12
$X3$	Wall area	7
$X4$	Roof area	4
$X5$	Overall height	2
$X6$	Orientation	4
$X7$	Glazing area	4
$X8$	Glazing area distribution	6
$Y1$	Heating load	586
$Y2$	Cooling load	636

Today, regression is used as a powerful tool in the scientific, commercial, and industrial fields for forecasting, modeling, and optimization [80]–[82]. In the remainder of this section, different types of neural networks and regression methods are discussed.

1) BACK-PROPAGATION NEURAL NETWORK (BPNN)

Developed by Parker in 1972, BPNN is one of the well-known and widely used neural network algorithms in engineering applications. This algorithm is similar to a FFNN in every aspect except that it adds a back propagation to its structure. It is estimated that today, this algorithm is utilized in some 80% of the structure of other neural networks [58, 61]. As shown in Fig. 2, BPNN comprises an input layer, a hidden layer, and an output layer in its structure [84]. The number of nodes in the input layer, hidden layer, and the output layer are represented by letters m , T , and n , respectively. w_{ij} , w_{jk} reflects the weights of connections in the layers. Network input values and network prediction values are expressed by X and Y , respectively. Input signals with weight are received by the input layer and transmitted to the hidden layer after processing. As an internal processing layer, the hidden layer processes the signals and transmits them to the output layer [85]. The neural network training process requires an activation function; $f(X)$ is the sigmoid activation function used in this paper [79]:

$$f(x) = \frac{1}{(1 + e^{-x})} \quad (1)$$

The output of each neuron in the input layer is calculated as follows [86]:

$$O_{ik} = f\left(\sum_{j=0}^l W_{kj} O_{ij}\right), k = 1, 2, \dots, n \quad (2)$$

where W_{kj} is the connection weight from the j th input neuron to the k th hidden neuron. The output of each neuron in the output layer providing the network prediction is calculated as follows [86]:

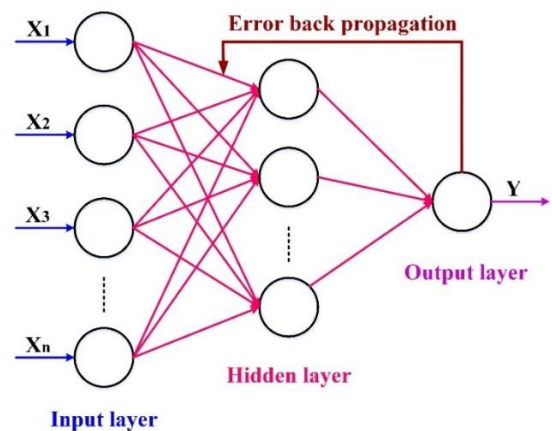


Figure 2. The structure of BPNN

$$Y_i = f\left(\sum_{k=0}^n W_k O_{ik}\right), k = 1, 2, \dots, n \quad (3)$$

where n is the number of hidden neurons, and W_k is the connection weight from k th hidden neuron to the output neuron.

2) GENERAL REGRESSION NEURAL NETWORKS (GRNN)

The general regression neural network (GRNN) is a one-pass learning algorithm suggested by Specht as an alternative to the back-error propagation training algorithm for the FFNN [87]. In fact, GRNN is an RBFN that can be used to predict and assess continuous variables, estimate nonlinear relationships between the output variable and a set of independent variables, and converge to the underlying regression level. Similar to other probabilistic neural networks, GRNN requires training samples to process. In this network, predictability and processing are also dependent on the data type [88]. Among the important advantages of this neural network, mention can be made of rapid learning even with large numbers of samples, establishing a relationship between the input variables and target variables of time series data, and fast convergence to a desirable regression level. As can be seen in Fig. 3, in the structure of GRNN, there are four layers, the input (X), pattern (P), summation (S), and output (Y), which are completely interconnected [89].

The input layer transfers the input variables to the pattern layer without any processing. The number of neurons in the training layer is determined by the training data, which functions as follows [90], [91]:

$$p_i = \exp\left[-\frac{(X - X_i)^T(X - X_i)}{2\sigma^2}\right], i = 1, 2, \dots, n \quad (5)$$

The outcome of the neuron i is expressed as follows:

$$D_i^2 = (X - X_i)^T(X - X_i) \quad (6)$$

where D_i^2 is the square of the Euclidean distance between the input variable and the sample corresponding to X , X is the

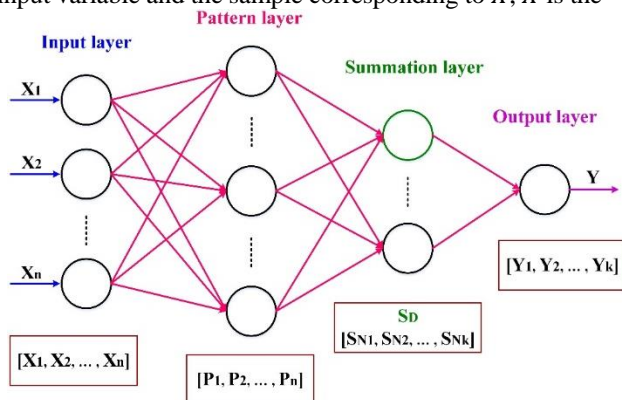


Figure 3. The four layers of GRNN

network input variable, T is the transpose symbol, and X_i is the learning sample corresponding to the neuron i .

