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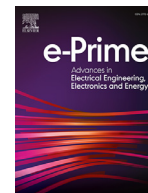
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# Energy efficiency enhancement in full-bridge PV inverters with advanced modulations

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## ABSTRACT

Transformerless single-phase inverters are preferring in residential grid-connected PV systems when compared to galvanic-isolated ones (i.e., transformer-based inverters). In addition to the special leakage current issue, high efficiency, power quality and reactive power injection are of concern that should be considered in grid-connected applications. Nowadays, the fast development of wide-bandgap (WBG) devices brings new challenges to transformerless inverters, e.g., electromagnetic interference (EMI) issues, but efficiency can be improved. This paper first reviews the full-bridge PV inverters seen from the perspective of topology configuration. The oscillation during switching transitions is analyzed and compared in typical full-bridge inverters under a hybrid modulation method, which has a significant relationship with the EMI issue. Then, power loss distribution is discussed to reveal the thermal performance under the hybrid modulation scheme with reactive power injection. Simulations are carried out on the full-bridge prototype to validate the discussions of the hybrid modulation strategy.

## 1. Introduction

As one of the important renewable energy resources, photovoltaic (PV) energy has continued being installed across the globe with an increase of 127 GW in 2020 [1]. Correspondingly, it promotes a relatively fast development of PV panels, power electronics (i.e., including semiconductor devices, topologies and control strategies) as well as the grid-connected standard [2]. To catch up with the large-scale integration of PV energy, PV inverters play an essential role in converting and delivering solar energy to the grid and users. According to the power levels, PV inverters can be classified into three types, including module-level micro-inverters (e.g., residential PV systems) [3], string inverters for medium and high power applications (e.g., offices or industrial PV power systems) [4], and utility-scale central inverters (e.g., PV plants) [5,6]. PV plants require a large area for installation, while low- and medium-power PV systems are preferring and can be built on the rooftops or walls [7]. Referring to single-phase PV inverters in those occasions, the performances in terms of efficiency, power density and system costs as well as intelligence are of concern.

In addition to the inherent intermittency, another unique issue of grid-connected PV systems is the leakage current due to the parasitic capacitor between the PV panels and the ground [8]. Many standards for grid-connected PV systems have strict requirements on the leakage current level, such as the VDE 0126-1-1 and VDE-AR-N4105 from Germany and IEEE Std. 1547-2018 [9-11]. To achieve effective galvanic isolation and then low leakage current, the traditional way is adding a physical device in the single-phase PV inverter, i.e., a high-frequency (HF) transformer on the DC side or a line-frequency transformer (LFT) on the AC

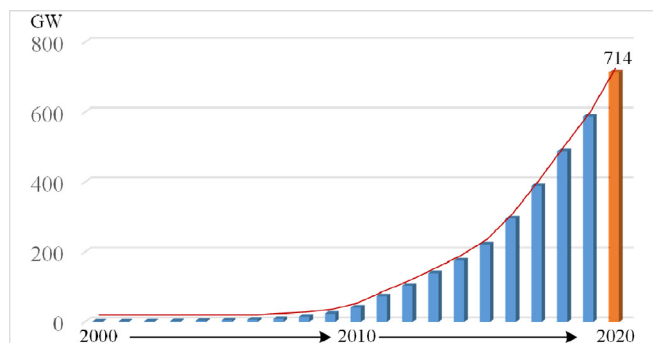


Fig. 1. Solar accumulative capacity from 2000 to 2020 based on the data available from IRENA [1], which includes photovoltaics and solar thermal.

side, as shown in Fig. 2. Those transformer-based inverters are contrary to the requirements of small size and low cost. Besides, the demand for high power density is also the reason, why voltage source inverters are more popular than current source inverters [12]. Another way to mitigate this issue is by configuring transformerless single-phase topologies, as shown in Fig. 2(b). The main idea is to clamp the common-mode voltage (CMV) at a constant value through adopting modulation methods or auxiliary circuits [13,14]. Referring to the modulation method, the typical one is the full-bridge single-phase inverter with the bipolar pulse width modulation (BPWM) scheme. With two-voltage levels generation, the switching losses are high, leading to low power density with

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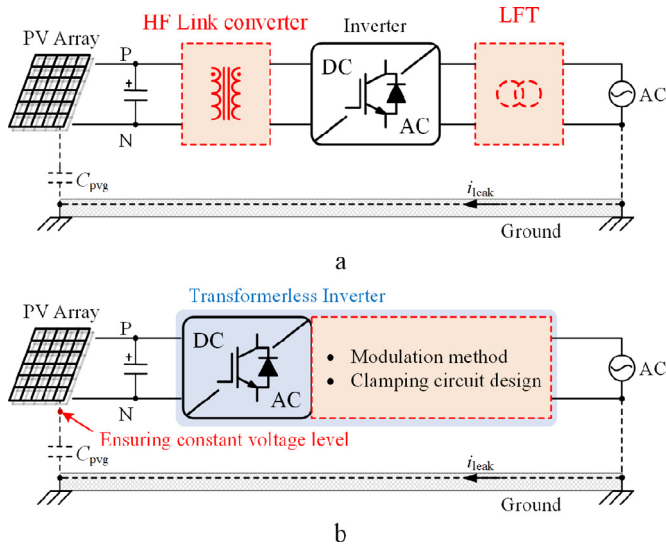


Fig. 2. Inverter structure schematic, where  $C_{pvg}$  is the parasitic capacitor between the PV panels and the ground, and  $i_{leak}$  is the leakage current.

a Transformer-based topologies

b Transformerless inverters.

a large size heat sink [15]. As for new topologies, many review papers have explored various transformerless single-phase inverters from the perspective of leakage current suppression [4,13,14,16,17].

Seen from the CMV clamping perspective, transformerless single-phase PV inverters can be classified into two types. One is the common-ground type, and another is the full-bridge type with constant CMV clamping capability. The common-ground configuration is presented in Fig. 3, where the PV panels are connected directly to the grid with the common negative terminal, i.e., the ground. The common-ground transformerless inverters can be separated into two types. That is, the PV voltage  $V_{PV}$  is two times the DC-link voltage ( $2V_{DC}$ ) and  $V_{PV}$  is equal to  $V_{DC}$  [18]. The representative transformerless inverters with  $V_{PV} = 2V_{DC}$  are half-bridge inverters, such as the conventional half-bridge inverter [19,20], the multilevel transformerless half-bridge inverter (e.g., T-type, neutral point clamping (NPC) and active neutral-point clamping (ANPC) topologies) [21,22], Karschny inverter [23], and the dual-buck half-bridge inverter in series [24]. While the other ( $V_{PV} = V_{DC}$ ) adopts extra active circuits to meet the voltage modulation requirement, such as virtual DC bus concept inverters [25] and the full-bridge dual-buck inverter [26]. The CMV is effectively clamped by the common-ground configuration of those transformerless inverters. However, the former type requires a high input voltage of the PV panels, and the latter type needs extra active switches as well as passive devices (e.g., capacitors providing virtual DC bus and inductors with low utilization in dual-buck half-bridge inverters). Thus, transformerless single-phase inverters based on symmetrical AC filter inductors with the full-bridge configuration are preferring in terms of high efficiency and high power density. The full-bridge inverters include DC-decoupling transformerless inverters [27–29], AC-decoupling transformerless inverters [31–35], and NPC transformerless inverters [37–46], as shown in Figs. 3(b)–(d), respectively.

Apart from leakage current issues and power density, reactive power injection has also been required in grid-connected PV systems. For instance, in the IEEE Std. 1547–2018, the minimum reactive power injection and absorption in distributed energy systems should be 44% and 25% of the rated apparent power, respectively [11]. Therefore, many modulation schemes have been proposed to enhance the reactive power capability of transformerless inverters, such as the combined modulation method [15]. Considering the performance of conversion efficiency and power quality, the bidirectional-path unipolar pulse width modula-

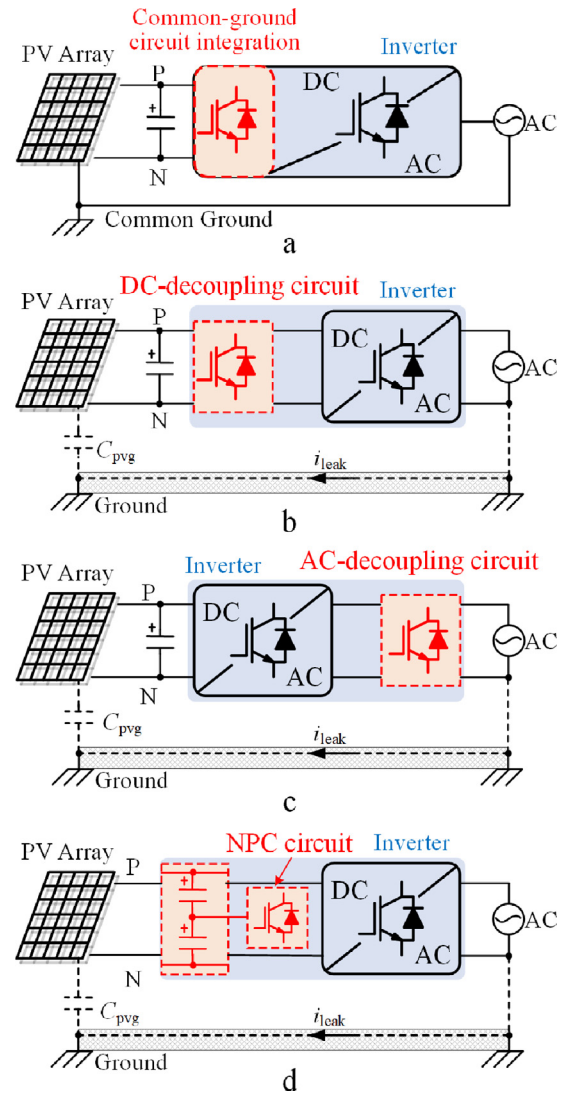


Fig. 3. Single-phase transformerless PV inverter configurations

a Common-ground type

b DC-decoupling type

c AC-decoupling type

d NPC circuit type.

tion method [47,48], and hybrid modulation techniques [49,50] have also been explored for applications in the above transformerless single-phase inverters.

