

Downsampling of DFT Precoded Signals for the AWGN Channel

Tobias Lindstrøm Jensen, Karsten Fyhn, Thomas Arildsen, Torben Larsen

Aalborg University,
Faculty of Engineering and Science,
Department of Electronic Systems, Denmark

Dec. 13, 2012

Outline

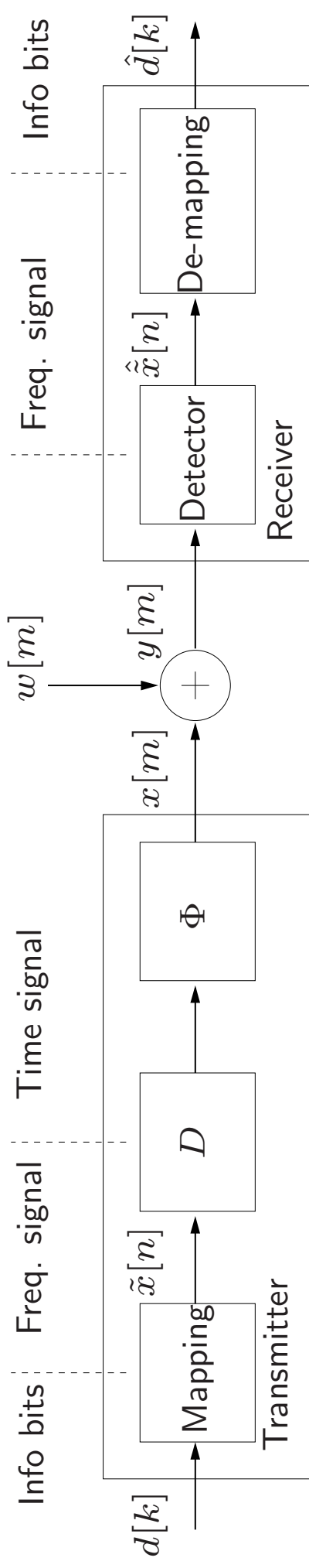
- **Motivation for downsampling/undersampling**
- Detection of downsampled signals
- Summary and discussion

Outline

- Compressed sensing (Candès, Romberg & Tao 2006, Donoho 2006)
 - Not always necessary to take N linear measurements to reconstruct a length N signal if the signal obeys certain structure.
 - Most focus on signals with sparse structure but other structure is also considered now (Davenport, Boufounos, Wakin & Baraniuk 2010, Donoho & Tanner 2010*b*).
- Can we use compressed sensing ideas to
 - reduce receiver ADC sampling rate?
 - form new error resistant constellation schemes?
- What is the cost?
 - Performance loss?
 - More complex detection algorithms?

Model

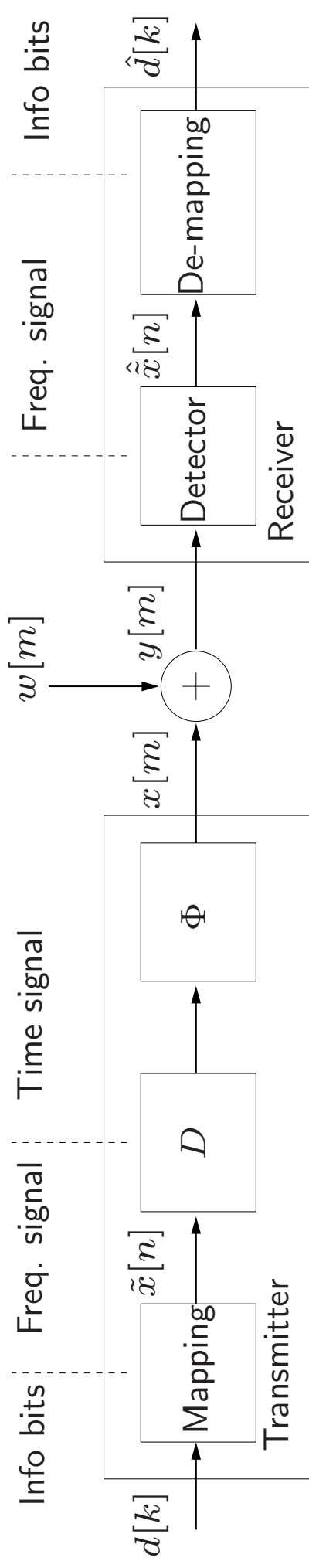
- Consider downsampled DFT precoded signals in the AWGN channel.



- *i.i.d.* bit stream $d[k] \in \{0, 1\}$ with $P(d[k] = 1) = P(d[k] = 0) = \frac{1}{2}$.