The extracted patterns are transferred to the summation layer as input, where two types of summation are calculated. The first summation is derived from equation (7), in which the arithmetic sum of all neurons is computed and the output is demonstrated as equation (8). The second summation is derived from equation (9), in which the weight coefficients are added to the neurons and the output is expressed as equation (10) [89], [91]:

$$\sum_{i=1}^n \exp\left[-\frac{(X - X_i)^T(X - X_i)}{2\sigma^2}\right] \quad (7)$$

$$S_D = \sum_{i=1}^n p_i \quad (8)$$

$$\sum_{i=1}^n Y_i \exp\left[-\frac{(X - X_i)^T(X - X_i)}{2\sigma^2}\right] \quad (9)$$

where Y_i defines the i -th connection weight.

$$S_{Nj} = \sum_{i=1}^n Y_{ij} p_i, \quad j = 1, 2, \dots, k. \quad (10)$$

After calculating both weighted and arithmetic summations, their results are transferred to the output layer. Finally, through dividing the two summation types, the final output of the network is calculated as follows [92]:

$$Y_j = \frac{S_{Nj}}{S_D}, \quad j = 1, 2, \dots, k. \quad (11)$$

3) K-NEAREST NEIGHBORS (KNN)

kNN is an efficient technique for regression problems, classification, and non-parametric feature extraction. The main objective behind kNN is to provide an appropriate estimate based on Euclidean distance or, in other words, the mean of the nearest neighbors in feature space for the training set. These neighbors are selected from a set of training points. kNN is a precision algorithm with a unique property as it delays and continues the calculation operation until it obtains the best results [93]. As in other artificial neural networks and machine learning algorithms, datasets and, in particular, the number of k neighbors selected, have a great impact on the performance of kNN. Choosing small quantities for k leads to over-fitting, while large quantities entail a poor performance. A comparison of different subsets of training data is the best approach to selecting the optimal value of k . If the feature space is multi-dimensional, the data must be normalized

beforehand due to the distance comparison to selecting the nearest neighbor [94]. In this paper, kNN is used for regression. In this case, the response of testing point X_t is estimated as the weighted mean of the reactions of k training points such as X_1, X_2, \dots, X_k . A kernel function was utilized to calculate the weight of each neighbor. If X is a dataset of X_1, X_2, \dots, X_k members, each with N features, equation (12) calculates the proximity of each training point X_i to the testing point X_t using the weighted Euclidean distance [95], [96].

$$d(X_t, X_i) = \sqrt{\sum_{n=1}^N w_n (x_{t,n} - x_{i,n})^2} \quad (12)$$

The following equation shows how to derive the arrangement statistics for distances $d(X_t, X_i), i = 1, 2, \dots, M$.

$$0 \leq d(X_t, X_{(1)}) \leq d(X_t, X_{(2)}) \leq \dots \leq d(X_t, X_{(M)}) \quad (13)$$

Then, k nearest training points $X_{(1)}, X_{(2)}, \dots, X_{(k)}$ as the k -nearest neighbors of X_t are calculated.

Fig. 4 depicts a transparent example of a two-dimensional feature space ($N = 2$) of the k -nearest neighbors. In this example, $k = 5$ is assumed. As observed, the five training points are in the nearest Euclidean distance, with one test point selected as the nearest neighbor [96]. A kernel function can be used for the flexibility of the kNN regression model. In this paper, the Gaussian radial basis function (RBF) kernel was used and defined as follows:

$$\phi(X_t, X_{(i)}) = e^{-d(X_t, X_{(i)})/\beta} \quad (14)$$

where $\phi(X_t, X_{(i)})$ is a kernel function centered at the i th training point $X_{(i)}$ and β is a Gaussian rottenness factor [97]. Ultimately, by applying the kernel regression, the following estimate of the response X_t is obtained [96]:

$$\hat{f}(X_t) = \frac{\sum_{i=1}^k \phi(X_t, X_{(i)}) f(X_{(i)})}{\sum_{i=1}^k \phi(X_t, X_{(i)})} \quad (15)$$

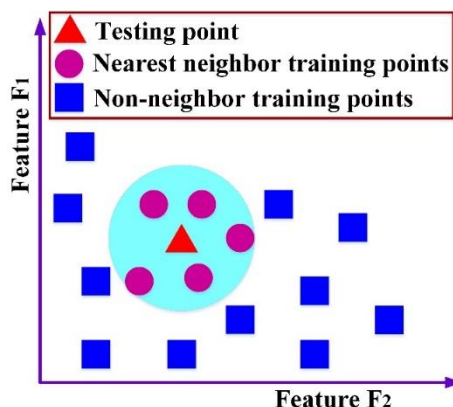


Figure 4. kNN of a testing point in a two-dimensional feature space

where k defines the number of the closest neighbors used for regression and $f(X_{(i)})$ is the known response of $X_{(i)}$.

4) GROUP METHOD OF DATA HANDLING (GMDH)

GMDH was first introduced in 1968 by Prof. Alexey Grigorevich Ivakhnenko as one of the data mining applications for performing nonlinear regression, prediction, function approximation, mathematical modeling, and pattern recognition. GMDH is further considered as a polynomial neural network. Continuous change during the training process is the major difference between GMDH and other neural networks [98], [99]. This network attempts to generate a performance in a feedback network based on a quadratic transmission function. Fig. 5 illustrates the GMDH neural network structure, which includes the input layers, the hidden layers, and the output layers. This network automatically specifies the effective input variables, the structure of an optimal model, the number of layers, and the number of neurons in the hidden layers [100]. High prediction accuracy, self-organized learning process, the accurate linear mapping between input and output variables, and precise identification of complex nonlinear systems are among the significant advantages of GMDH over other neural networks [101].