However, there are very few review papers comparing the commutation oscillation performance induced by parasitic parameters, and loss distribution under the advanced hybrid modulation method. With the fast development of wide-bandgap (WBG) devices, e.g., silicon carbide (SiC) and gallium-nitride (GaN) power devices, the challenge of electromagnetic interference (EMI) issues (i.e., due to the parasitic oscillation) increase with their advanced switching performance (i.e., high switching speed) [51,52]. Another important aspect for PV inverters is the reliability-related system cost, where losses unbalance issues of the power devices play an important role. Consequently, this paper reviews the full-bridge PV inverters under the prior-art hybrid modulation schemes with reactive power injection from the two issues in Sections 2 and 3. In Section 4, an instructive discussion is presented for the design of residential transformerless PV inverters. Section 5 demonstrates the hybrid modulation method on the full-bridge inverter, which validates the discussions of the loss distribution. Finally, the conclusion is given in Section 6.

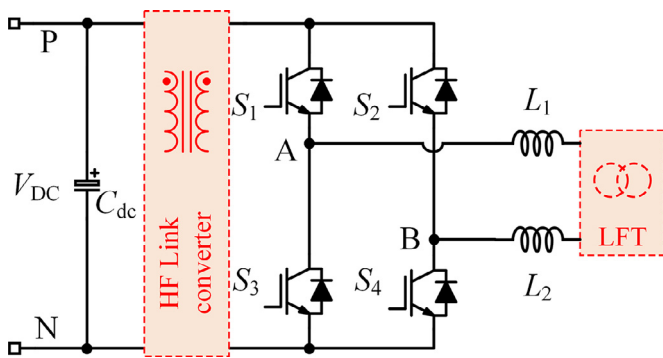


Fig. 4. Full-bridge inverter.

## 2. Review of full-bridge PV inverters

As mentioned previously, full-bridge single-phase PV inverters have better performance of power density due to their split symmetrical AC inductors structure. The full-bridge PV inverters discussed in this paper can be separated into four groups.

- 1) **Transformer-based type:** Transformer-based single-phase inverters always have two configurations, including the one with a DC-DC converter of a high-frequency transformer and the one with a low-frequency transformer, as shown in Fig. 2(a). Both have a full-bridge inverter with four semiconductor devices (e.g., IGBTs and MOSFETs), as shown as  $S_{1-4}$  in Fig. 4. Besides, the symmetrical AC filter inductors are  $L_1$  and  $L_2$ , which are the same in all the following figures. With the transformer, a unipolar pulse width modulation (UPWM) scheme can be adopted in the full-bridge inverter to achieve galvanic isolation, small AC filter inductors, and reactive power injection. Otherwise, the full-bridge inverter must adopt the BPWM to ensure a constant CMV.
- 2) **DC-decoupling type:** As shown in Fig. 3(b), the DC-decoupling transformerless single-phase inverters employ an extra circuit at the DC bus, which can decouple the PV panels and the AC side during the freewheeling period (i.e., zero output voltage). The well-known DC-decoupling transformerless inverter is the H5 inverter [27]. As shown in Fig. 5(a), an active blocking switch can be inserted at the positive/negative rail of the DC bus. However, the blocking switch  $S_5$  has two times more switching losses than others. Thus, the H6 DC-decoupling transformerless inverter adopts two blocking switches to share the switching losses, as shown in Fig. 5(b). The symmetrical blocking switches  $S_5$  and  $S_6$  can share the switching losses, yet increase the conduction losses since the current needs flow through four switches in the conduction period [28]. To improve this issue, advanced H6 transformerless DC-decoupling inverters adopt a bypass switch on the H5 topology [29,30]. As presented in Fig. 5(c), the bypass switch  $S_6$  can be connected to terminals A, B, or C. That is the so-called redundant design to share the switching losses by extra switches.
- 3) **AC-decoupling type:** The AC-decoupling transformerless inverters add the decoupling circuit at the AC side port, as presented in Fig. 3(c). In [31], the derivation method of H6 AC-decoupling type inverters was presented, where the main structure is embedding an AC-decoupling circuit in the mid-point of the full-bridge cell for bidirectional freewheeling paths. For instance, Fig. 6(a) shows symmetrical H6 transformerless inverters [32,33], which have different structures, but similar modulation and CMV performances. Furthermore, a hybrid-bridge H6 inverter (see Fig. 6(b)) can be derived accordingly [34], where the AC-decoupling circuit only inserts in one leg of the full-bridge inverter. To realize bidirectional freewheeling by two active switches, a mid-switch H6-type inverter was proposed in [35], as depicted in Fig. 6(c). It can be seen from Figs. 6(a)-(c) that

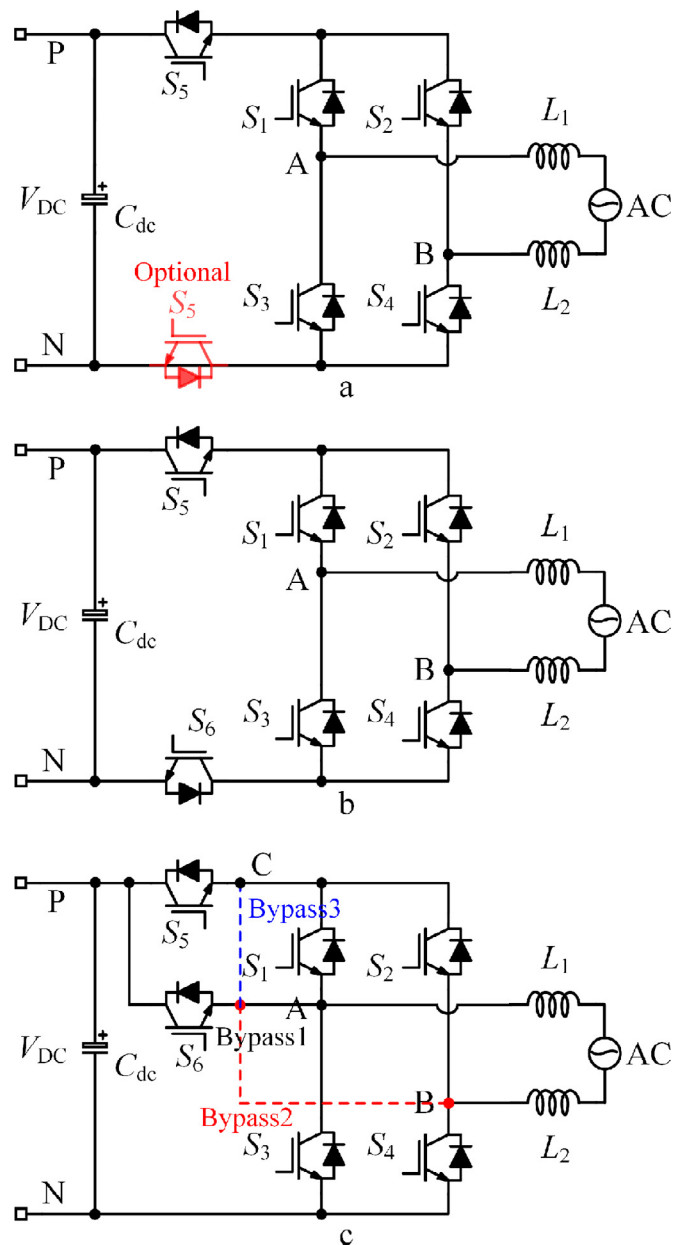


Fig. 5. DC-decoupling inverters

a H5 topology [27]

b H6-DC-decoupling topology [28]

c H6-bypass topologies [29,30], where there are three bypass ways, i.e., the bypass1 is setting  $S_6$  between terminals P and A, the bypass2 is placing  $S_6$  between terminals P and B, and the bypass3 is locating  $S_6$  between terminals P and C.

when the AC-decoupling circuit is inserted in the branches of the full-bridge inverter, the conduction losses are relatively increased. To alleviate this issue, the highly efficient and reliable inverter concept (HERIC) adopts two active switches as the AC-decoupling circuit [36], as presented in Fig. 6(d). As for the HERIC topology, the AC-decoupling circuit has various configurations, such as two active switches with two diodes, two active switches, and one active switch with a rectifier bridge [4]. By comparison, the HERIC inverter with two anti-series-connected active switches has good performance in terms of fewer power devices and higher efficiency.