As a brief introduction for GMDH formulation description, a nonlinear system with n number of input variables (X_n) and output variables (Y) connected by the function f is considered as follows [100], [101]:

$$Y = f(X_1, X_2, \dots, X_n) \quad (16)$$

The relationship between the input and output variables in the above system can be rewritten based on the Kolmogorov–Gabor polynomial as below [102]:

$$Y = a_0 + \sum_{i=1}^m a_i X_i + \sum_{i=1}^m \sum_{j=1}^m a_{ij} X_i X_j + \sum_{i=1}^m \sum_{j=1}^m \sum_{k=1}^m a_{ijk} X_i X_j X_k + \dots \quad (17)$$

where X stands for inputs, m is the number of inputs, a shows the weights or coefficients, and Y is the model estimation of output. Each layer in the neural network functions based on its neurons. In a GMD neural network, each neuron must have two inputs per output. The following equation describes the number of neurons in the first layer for the n number of inputs [101]:

$$m = \frac{n^2 - n}{2} \quad (18)$$

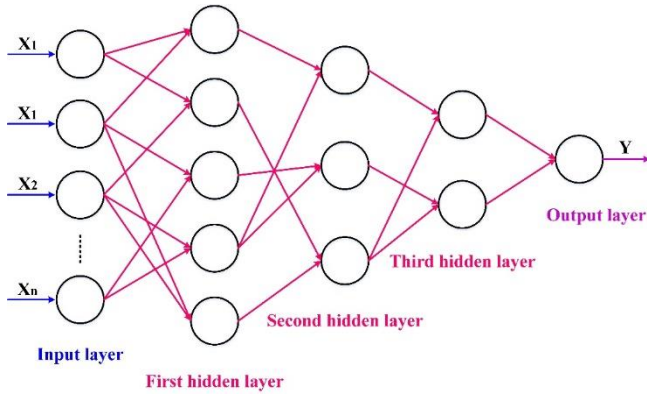


Figure 5. The principle structure of GMDH

In order for the GMDH algorithm to identify unknown α_i coefficients in the Kolmogorov–Gabor polynomial relation, it can be analyzed as follows [102], [103]:

$$G(X_i, X_j) = a_0 + a_1 X_i + a_2 X_j + a_3 X_i^2 + a_4 X_j^2 + a_5 X_i X_j \quad (19)$$

The regression methods for each pair of input variables X_i and X_j can optimally solve the coefficients α_i , according to which, the function G is given by considering the least squares error (20) principle as equation (21) [100], [102].

$$E = \frac{1}{M} \sum_{i=1}^M (Y_i - G_i O)^2 \quad (20)$$

where E is the least squares error, M shows the number of samples, and $G_i O$ depicts the desired output or target of the network.

$$Y_i = f(X_{i1}, X_{i2}, X_{i3}, \dots, X_{im}), i = 1, 2, 3, \dots, m \quad (21)$$

5) ELASTIC-NET REGRESSION (ENR)

In machine learning applications and the methods related to regression, classification, and prediction of different models, such factors as variance and bias affect the accuracy coefficient of the model. Until now, different methods have been proposed for regression or linear modeling in machine learning. The linear regression (LR) is one of the most common methods for linear modeling. Nevertheless, this method is sometimes observed to have poor performance in forecasting and analyzing. Over the recent years, researchers have proposed various suitable techniques for improving LR performance such as lasso, ridge regression, and ENR [104], [105].

ENR combines ridge regression and lasso, which was primarily introduced by Zou and Hastie in 2003 as a powerful technique for prediction and variable selection. Therefore, this method is utilized to generate regression and linear mapping between input and output variables for practical solutions

requiring high analytical accuracy [105], [106]. For an observed vector/signal ($Y \in R_n$), a certain measurement matrix ($X \in R_{n \times p}$), an unknown correct vector/signal to be recovered ($\beta^* \in R_p$), and the Gaussian noise term (z), the linear regression in the standard model is generally expressed as follows [107]:

$$Y = X\beta^* + z \quad (22)$$

ENR is feasible by solving the following minimization [107], [108]:

$$\min \lambda_1 \|\beta\|_1 + \frac{\lambda_2}{2} \|\beta\|_2^2 + \frac{1}{2} \|X\beta - Y\|_2^2 \quad (23)$$

where $\lambda_1, \lambda_2 \geq 0$ are both regularization parameters. In the above equation, two particular cases of elastic regression are further included: ridge regression in [109] with $\lambda_1 = 0$ and lasso in [110] with $\lambda_2 = 0$.

6) SUPPORT VECTOR REGRESSION (SVR)

As one of the SVM applications, SVR is used for regression, producing a linear mapping between input and target variables, and function estimation. Solving regression problems is the main function of SVR [111], [112]. Among SVR models, the classical model (ϵ -SVR) is a version of SVR basically considered in engineering and also used in this work. Fig. 6 shows the principle structure of SVR. This method presents the principle idea by minimizing the rate of error and singularizing the hyperplane, which gives the maximum margin [46]. In the SVR, the risk function (24) is minimized by training the function (25) and vectors contained in (26) [113]:

$$R = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^l (y1, \langle w, x \rangle) \quad (24)$$

$$f(x) = \langle w, x \rangle + b \quad (25)$$

$$\{(x1, y1), \dots, (xi, yi), i = 1, \dots, l\} \quad (26)$$

where w adjusts the model smoothness, $\langle w, x \rangle$ is a function of the input space fitting to the feature space, b shows the bias, and $(y1, \langle w, x \rangle)$ depicts the selected loss function. Solving this model requires solving an optimization problem as follow: [113], [114]:

$$\min \left(\frac{1}{2} \|w\|^2 + C \sum_{i=1}^l (\xi_i + \xi_i^*) \right) \quad (27)$$

Subject to:

$$\begin{cases} y_i - \langle W, X_i \rangle - b \leq \varepsilon + \xi_i \\ \langle W, X_i \rangle + b - y_i \leq \varepsilon + \xi_i^* \\ \xi_i, \xi_i^* \geq 0 \end{cases} \quad (28)$$