- 4) **Neutral Point Clamping (NPC) type:** Being different from the physical switch (e.g., relay), the semiconductor devices exist switch junction capacitors, which have an unexpected impact on the leakage

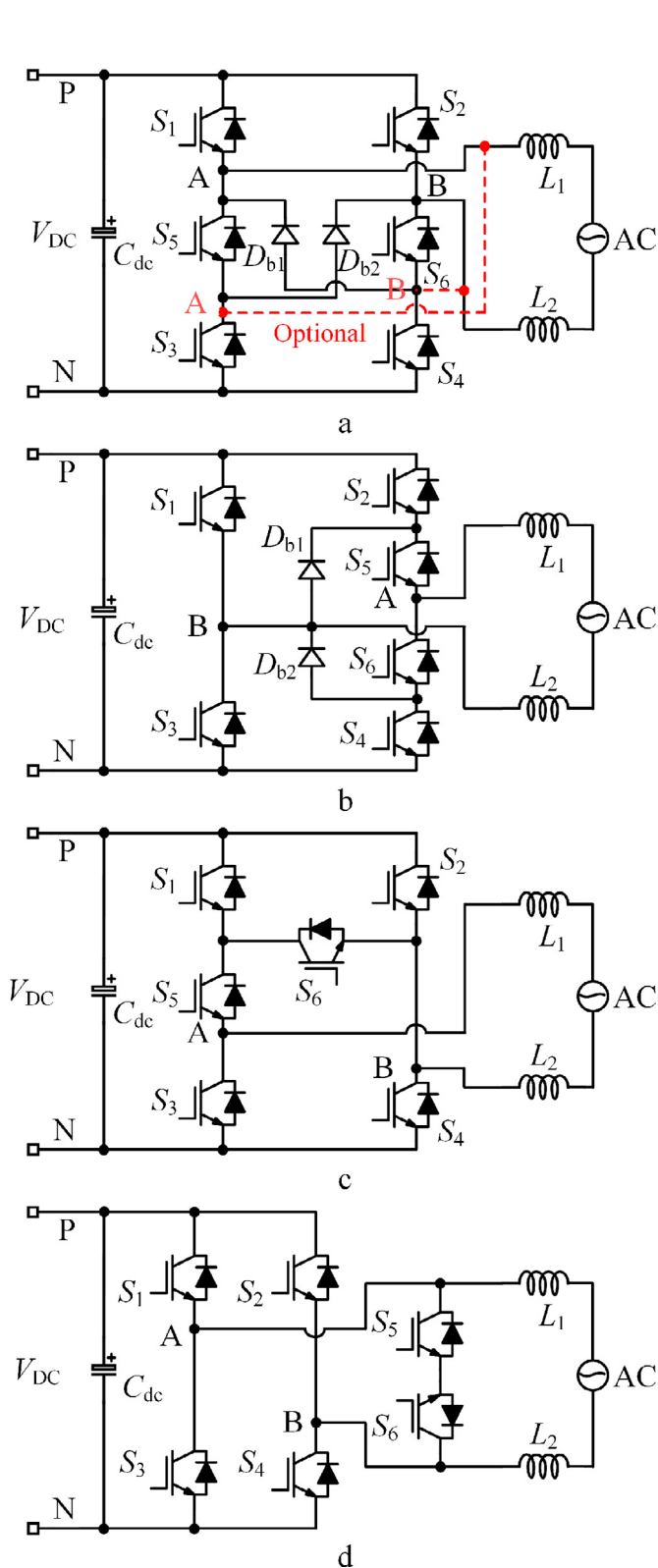


Fig. 6. AC-decoupling inverters

a H6-AC-decoupling topologies [32,33], where the circuit branches can also be embedded as indicated by the red line.

b Hybrid-bridge H6 topology [34]

c Mid-switch H6 topology [35]

d HERIC topology [36].

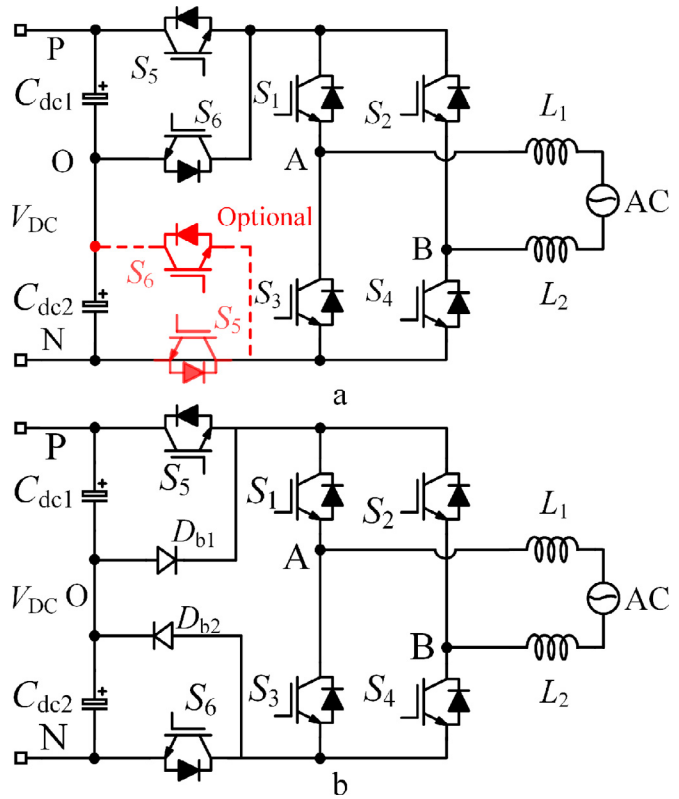


Fig. 7. DC-decoupling NPC inverters

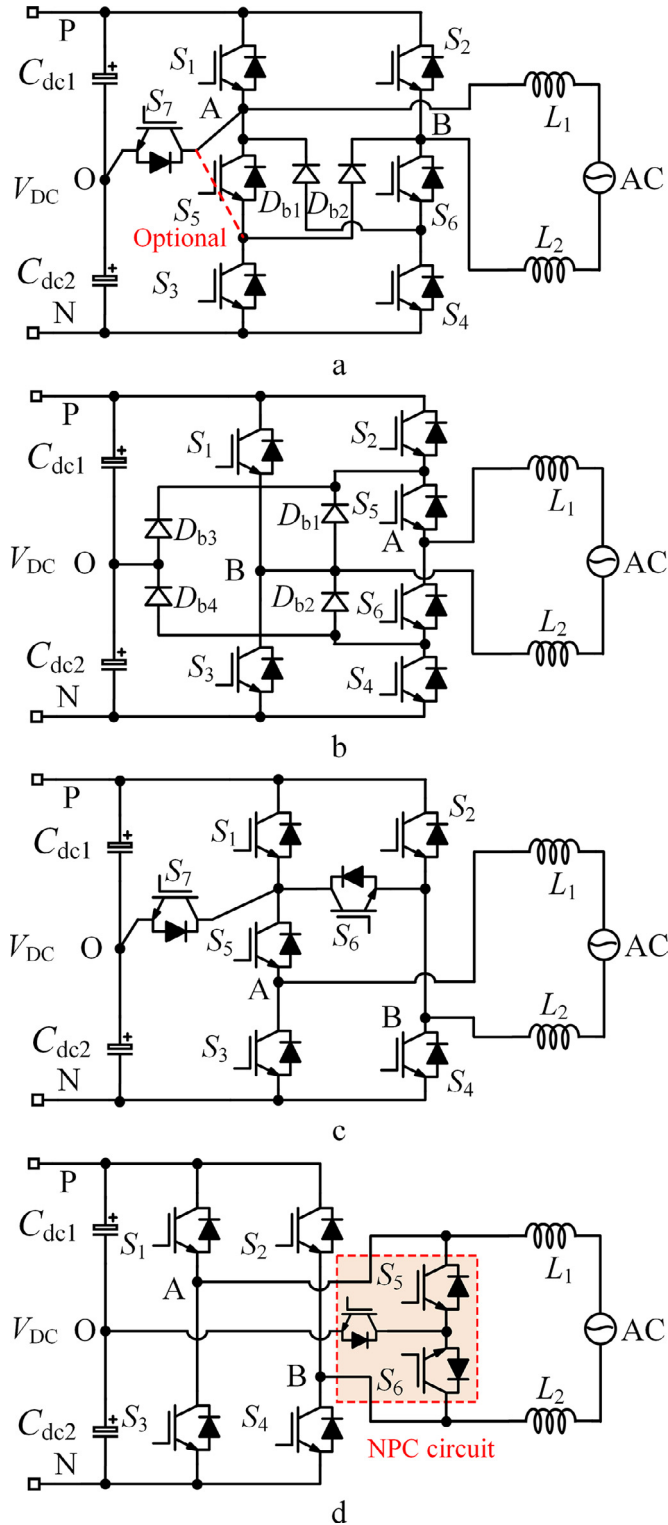
a O-H5 topology [41], where  $S_5$  and  $S_6$  can be set at both the positive/negative DC-links

b H6-DC-decoupling NPC topology [43].

current performance [4,8]. For instance, [4] and [42] analyzed the inherent leakage current caused by the junction capacitors in the H5 inverter. The asymmetrical structure of the H5 topology cannot maintain a constant CMV, especially in high-power inverters with high-speed switching devices. Therefore, the NPC type inverters have been proposed to achieve a constant CMV by the capacitor clamping circuit, as shown in Fig. 3(d) [37–40]. The methodology of NPC topologies is to clamp the CMV to be half of the DC-link voltage during the freewheeling period, which can be easily built based on the DC/AC-decoupling inverters. Fig. 7 exhibits the DC-decoupling NPC transformerless topologies. The O-H5 topology has two structures, where  $S_5$  and  $S_6$  can be inserted in both the positive and negative rails, as shown in Fig. 7(a) [41]. In [42], an H5-D topology was proposed, which only uses a diode to provide NPC function, and  $S_5$  is on the negative DC rail. The CMV clamping performance is worse than that for the O-H5 topologies (i.e., with active clamping). In addition, a diode bidirectional NPC circuit was adopted in the H6-DC-decoupling inverter, as depicted in Fig. 7(b) [43].