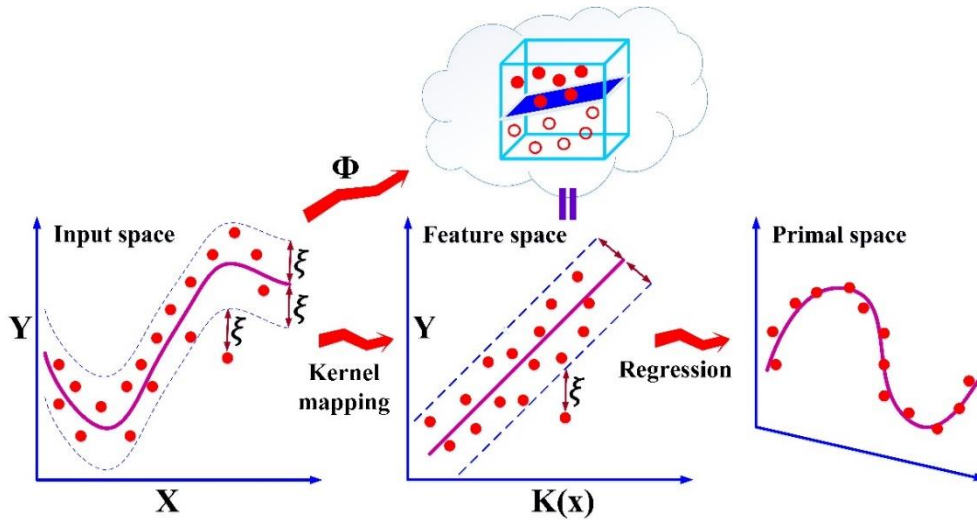


Figure 6. The principle approach of SVR

where ξ_i and ξ_i^* apply the functional constraints. The following expression is obtained after solving equation (27) [115], [116]:

$$f(X, \alpha_i, \alpha_i^*) = \sum_{i=1}^{N_{sv}} (\alpha_i - \alpha_i^*) (K(X_i, X_j)) + b \quad (29)$$

where α_i and α_i^* are Lagrange coefficients. According to (29), new predictions are made using new training data [115].

7) PARTIAL LEAST SQUARES REGRESSION (PLSR)

PLSR is known as data-driven modeling and multivariate regression. This method is able to create a linear regression model and analyze a wide range of data via transmitting the input variables (input matrix X) and output variables (output matrix Y) to a new space. PLSR basically uses the covariance between the input and output variables instead of analyzing the hyperplanes with the least variance between the dependent and independent variables [117], [118]. This method interrelates input and output variables in a database using a linear multivariate model. The analysis of X and Y for m number of pulse components is as follows [117], [119]:

$$X = \sum_{h=1}^m t_h p_h^T + E = TP^T + E \quad (30)$$

$$Y = \sum_{h=1}^m u_h q_h^T + F = UQ^T + F \quad (31)$$

where X shows $n \times K$ matrix while K stands for the number of input variables, Y depicts $n \times M$ matrix while M represents the number of output variables, n displays the number of observations, E shows the input residual, while p is the input loading vector, and F depicts the output residual, while q is

the output loading vector [117]. PLS is comprised of inner and outer parts [120]; in the inner part, the relationship between the X and Y matrices is established indirectly through their scores via the internal model which is a function of (t) on (u) . In the outer part, T and P are the score and loading matrices for the X data set, U and Q are the score and loading matrices for the Y data set.

8) GROUP SUPPORT VECTOR REGRESSION (GSVR)

GSVM is a hybrid model of GMDH and SVR. The input data of the proposed hybrid model are selected based on the decision made by GMDH and utilized as the input data of SVR to forecast the output [56, 100]. In each layer of GSVR, all combinations of the two input variables (X_i, X_j) are generated, for each of which the regression is constructed through forming the polynomial function which approximates the output y in Eq. (19). The GMDH output data, which generates the least error, is used together with the input variables as the SVR inputs. In order for the output data to have the least error, the GSVR model must have 3-5 iterations [56, 101]. Finally, the GSVR model with the least error is chosen as the output model. The GSVR structure is shown in Fig. 7 [121].

B. EVALUATION OF MODEL PERFORMANCE

Different methods can be used to ensure the accuracy of results and their evaluation. The correlation coefficient of determination (R), mean absolute error (MAE), mean squared error (MSE), and root mean squared error (RMSE) are statistical performance metrics used in this paper to assess the performance of the proposed methods [123], [124].

Each of the indicators has various emphases. R indicates the correlation coefficient between the forecasted value and the actual value of the designed model. MAE shows the mean distance between the forecasted value and the actual value. MSE is the mean of the squares of the errors, meaning the mean squared difference between the forecasted values and the actual value of the designed model. RMSE is utilized to

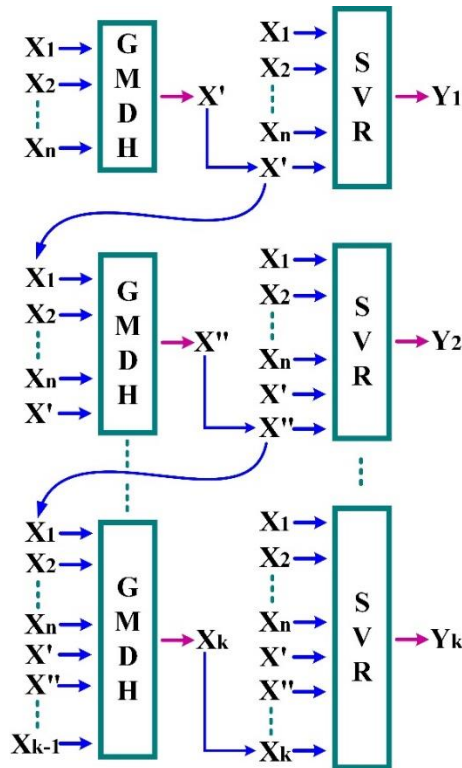


Figure 7. The principle structure of GSVR

recognize great errors and assessment of the variation in method response regarding variance and. The larger the value for R indicator is, and the smaller the values of MAE, MSE, and RMSE are, the better the model performance will be. The above-mentioned statistical performance metrics for N number of inputs were calculated using the following formulas [32], [123]:

$$R = \frac{\sum_{i=1}^N (X_i - \bar{X})(Y_i - \bar{Y})}{\sqrt{\sum_{i=1}^N (X_i - \bar{X})^2 \sum_{i=1}^N (Y_i - \bar{Y})^2}} \quad (32)$$

$$MAE = \frac{1}{N} \sum_{i=1}^N |X_i - Y_i| \quad (33)$$

$$MSE = \frac{1}{N} \sum_{i=1}^N (X_i - Y_i)^2 \quad (34)$$

$$RMSE = \sqrt{\frac{1}{N} \sum_{i=1}^N (X_i - Y_i)^2} \quad (35)$$

where X_i , \bar{X} , Y_i , and \bar{Y} represent the actual value, mean of actual values, estimated value, and mean of actual values, respectively.