As for AC-decoupling NPC inverters, four typical topologies are exemplified in Fig. 8. Fig. 8(a) shows the H6-AC-decoupling NPC inverters, where an active switch connects the AC-decoupling circuit to the neutral point of the series capacitors. The diode bidirectional NPC circuit was added in the hybrid-bridge H6 inverter in [38], as shown in Fig. 8(b). Besides, the mid-switch H6 NPC topology was introduced, as shown in Fig. 8(c), which has relatively high efficiency. Based on the HERIC inverter, many NPC single-phase transformerless inverters have been proposed, such as the active voltage clamping HERIC (AVC-HERIC) topology (i.e., in Fig. 8(d)) [44], H-bridge zero-voltage state (HB-ZVR) topology [45], and full-bridge constant common-mode voltage (FB-CCV) [46].





**Fig. 8.** AC-decoupling NPC inverters  
**a** H6-AC-decoupling NPC topologies, where the red line shows the optional connection  
**b** Hybrid-bridge NPC topology [38]  
**c** Mid-switch H6 NPC topology [38]  
**d** AVC-HERIC topology [44].

The above classification of PV inverters is based on the leakage current suppression schemes. In addition, many review papers have carried out various comparisons and analyses combined with the performance of efficiency and device count. It can be seen in [37,38] that the NPC topologies have the best CMV clamping characteristic, the HERIC inverter has the highest efficiency, and the H5 has the least device count. However, commutation oscillation and loss distribution issues, which have a close relationship with power density, are barely focused on. When the operation modes of inverters commute at a switching frequency, the parasitic inductor and capacitor in the current loop will generate high-frequency oscillation. The different parasitic parameters in different current loops lead to multi-frequency oscillation during the mode transitions (i.e., serious oscillation performance). In practice, many standards have strict EMI requirements (e.g., the Standard EN-61,800-3 has requirements for the main terminals disturbance voltage in the frequency band 150 kHz–30 MHz) [53,54], thus huge EMI filters should be added under the serious oscillation performance. On the other hand, the heat sink should be designed properly to cool down the hottest component [55,56]. Therefore, the loss balance of switches in a converter can benefit the heatsink design and improve the lifetime of the entire PV inverters. This paper will discuss the parasitic oscillation and loss distribution performance of several typical single-phase PV inverters under the hybrid UPWM method with reactive power injection [48].

### 3. Parasitic oscillation and loss analysis

To meet the requirement of reactive power regulation, high efficiency, and high power quality, [48] summarized the hybrid UPWM scheme for various single-phase grid-connected transformerless PV inverters. With this modulation method, the parasitic oscillation and loss distribution performances are different for the above transformerless single-phase inverters [57,58]. Since the NPC topologies are almost based on the DC/AC decoupling topologies, the full-bridge inverter, H5 topology, H6-DC-decoupling topology, one H6-AC-decoupling topology, the mid-switch H6 topology, and HERIC topology are chosen to analyze and compare in this paper. Since the parasitic oscillation and loss distribution are analyzed under the modulation method, the DC-link voltage  $V_{DC}$  is assumed to be constant. Besides, a simple PR current controller is adopted to generate the duty cycle ratio, which is used in the hybrid modulation method [59]. To better benchmark the parasitic oscillation, the analysis only considers the parasitic parameters of the semiconductor devices. That means the parasitic inductances on the printed circuit boards (PCB) layout are assumed to be the same among the selected topologies.

#### 3.1. Full-bridge inverter

Fig. 9 shows the full-bridge inverter with parasitic inductors, where  $L_{\sigma 1-4}$  represents the parasitic inductances of the switches  $S_{1-4}$  and  $L_{\sigma 1-4}$  are assumed to be identical. The hybrid UPWM scheme is presented in Fig. 10, where its loss distribution is also shown. When the reference voltage  $v_{ref} > 0$ ,  $S_1$  is ON,  $S_3$  is OFF, and  $S_2$  and  $S_4$  commute at the switching frequency. While  $v_{ref} < 0$ ,  $S_3$  is ON,  $S_1$  is OFF, and  $S_2$  and  $S_4$  switch at the same high frequency. Since  $S_1$  and  $S_3$  operate at the grid frequency (i.e., 50/60 Hz) and  $S_2$  and  $S_4$  work at the switching frequency (i.e., being above tens kHz), the switching losses are almost distributed on  $S_2$  and  $S_4$ , as the gray part in Fig. 10. As for conduction losses [60], the total losses on  $S_{1-4}$  are the same, yet being unbalanced and distributed on IGBTs and diodes under different power factor angles  $\varphi$ .

According to the hybrid modulation scheme, the loop commutations in the positive and negative half-cycles are almost the same. Taking the positive half cycle for example, Fig. 11 presents the equivalent circuit with parasitic inductances of the full-bridge inverter, which includes two commutation modes. The total loop inductance in '+  $V_{DC}$ ' mode and '0'

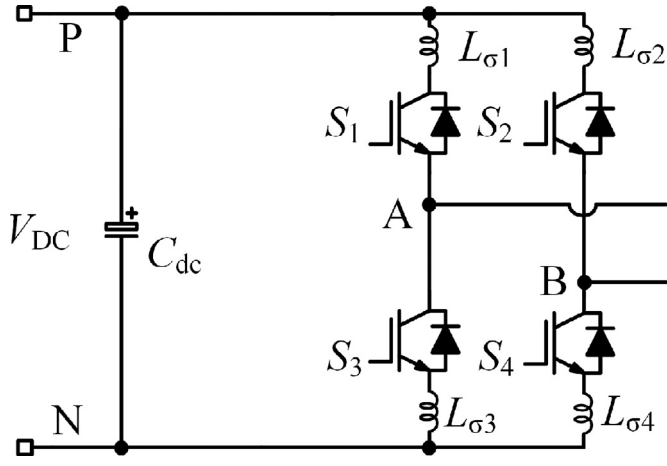


Fig. 9. Full-bridge inverter-equivalent circuit with parasitic inductances, where  $L_{\sigma 1-4}$  are the parasitic inductances of switches  $S_{1-4}$ .

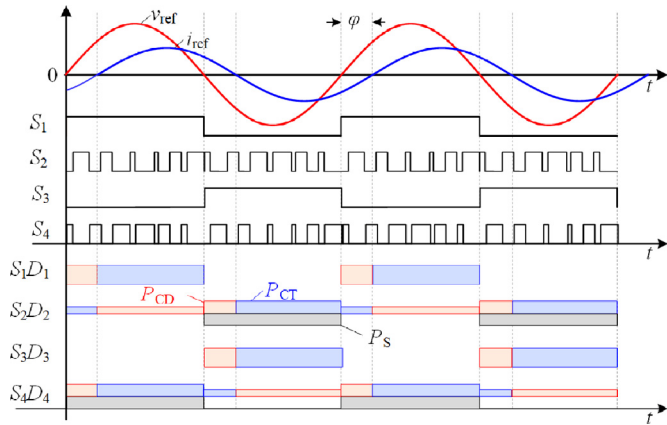


Fig. 10. Full-bridge inverter-hybrid modulation scheme and loss distribution, where  $P_{CD}$  and  $P_{CT}$  are the conduction losses of the anti-parallel diode and the IGBT, respectively, and  $P_S$  is the switching losses,  $v_{ref}$ ,  $i_{ref}$  are the reference voltage and current for modulation signals,  $\varphi$  is the power factor angle. When outputting positive power, the conduction losses are almost on IGBT, which the conduction losses are on diodes during negative power generating.

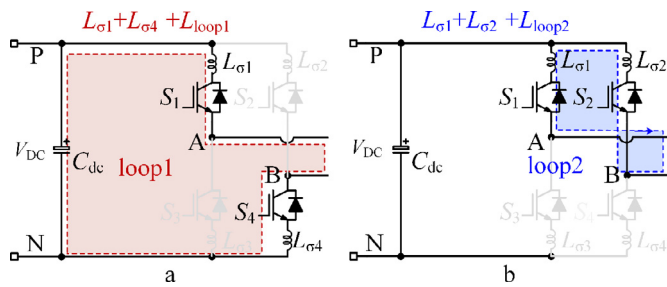


Fig. 11. Full-bridge inverter-operation commutation modes in the positive half-cycle, where  $L_{loop1}$  and  $L_{loop2}$  are the PCB routing inductances  
a '+  $V_{DC}$ ' mode  
b '0' mode.

mode can be given as

$$L_{+V_{DC\_FB}} = L_{\sigma 1} + L_{\sigma 4} + L_{loop1} \quad (1)$$

$$L_{0\_FB} = L_{\sigma 1} + L_{\sigma 2} + L_{loop2} \quad (2)$$

Along with the semiconductor device output capacitor, high-frequency oscillations will be generated. When the loop inductances are

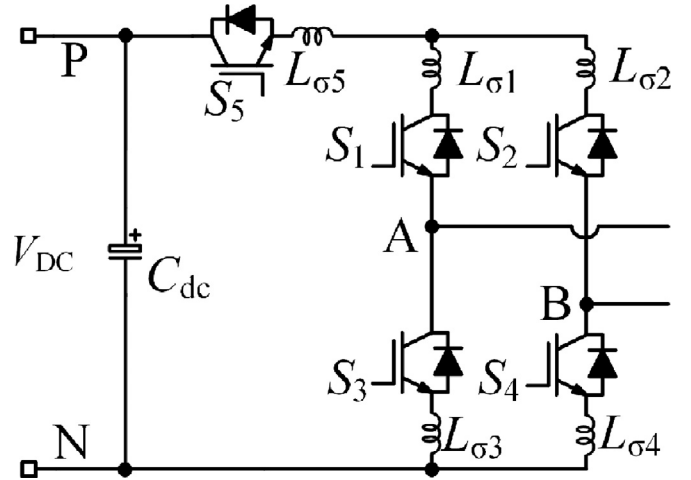


Fig. 12. H5 inverter-equivalent circuit with parasitic inductances, where  $L_{\sigma 1-5}$  are the parasitic inductances of switches  $S_{1-5}$ .

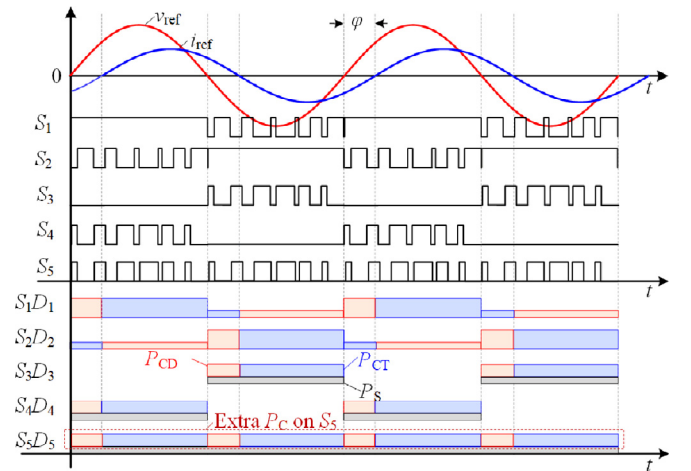


Fig. 13. H5 inverter-modulation scheme and loss distribution.

unbalanced in those two commutation modes, the oscillations have two frequencies. In that case, it will increase the design burden on the EMI filter [61]. It can be revealed from Eqs. (1) and (2) that the oscillation frequencies are almost the same in the full-bridge inverter under the hybrid modulation method if the PCB layout design can ensure the symmetry of the loop inductances, i.e.,  $L_{loop1} = L_{loop2}$ . It should be mentioned that although only  $S_1$  is ON in the deadtime during the mode transition, the current loop is the same as the '0' mode. Thus, the loop inductance of the deadtime period has not been further discussed.

### 3.2. H5 inverter topology

The equivalent circuit of the H5 topology with the parasitic inductances is shown in Fig. 12, which adopts an active switch  $S_5$  at the positive DC-link rail to disconnect the DC side and the AC side. The improved hybrid UPWM method with reactive power injection is shown in Fig. 13 [47]. At the positive half-cycle,  $S_1$  is ON, and  $S_2$  and  $S_{4,5}$  complementarily switch at a high frequency, generating a two-level voltage of +  $V_{DC}$  and 0. At the negative half-cycle,  $S_2$  is ON, and  $S_1$  and  $S_{3,5}$  commutate at the switching frequency, obtaining a two-level voltage of -  $V_{DC}$  and 0. Correspondingly, loss distribution is presented at the lower part of Fig. 13, where  $S_5$  has high conduction losses and switching losses due to its long operation time. From the thermal analysis,  $S_5$  is the most fragile component in the H5 inverter [62,63].



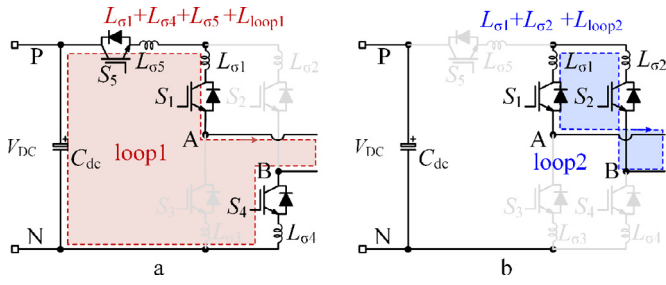


Fig. 14. H5 inverter-commutation modes in the positive half-cycle, where  $L_{loop1}$  and  $L_{loop2}$  are the PCB routing inductances  
a '+  $V_{DC}$ ' mode  
b '0' mode.

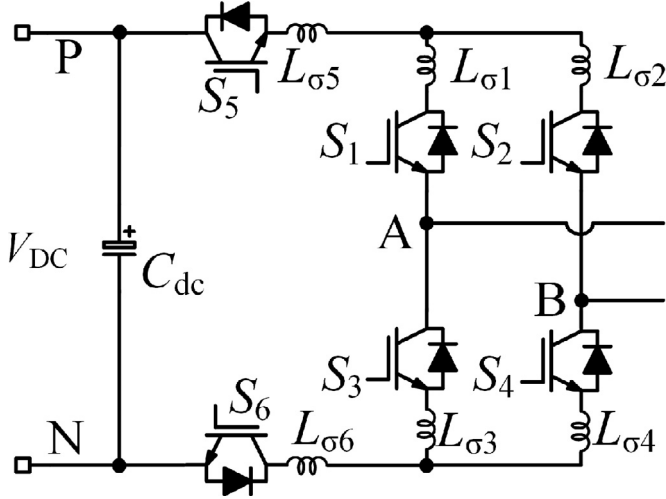


Fig. 15. H6-DC-decoupling inverter-equivalent circuit with parasitic inductances, where  $L_{σ1-6}$  are the parasitic inductances of switches  $S_{1-6}$ .

Similarly, the commutation operation modes of the H5 topology in the positive half-cycle are shown in Fig. 14, which consider the parasitic inductances. The loop inductances of both the operation modes can be expressed as

$$L_{+V_{DC\_H5}} = L_{σ1} + L_{σ4} + L_{σ5} + L_{loop1} \quad (3)$$

$$L_{0\_H5} = L_{σ1} + L_{σ2} + L_{loop2} \quad (4)$$

which can illustrate that the loop inductance of the '+  $V_{DC}$ ' mode (i.e., see Fig. 14(a)) is larger than that of the '0' mode (i.e., see Fig. 14(b)). The EMI filter for the H5 inverter should be designed to suppress the oscillation in a large range of frequencies, which means a larger volume and a higher cost. When compared to the symmetrical full-bridge inverter, the volume of the heatsink and the EMI filter increase although the transformer is removed.

### 3.3. H6 DC-decoupling topology

As mentioned in Section 2, the H6 DC-decoupling topology adopts two additional active switches on the DC rails to distribute the switching losses. Compared to the H5 topology, it benefits the thermal design of the PCB and the lifetime of the entire inverter [28]. The equivalent schematic of the H6 DC-decoupling inverter with parasitic parameters is shown in Fig. 15, where DC-decoupling switches  $S_5$  and  $S_6$  are set at the positive and negative DC rails, respectively. The improved hybrid modulation with reactive power injection has been discussed for the H6 DC-decoupling in [28,48], as shown in Fig. 16. During the positive half-cycle,  $S_1$  is in ON-state, and  $S_2$  and  $S_{4-6}$  complementarily change at

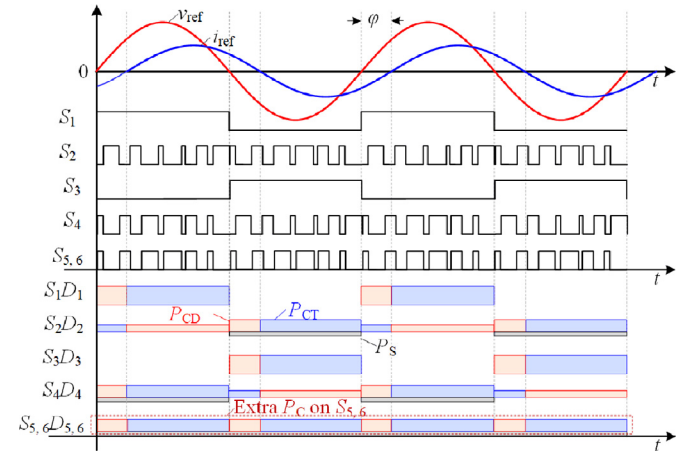


Fig. 16. H6-DC-decoupling inverter-modulation method and loss distribution.

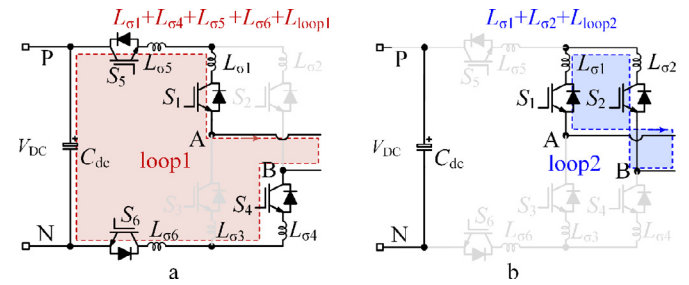


Fig. 17. H6-DC-decoupling inverter-operation modes in the positive half-cycle  
a '+  $V_{DC}$ ' mode  
b '0' mode.

the switching frequency. While at the negative half-cycle,  $S_3$  is ON, and  $S_4$  and  $S_{2,5,6}$  are commutating at the same high frequency. Although the structure is fully symmetrical, the junction capacitances of switches will affect the leakage current with the hybrid UPWM method, where the detail has been analyzed in [28]. As for the loss distribution, the extra switch  $S_6$  on the negative rail increases the conduction losses, yet shares the switching losses with  $S_5$ .

According to the fully symmetrical structure and the modulation scheme in Fig. 16, the oscillation performance of the H6 DC-decoupling inverter is the same at both the positive and negative half-cycles. Fig. 17 presents the commutation modes in positive half-cycle, where the loop inductances at the '+  $V_{DC}$ ' mode (i.e., Fig. 17(a)) and '0' mode (i.e., Fig. 17(b)) can be given as

$$L_{+V_{DC\_H6DC}} = L_{σ1} + L_{σ4} + L_{σ5} + L_{σ6} + L_{loop1} \quad (5)$$

$$L_{0\_H6DC} = L_{σ1} + L_{σ2} + L_{loop2} \quad (6)$$

which reveals that the parasitic inductances of switches in Loop 1 are doubled compared to that in Loop 2. That is, the oscillation frequency is larger than the H5 topology.