IV. SIMULATION RESULTS

The proposed methods in this paper require initial design, structure formation, and selection of the number of neurons and the related coefficients in the hidden layers and structures. After the design, any neural network or machine learning application requires a dataset as input to enter the training phase. In the operational data of this study, as described in the relevant section, there exist two outputs (CL and HL) for each sample. Therefore, each network must be trained twice to perform forecasts, one for CL forecasting and the other for HL forecasting. Out of the total available datasets of 768 samples, 90% (688 samples) are selected for initial training and testing of each network; moreover, the remaining 10% (80 samples) are kept as unknown data to test the trained networks and forecast the required energy of buildings. For each network in each case of CL and HL, 70% and 30% of the intended dataset are considered as training and testing data, respectively. The neural networks and machine learning algorithms to forecast CL and HL models were applied in the MATLAB environment (Ver. 2018b).

The proposed networks were trained with relevant data and the results of each are described below. Figure 8 demonstrates an acceptable correlation and excellent overlap between the target data and the output of the designed GSVR for CL and HL training data. After training the network via CL and HL training data, the CL and HL were predicted as the testing data (Fig. 9). Figs. 10 and 11 depict the GSVR testing error for CL and HL prediction in the forms of MSE, RMSE, and histogram.

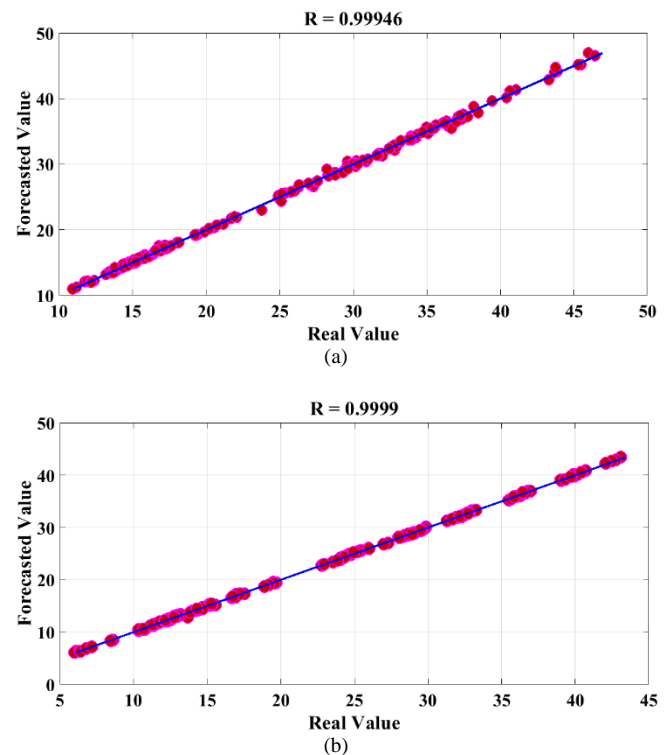


Figure 8. Fit regression between input variables and outputs: (a) for CL; (b) for HL

The regression and types of errors were shown only for the GSVR network. These results are expressed numerically for the rest of the methods in the following tables. Tables 6 and 7 show the CL and HL prediction results for training and testing data, respectively.

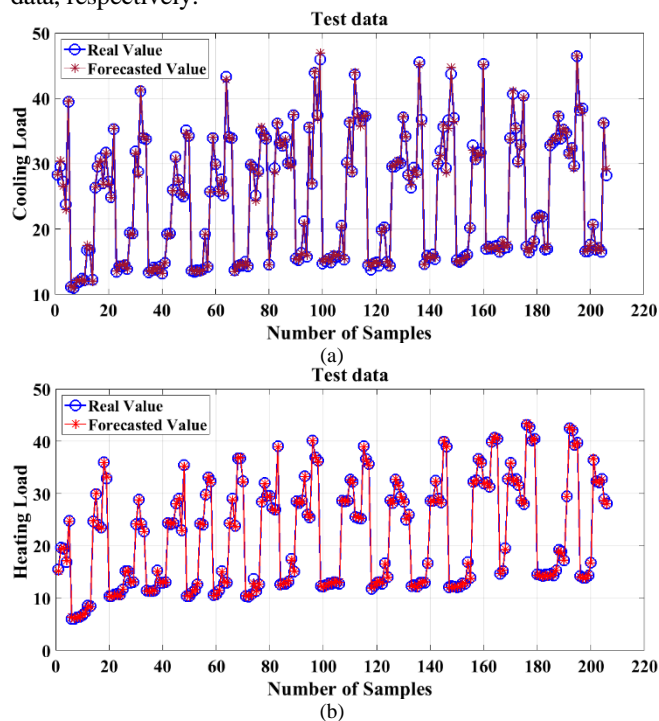


Figure 9. Prediction of CL and HL for testing data via GSVR: (a) for CL; (b) for HL