It should be noted that the modulation method for H6-DC-decoupling NPC topology in [43] has a higher efficiency than the improved modulation scheme in Fig. 16 [28]. In [43], all the switches of the full-bridge part (i.e.,  $S_{1-4}$ ) are turned on during the freewheeling period, achieving two freewheeling current paths (i.e., low conduction losses) and eliminating the influence of the unbalanced junction capacitances.

### 3.4. H6-AC-decoupling topology

Fig. 18 shows the topology of one typical H6-AC-decoupling inverter, where the structure is symmetrical. Two extra diodes  $D_{b1}$  and  $D_{b2}$  are

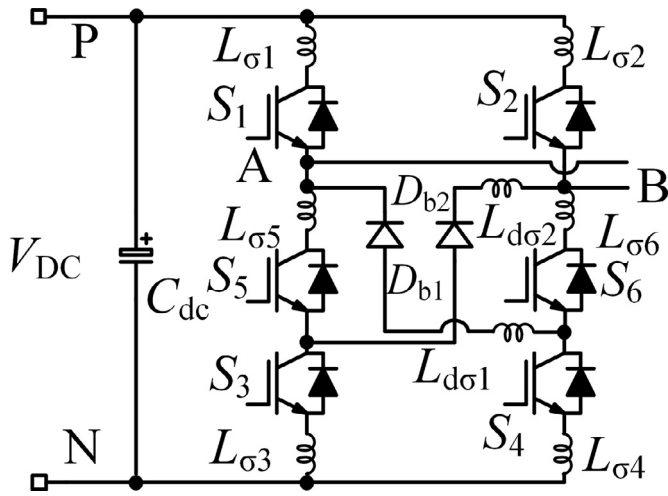


Fig. 18. One typical H6-AC-decoupling inverter-equivalent circuit with parasitic inductances, where  $L_{\sigma 1-6}$  are the parasitic inductances of switches  $S_{1-6}$ , and  $L_{d\sigma 1}$  and  $L_{d\sigma 2}$  are the parasitic inductances of diodes  $D_{b1}$  and  $D_{b2}$ .

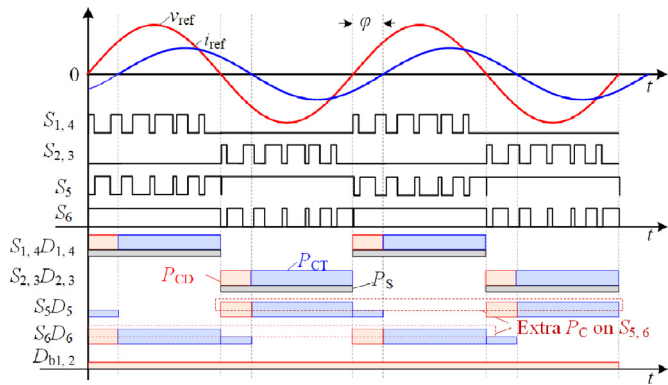


Fig. 19. H6-AC-decoupling inverter-modulation scheme and loss distribution.

added in the middle of the two bridge-legs along with  $S_5$  and  $S_6$ , providing the freewheeling path and the AC-decoupling. Although the H6-AC-decoupling has an improved performance in leakage current suppression, the conversion efficiency is compromised since the current should flow through the two more extra active switches  $S_5$  and  $S_6$  [32,33]. The hybrid modulation method with reactive power injection applied in the H6-AC-decoupling inverter is detailed in Fig. 19. The switch  $S_6$  is ON in the positive half-cycle, and  $S_{1,4}$  and  $S_5$  are changing in the switching frequency to generate the modulation voltage of  $+V_{DC}$  and 0. On the contrary,  $S_5$  is in ON state in the negative half-cycle, and  $S_{2,3}$  and  $S_6$  switch at a high frequency, achieving the output voltage of  $-V_{DC}$  and 0. Since both  $S_5$  and  $S_6$  are ON in the freewheeling period, the hybrid modulation method can enable the bidirectional current path (i.e., reactive power injection). It can be seen from Fig. 19 that  $S_5$  and  $S_6$  have extra conduction losses, but the loss distribution is balanced in  $S_5$  and  $S_6$ .

The H6-AC-decoupling topology in Fig. 18 has a symmetrical structure. Therefore, the commutation oscillation performances in the positive and negative half-cycles are the same, where Fig. 20(a) and (b) show the switching modes of  $‘+V_{DC}’$  and  $‘0’$ , respectively. Correspondingly, the loop inductances in those two modes can be expressed as

$$L_{+V_{DC},H6AC} = L_{\sigma 1} + L_{\sigma 4} + L_{\sigma 5} + L_{loop1} \quad (7)$$

$$L_{0,H6AC} = L_{d\sigma 2} + L_{\sigma 6} + L_{loop2} \quad (8)$$

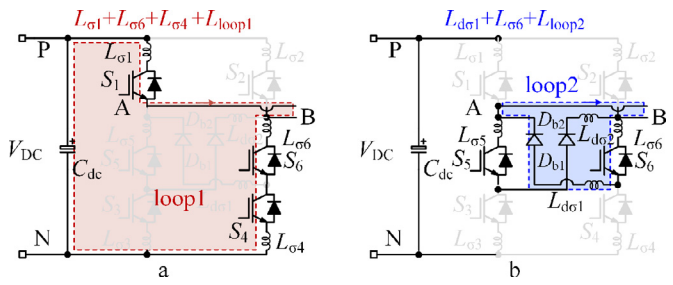


Fig. 20. H6-AC-decoupling inverter-commutation modes, where  $L_{loop1}$  and  $L_{loop2}$  are the PCB routing inductances

a  $‘+V_{DC}’$  mode  
b  $‘0’$  mode.

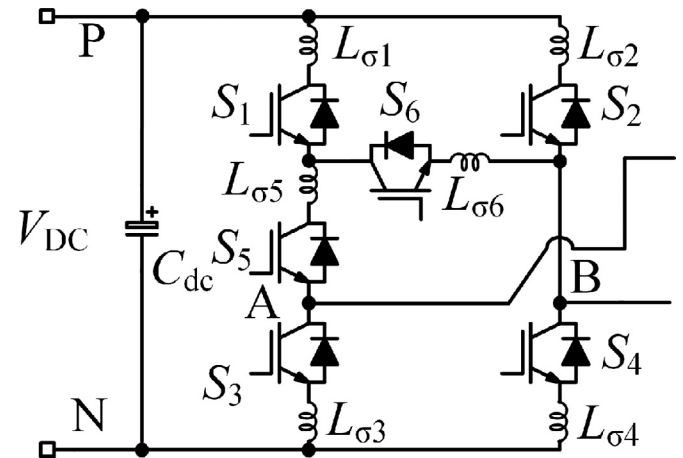


Fig. 21. Hybrid-bridge H6 inverter-equivalent circuit with parasitic inductances, where  $L_{\sigma 1-6}$  are the parasitic inductances of switches  $S_{1-6}$ .

where the parasitic inductor of diodes  $D_{b1}$  and  $D_{b2}$  are equal, i.e.,  $L_{d\sigma 1} = L_{d\sigma 2}$ . Compared the loop inductors in Eqs. (7) and (8) with that of the H5 topology, they are almost similar if  $L_{d\sigma 1,2}$  are equal to  $L_{\sigma 1-6}$ . However, the H6-AC-decoupling inverter has better performance in loss distribution.

### 3.5. Hybrid-bridge H6 topology

The hybrid-bridge H6 topology provides a bidirectional freewheeling path with two asymmetrical active switches, as shown in Fig. 21. As presented in Fig. 21, one additional switch is set on one bridge-leg, while another is connecting the negative terminals of both two upper switches of the bridge-legs. Compared with the H6-bypass topology in Fig. 5(c) [30], the hybrid-bridge H6 inverter has higher efficiency since the current only flows through two switches during the negative half-cycle. Fig. 22 shows the hybrid modulation method with reactive power injection. In the positive half-cycle,  $S_5$  is ON, and  $S_{1,4}$  and  $S_6$  commute at the switching frequency. In the negative half-cycle,  $S_6$  is in ON-state, and  $S_{2,3}$  and  $S_5$  complementarily switch at the same high frequency. In that case, the hybrid-bridge H6 inverter can achieve three-level voltages, i.e.,  $+V_{DC}$ , 0, and  $-V_{DC}$ . As depicted in Fig. 22,  $S_6$  is ON during the negative half-cycle, and yet, there is no current flowing through  $S_6$  during the  $‘+V_{DC}’$  mode. Therefore, the losses on  $S_5$  and  $S_6$  are unbalanced although the conduction losses are relatively less than the H6-bypass topology in Fig. 5(c) and the H6-AC-decoupling topology in Fig. 6(a).

Due to the asymmetrical structure, the oscillation performances in positive and negative half-cycles are different, Figs. 23(a)-(c) show the commutation modes of  $‘+V_{DC}’$ ,  $‘0’$ , and  $‘-V_{DC}’$ , respectively. Accordingly, the loop inductances in each mode can be calculated by

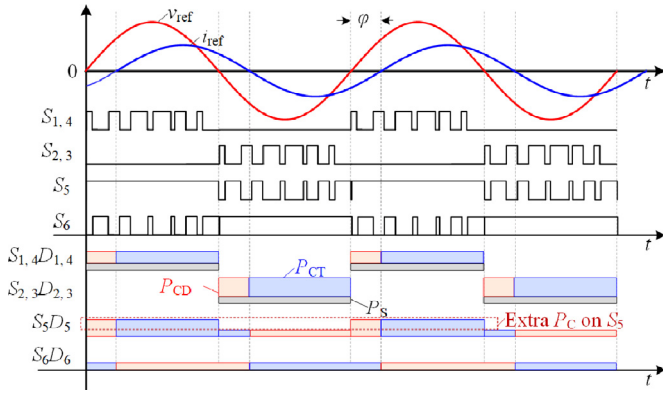


Fig. 22. Hybrid-bridge H6 inverter-modulation scheme and loss distribution.

$$L_{+V_{DC\_HB}} = L_{\sigma 1} + L_{\sigma 4} + L_{\sigma 5} + L_{loop1} \quad (9)$$

$$L_{0\_HB} = L_{\sigma 5} + L_{\sigma 6} + L_{loop2} \quad (10)$$

$$L_{-V_{DC\_HB}} = L_{\sigma 2} + L_{\sigma 3} + L_{loop3} \quad (11)$$

Since the parasitic inductances of switches and loop inductances are assumed to be the same, the oscillation frequency of the hybrid-bridge H6 inverter in positive half-cycle is similar to that of the H5 topology, while being the same as the oscillation performance of the full-bridge inverter in the negative half-cycle. In a word, the hybrid-bridge H6 inverter can achieve higher efficiency with the same EMI filter condition as what the H5 topology does.

### 3.6. HERIC topology

According to the HERIC topology, [36], two active switches and two diodes compose the AC-decoupling circuit. Fig. 24 shows the HERIC inverter using the AC-decoupling circuit with two active switches. In that case, the device count is reduced without any performance com-

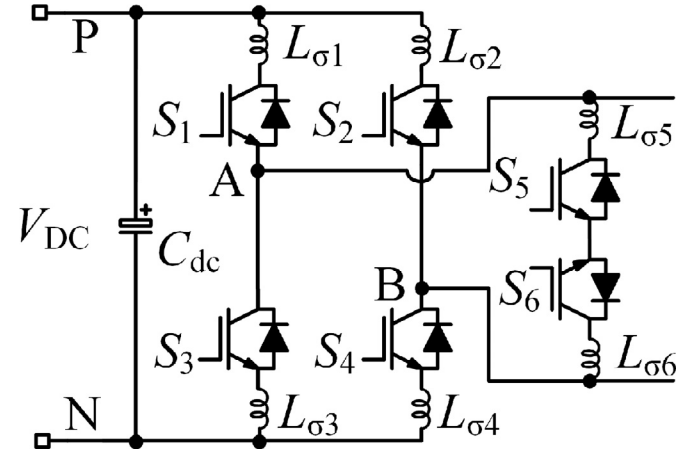


Fig. 24. HERIC inverter- equivalent circuit with parasitic inductances, where  $L_{\sigma 1-6}$  are the parasitic inductances of switches  $S_{1-6}$ .

promise. The hybrid UPWM method with reactive power injection and the corresponding loss distribution is then shown introduced in Fig. 25. At the positive half-cycle,  $S_6$  is in ON-state, and  $S_{1,4}$  and  $S_5$  switch at a high frequency to achieve the output voltage of  $+V_{DC}$  and 0. At the negative half-cycle,  $S_5$  is ON, and  $S_{2,3}$  and  $S_6$  change at the switching frequency to generate the voltage of  $-V_{DC}$  and 0. As for the loss distribution demonstrated in Fig. 25, the switching losses are equally shared by  $S_{1-4}$ , and only conduction losses are generated on  $S_5$  and  $S_6$ . The fully symmetrical structure with the hybrid modulation can achieve balanced losses among switches  $S_{1-4}$  and the AC-decoupling switches  $S_{5,6}$ . Besides, the total power losses of the HERIC topology are the same as the full-bridge inverter with the hybrid UPWM method.

Referring to the commutation operation modes, Fig. 26 exhibits the switching states of the HERIC in the positive half-cycle. The corresponding loop inductances can be expressed as

$$L_{+V_{DC\_HERIC}} = L_{\sigma 1} + L_{\sigma 4} + L_{loop1} \quad (10)$$

$$L_{0\_HERIC} = L_{\sigma 5} + L_{\sigma 6} + L_{loop2} \quad (11)$$

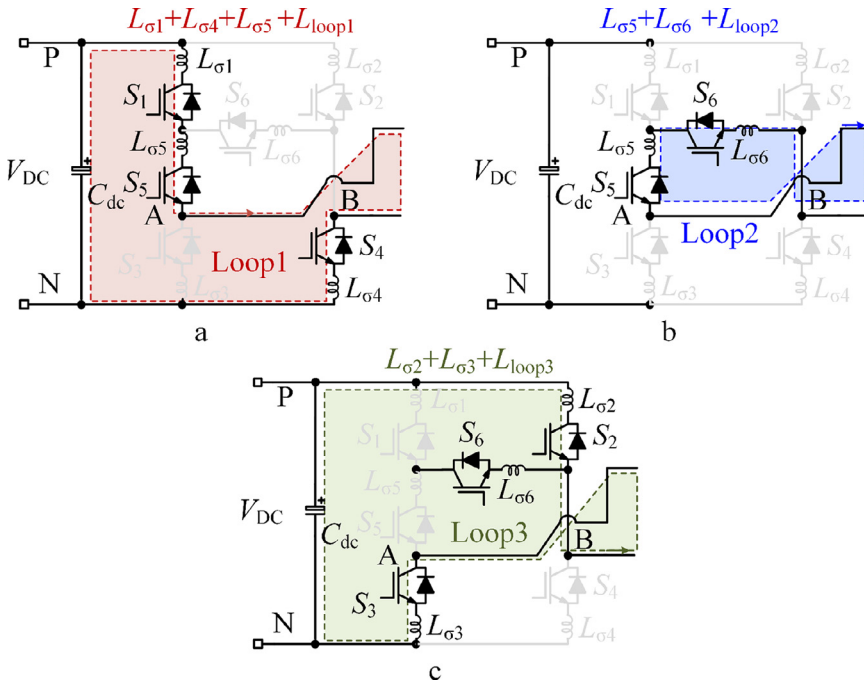


Fig. 23. Hybrid-bridge H6 inverter-commutation modes, where  $L_{loop1}$ ,  $L_{loop2}$  and  $L_{loop3}$  are the PCB routing inductances

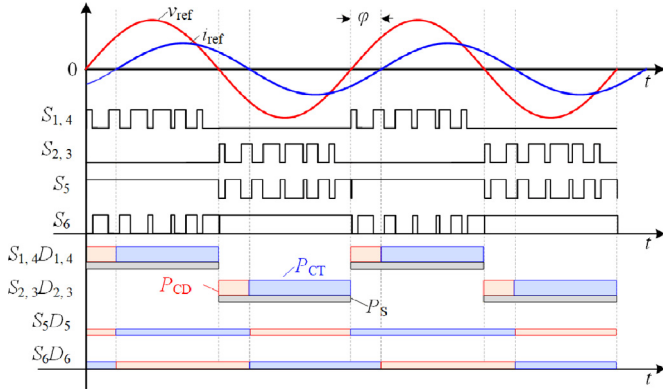
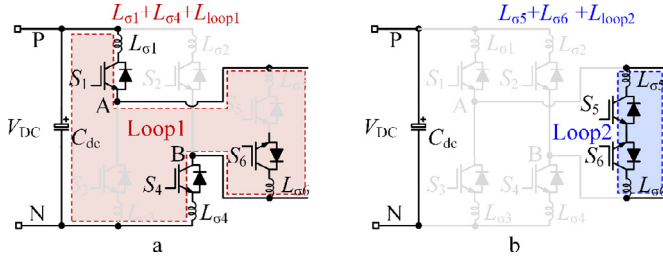
- a '+  $V_{DC}$ ' mode
- b '0' mode
- c '-  $V_{DC}$ ' mode.

**Table 1**

Performance comparison of the full-bridge type PV inverters with the hybrid UPWM method [48].

| Converter                   | Semiconductor devices No. |       | Leakage current suppression | Efficiency | Power density | Losses balance | Oscillation performance |
|-----------------------------|---------------------------|-------|-----------------------------|------------|---------------|----------------|-------------------------|
|                             | IGBT                      | Diode |                             |            |               |                |                         |
| Full-bridge                 | 4                         | 0     | Non                         | ++++       | +             | ++             | +++                     |
| H5                          | 5                         | 0     | +                           | ++         | ++            | +              | ++                      |
| DC-decoupling H6 [28]       | 6                         | 0     | +                           | +          | ++            | +++            | +                       |
| AC-decoupling H6 [32], [33] | 6                         | 2     | ++                          | +          | ++            | +++            | ++                      |
| Mid-switch H6 [35]          | 6                         | 2     | ++                          | +          | ++            | +++            | ++                      |
| Hybrid-bridge H6 [34]       | 6                         | 0     | +++                         | +++        | +++           | ++++           | ++                      |
| HERIC [36]                  | 6                         | 0     | +++                         | ++++       | ++++          | +++++          | +++                     |

Note: The more '+' means the higher performance, representing the comparative level. 'Non' represents there is no such function.

**Fig. 25.** HERIC inverter-hybrid modulation scheme and loss distribution.**Fig. 26.** HERIC inverter-commutation modes in the positive half-cycle, where  $L_{loop1}$  and  $L_{loop2}$  are the PCB routing inductances

a '+  $V_{DC}$ ' mode  
b '0' mode.

By comparison, the loop inductances in each operation mode are almost the same if only considering the parasitic inductance of switches. Consequently, the oscillation frequency has a small range, reducing the design burden of the EMI filter.

#### 4. Comparison discussion

The above five single-phase PV inverters under the hybrid UPWM method with reactive power injection have representative characteristics in terms of structure, leakage current suppression, conversion efficiency, loss distribution, and commutation oscillation. Since the NPC type inverters are almost based on DC/AC decoupling inverters, their performances of loss distribution and commutation oscillation under the hybrid modulation scheme are similar to DC/AC decoupling ones. Therefore, the performance of full-bridge type inverters compared in Table 1 has not included the NPC type. The specific discussions seen from the perspective of commutation oscillation and loss distribution are as follows.