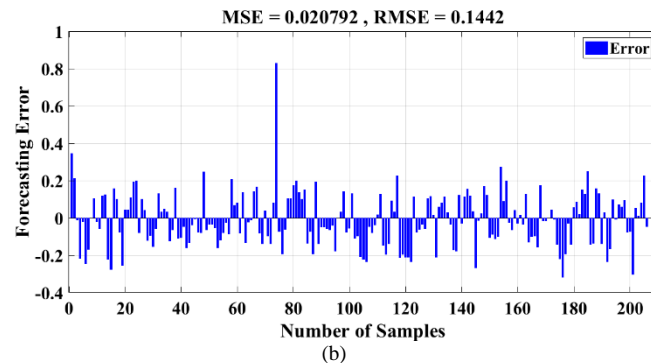
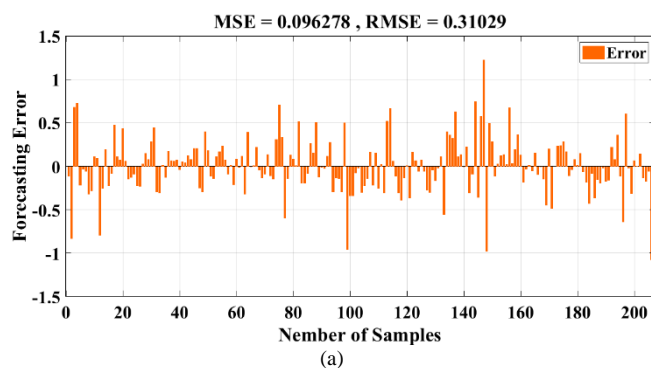


Figure 10. Testing error for CL and HL prediction in the form of MSE and RMSE; (a) for CL; (b) for HL

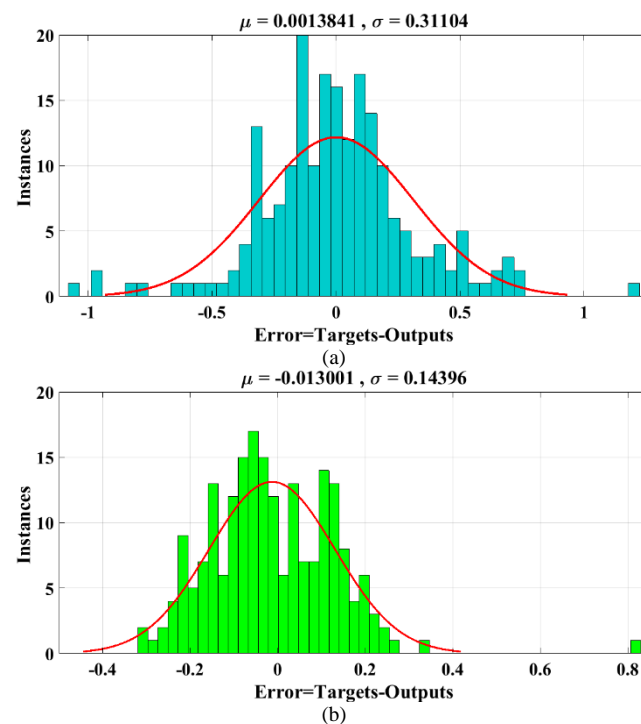


Figure 11. Testing error for CL and HL prediction in the form of histogram; (a) for CL; (b) for HL

TABLE 6. Results of accuracy and error for CL prediction via all proposed methods

Methods	Train				Test			
	R	MSE	RMSE	MAE	R	MSE	RMSE	MAE
BPNN	0.9977	0.4679	0.6840	0.5808	0.9899	1.9802	1.4071	0.8448
GRNN	0.9987	0.1458	0.3818	0.2634	0.998	0.3831	0.6189	0.4810
kNN	0.9795	3.0158	1.7366	1.2471	0.9708	3.6891	1.9207	1.5457
GMDH	0.9991	0.0701	0.2647	0.1647	0.9988	0.2104	0.4586	0.3154
ENR	0.9808	2.4857	1.5734	1.1258	0.9741	3.2584	1.8051	1.3064
SVR	0.9877	1.638	1.2798	0.6409	0.9874	2.1897	1.4798	0.8809
PLSR	0.9854	1.985	1.4089	0.9185	0.9792	3.0189	1.7374	1.2651
GSVR	0.9994	0.0428	0.2069	0.1349	0.999	0.0962	0.3102	0.2260

TABLE 7. Results of accuracy and error for HL prediction via all proposed methods

Methods	Train				Test			
	R	MSE	RMSE	MAE	R	MSE	RMSE	MAE
BPNN	0.9996	0.0682	0.2611	0.1346	0.9990	0.1706	0.4130	0.2305
GRNN	0.9997	0.0589	0.2426	0.1371	0.9991	0.1672	0.4089	0.2193
kNN	0.9887	0.9485	0.9739	0.6154	0.9871	1.3785	1.174	0.7362
GMDH	0.9997	0.0562	0.237	0.1362	0.9991	0.1528	0.3908	0.209
ENR	0.9814	2.3646	1.5377	1.0028	0.9801	2.4504	1.5653	1.1183
SVR	0.9985	0.17782	0.42169	0.28775	0.9980	0.27164	0.52119	0.3803
PLSR	0.9938	0.5015	0.7081	0.4125	0.9896	0.8458	0.9196	0.5476
GSVR	0.9999	0.01663	0.12899	0.10134	0.9993	0.02079	0.1442	0.11465

The above tables present the results of accuracy coefficients and error of training and testing for each of the networks. The results showed that the proposed methods were capable of predicting the test data after training. Studies of data mining applications showed that training and prediction operations were highly dependent on the type of data in regard to a variety of neural networks and machine learning algorithms. After training, all of the above networks were saved in the form of black box and utilized as a toolbox. This toolbox contained the features and detected patterns extracted from data or input variables. The CL and HL for new and unknown data were extracted using these black boxes. To do this, 10% (80 samples) of the main database (kept as new and unknown data) were utilized as inputs for each trained and saved network. Fig. 12 shows that each of the input variables (building characteristics) and output variables (CL and HL) were used as new and unknown data.