- 1) Commutation oscillation: Considering the design of the EMI filter, it is expected that the frequency range of the commutation oscillation

is small in the PV inverters. Thus, it is better to ensure the symmetrical loop inductances of all the commutation operation modes. From this, the full-bridge inverter and the HERIC have the best performance, while the DC-decoupling H6 inverter is the worst, as summarised in Table I. To improve this, the inductances in the loop routine can be improved by the PCB design, balancing the total loop inductances.

- 2) Loss distribution: According to the modulation scheme and loss distribution performance in Figs. 10,13,16,19, and 22, the HERIC has the best performance in losses balance, then decreasing, in the order of the hybrid-bridge inverter, the AC decoupling inverters [32,33] and the DC decoupling inverter [28], the full-bridge inverter and the H5 inverter [27]. The stable junction temperature of the power devices (i.e., relating to the balanced losses) benefits the lifetime of power devices [64]. When the losses unbalance is dominated by the conduction losses, the redundant design is a promising way, such as the bypass DC-decoupling H6 topologies in Fig. 5(c) (i.e., improved topology based on the H5 topology). While the unbalanced losses of the power devices are caused by the different switching frequencies, an improved modulation method is a proper solution, such as the circulating modulation control in [65] for the full-bridge inverter.

According to the performance comparison in Table I, the full-bridge inverter with the hybrid modulation method [48] has a fewer device count, higher efficiency, and better oscillation performance, and yet it needs extra transformers. Comparatively, the HERIC inverter is the most cost-effective one among those representative transformerless full-bridge type PV inverters, which can achieve an optimal trade-off of efficiency, leakage current suppression, losses balance, and commutation oscillation. In the future, the WBG devices will replace the Si switches gradually. The oscillation will be paid more and more attention due to strict EMI requirements [53,54]. To better the application of WBG devices, there are some challenges: 1) Building the EMI model from the semiconductor level to power system level; 2) accurately extracting parasitic parameters for modeling; 3) Methodology developing to alleviate the EMI issues, such as parasitic parameter reduction. In addition, the loss distribution has a close relationship with the heatsink design, impacting power density, reliability, and system cost. Many excellent redundant designs, improved modulation methods, and thermal control strategies will be encouraged.

#### 5. Case studies

To demonstrate the loss distribution analysis under the hybrid modulation method, simulations are carried out on a full-bridge inverter prototype in PLECS. The thermal-loss models of active switches  $S_{1-4}$  are built according to the device datasheet (i.e., Infineon IGBT-FS25R12KT3). The system parameters are the DC-link voltage  $V_{DC} = 365$  V, the output AC voltage  $v_{ac} = 220$  V (the root mean square) / 50 Hz, the output power  $P = 5$  kW, and the switching frequency  $f_{sw} = 20$  kHz. There are two modulation methods compared in the full-bridge inverter, where the power factor angle  $\varphi$  is a variable between 0 to  $\pi$ .



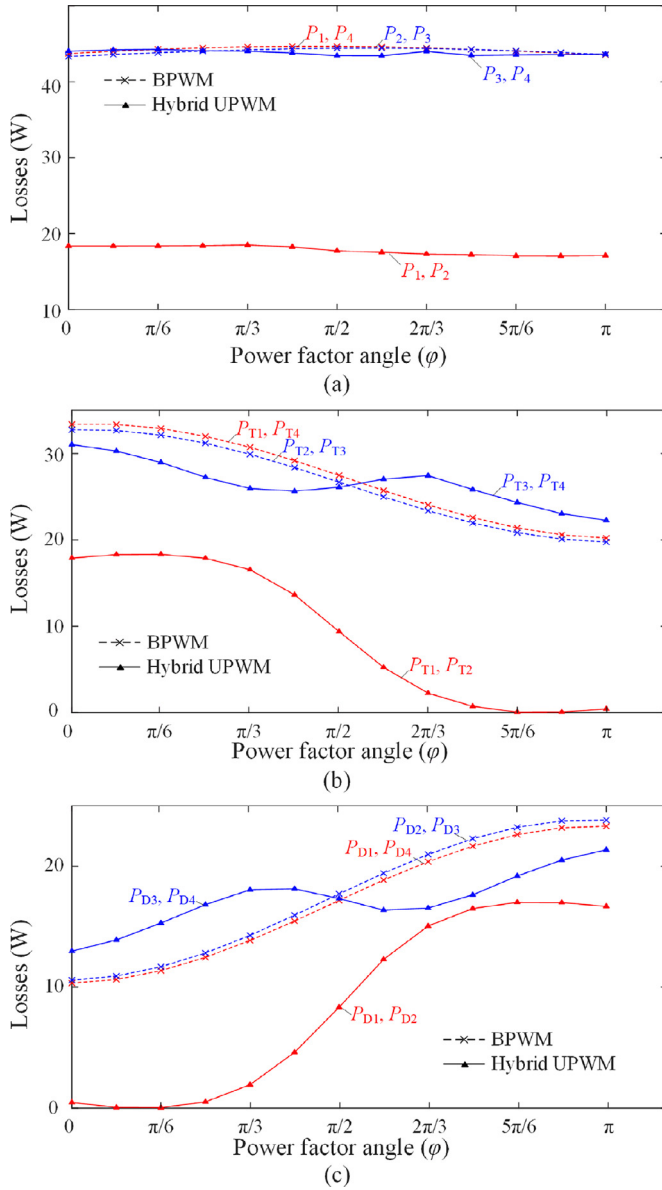


Fig. 27. Comparison of loss distribution of the full-bridge inverter, where  $P_{CT}$ ,  $P_{CD}$  and  $P_S$  are the conduction losses on IGBT, the conduction losses on the anti-parallel diodes, and the switching losses when the full-bridge inverter operates under various power factors.

- a Total losses
- b Losses on unidirectional switches
- c Losses on anti-parallel diodes.

Fig. 27 shows the comparison results, in which total losses of devices ( $P_{1-4}$ ), losses of unidirectional switches ( $P_{T1-4}$ ), and losses of anti-parallel diodes ( $P_{D1-4}$ ) are depicted in Fig. 27(a)-(c), respectively. As shown in Figs. 27(a), the total losses of semiconductor devices  $S_{1-4}$  in the full-bridge inverter are equally distributed under the BPWM method. The losses of  $S_{1,3}$  are far less than that of  $S_{2,4}$ . When the full-bridge inverter adopts the hybrid UPWM method [48]. However, the losses of the hybrid UPWM method are less than that of the BPWM. As presented in Fig. 27(b) and (c), the power losses of the body diodes and the unidirectional switches change with the power factor angle when the full-bridge inverter adopts both the BPWM and the hybrid UPWM methods. That is, the reactive power injection will influence the internal loss distribution of the power device, which can be considered in the power control strategy. In addition, the power losses of the unidirectional switches

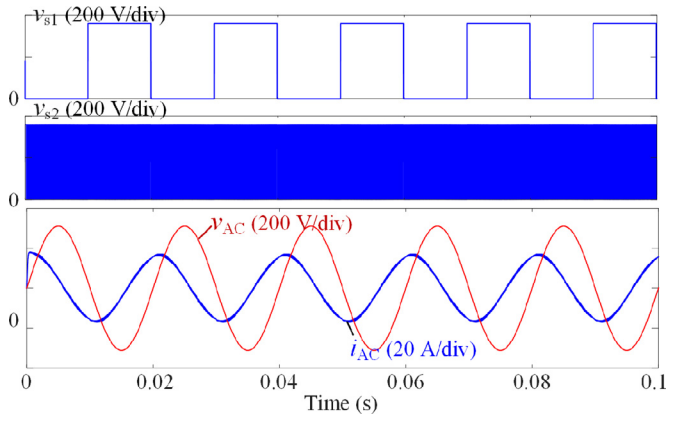


Fig. 28. Simulation performance of the full-bridge inverter with the hybrid UPWM method, where  $v_{s1}$ ,  $v_{s2}$  are the voltages of  $S_1$  and  $S_2$ , and  $v_{AC}$  and  $i_{AC}$  are the grid voltage and current.

and body diodes are identical when the full-bridge inverter employs the BPWM method.

Fig. 28 shows the modulation waveforms of the full-bridge inverter under the hybrid UPWM method, where  $v_{s1}$ ,  $v_{s2}$ ,  $v_{AC}$  and  $i_{AC}$  are the voltages of  $S_1$  and  $S_2$ , the grid voltage and current. As shown in Fig. 27,  $v_{s1}$  changes at the grid frequency and  $v_{s2}$  changes at a high frequency. The comparison results agree well with the theoretical analysis in Section 3.1. In all, the simulation results validate the loss distribution of the full-bridge inverter under the hybrid modulation method with reactive power injection.

## 6. Conclusion

In this paper, the full-bridge type PV inverters have been classified and reviewed according to the leakage current suppression. Then, the commutation oscillation and loss distribution performances have been analyzed in selected full-bridge PV inverters under the hybrid UPWM method with reactive power injection. The identical loop inductances in different commutation modes have good oscillation performance, benefiting the EMI filter design. Then, a comprehensive comparison of the full-bridge inverters has been presented in leakage current suppression, efficiency, loss distribution, oscillation, and system costs. Finally, simulations validated the analysis of loss distribution under the hybrid modulation method with reactive power injection in the full-bridge inverter.

## Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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## Data availability statement

Data sharing does not apply to this article as no datasets were generated or analyzed during the current study

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