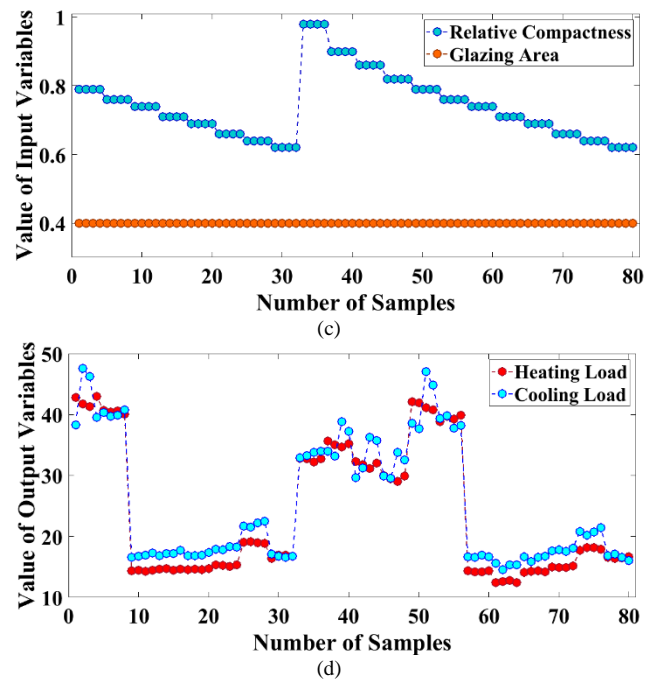
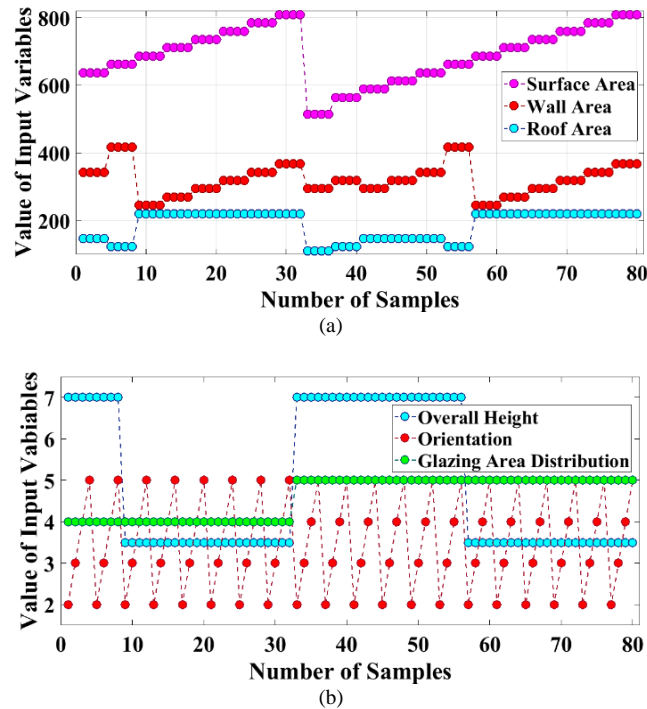


Figure 12. The characteristics and the energy load data of buildings: (a) Surface area, wall area, and roof area; (b) Overall height, orientation, and glazing area distribution; (c) Relative compactness and glazing area; (d) HL and CL

The key step in performing operations such as load forecasting and home energy forecasting is to perform forecasting operations for new and unknown data based on prior training. The CL and HL of residential buildings were predicted through the networks saved for the new data (Fig. 13).

Based on the results of Fig. 13, it can be deduced that each of the proposed methods was able to forecast the CL and HL for the new data based on the recognized patterns of the input variables via the training operation. The forecasted results were very close to the actual values, indicating that the proposed methods can be used as powerful tools for managing and saving the energy of residential and office buildings. Table 8 presents the precision and error rates for each of the proposed methods. The results of the proposed solutions are compared in the next section.

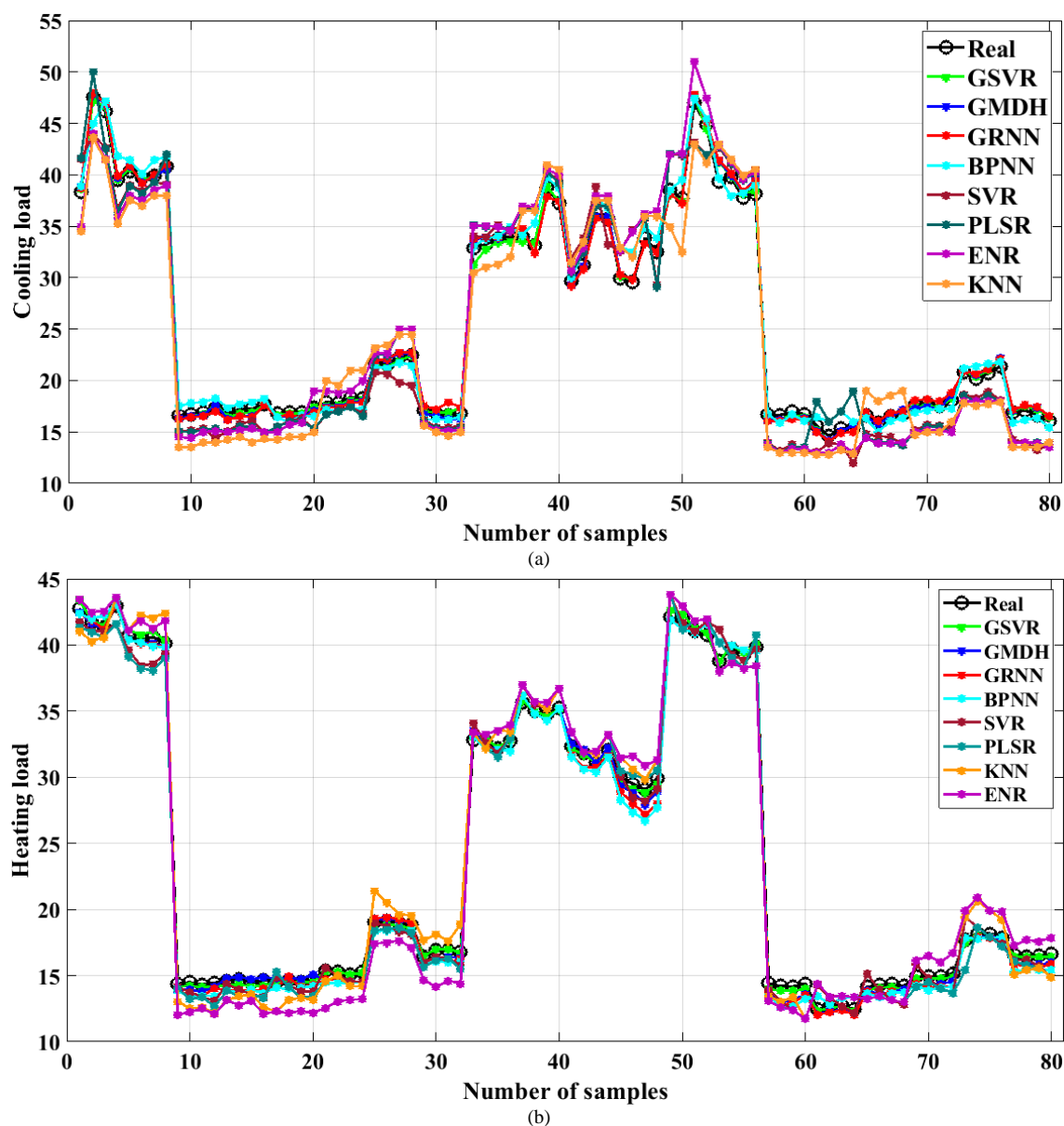


Figure 13. Forecasting the CL and HL of residential buildings for new data: (a) CL forecasting; (b) HL forecasting

Table 8. Various errors in forecasting CL and HL

Methods	HL				CL			
	R	MSE	RMSE	MAE	R	MSE	RMSE	MAE
BPNN	0.9983	0.7544	0.8685	0.7304	0.9958	1.1175	1.0571	0.8671
GRNN	0.9989	0.488	0.6985	0.5827	0.9986	0.3330	0.5770	0.4961
kNN	0.9933	1.8311	1.3531	1.244	0.9704	8.0046	2.8292	2.72
GMDH	0.9992	0.2709	0.5204	0.435	0.9989	0.2678	0.5174	0.4305
ENR	0.9924	2.6267	1.6207	1.4933	0.9815	6.4678	2.5431	2.3666
SVR	0.9965	0.9837	0.9918	0.8064	0.9843	5.6663	2.3803	2.1621
PLSR	0.9961	1.2018	1.0432	0.9717	0.982	5.6418	2.3752	2.1731
GSVR	0.9999	0.063	0.2509	0.2078	0.9992	0.1783	0.4222	0.313

V. ANALYSIS AND COMPARISON OF RESULTS

The effectiveness of each method was determined by comparing the results with other similar solutions. The parameters R, MSE, RMSE, MAE obtained from the results of the proposed methods were compared with each other and with the results obtained in other papers. All of the comparison methods were implemented in the same dataset. The division of the database for training, testing, and validation operations was different among these studies, hence the fact that the direct comparison should be drawn with caution. Table 5 summarizes the results obtained after testing the saved networks with the new data. As seen, the GSVR model with the best R value obtained for HL on new test data (0.9999) was in the range of best forecasting models. For HL prediction, GSVR had minimal errors in terms of MSE (0.0630), MAE (0.2078), and RMSE (0.2509). ENR with the lowest R value (0.9924) had the maximal errors in the form of MSE (2.6267), MAE (1.4933), and RMSE (1.6207). After the GSVR model, the GMDH and GRNN models were the most suitable methods for forecasting the HL with the R values of 0.9992 and 0.9989, respectively. Regarding CL prediction, GSVR had the most optimal R value (0.9992), and the minimal errors in terms of MSE (0.1783), MAE (0.3130), and RMSE (0.4222). In this forecasting, after GVR, GMDH and GRNN were the most appropriate models with R values of 0.9989 and 0.9986, respectively. However, the kNN method with the lowest R value (0.9704) and the highest error values in the forms of MSE (8.0046), MAE (2.7200), and RMSE (2.8292) provided the weakest forecast for CL. By comparing the results presented in Table 5 with the information presented in Table 1, the energy prediction results associated with buildings using the proposed methods can be compared with other models used in other studies for similar data.

VI. CONCLUSION

The importance of forecasting the energy consumption of buildings, especially CL and HL in order to estimate, manage, and save energy, has raised many challenges. Today, most researchers are looking for an improved model with high predictive performance. This paper introduced a variety of energy forecasting models for residential and non-residential buildings and assessed the performance of each. Through the use of hybrid models, this paper proposed a new (hybrid) model of machine learning application called GSVR to forecast the CL and HL of a residential building. The principle goal of the proposed model was to combine the GMDH and SVR models. In addition to the proposed model, several other models of neural network and regression applications, including BPNN, ENR, GRNN, kNN, PLSR, GMDH, and SVR were used in this paper to forecast CL and HL. Eight technical parameters of the building (X1, X2, ..., X8) were employed as input variables, and CL and HL were selected as the output variables of the proposed models. After training and saving the trained networks, the CL and HL were forecasted using new data. The presented results indicated that the

suggested hybrid model was the best model for predicting building energy as it had the highest R value (0.9999) and the lowest error values in the forms of MSE (0.063), RMSE (0.2509), and MAE (0.2078) for forecasting HL and the most optimal R value (0.9992) and minimal errors in terms of MSE (0.1783), RMSE (0.4222), and MAE (0.313) in forecasting CL. Noteworthy, the proposed method is also applicable to real-world data as well as all available energies, such as water and gas.

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