Model

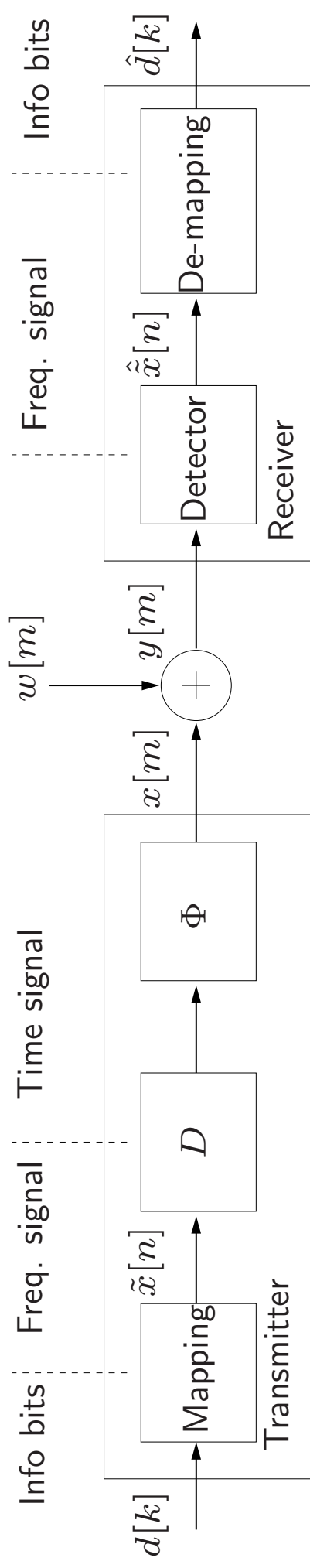
- Consider downsampled DFT precoded signals in the AWGN channel.



- *i.i.d.* bit stream $d[k] \in \{0, 1\}$ with $P(d[k] = 1) = P(d[k] = 0) = \frac{1}{2}$.
- Constellations symbols $\tilde{x}[n] \in \mathcal{S}^N \subset \mathbb{C}^N$, $E[|\tilde{x}[n]|^2] = 1$, $|\mathcal{S}| = L$.

Model

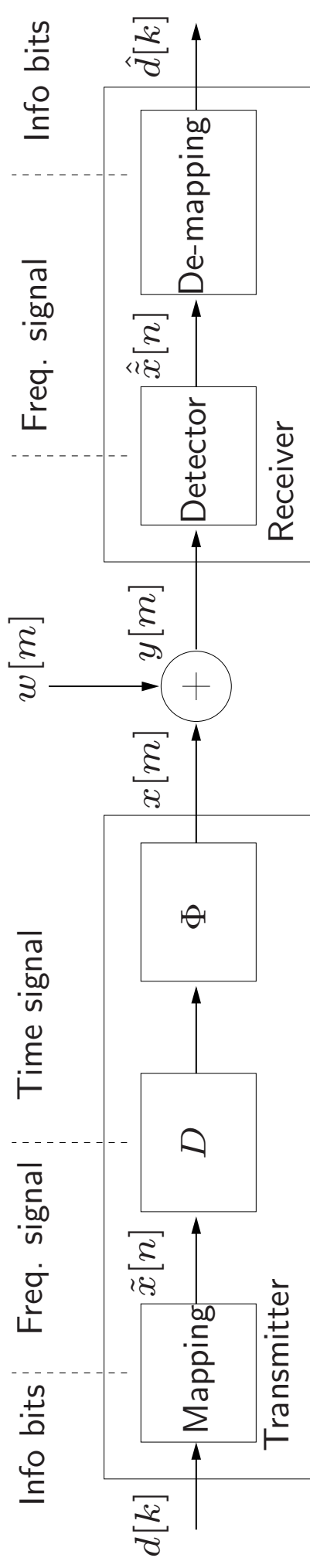
- Consider downsampled DFT precoded signals in the AWGN channel.



- *i.i.d.* bit stream $d[k] \in \{0, 1\}$ with $P(d[k] = 1) = P(d[k] = 0) = \frac{1}{2}$.
- Constellations symbols $\tilde{x}[n] \in \mathcal{S}^N \subset \mathbb{C}^N$, $E[|\tilde{x}[n]|^2] = 1$, $|\mathcal{S}| = L$.
- Normalized inverse DFT matrix $D \in \mathbb{C}^{N \times N}$ with $\|Dz\|_2 = \|z\|_2, \forall z \in \mathbb{C}^N$. Noise $E[|w[m]|^2] = \sigma^2$.

Model

- Consider downsampled DFT precoded signals in the AWGN channel.



- *i.i.d.* bit stream $d[k] \in \{0, 1\}$ with $P(d[k] = 1) = P(d[k] = 0) = \frac{1}{2}$.
- Constellations symbols $\tilde{x}[n] \in \mathcal{S}^N \subset \mathbb{C}^N$, $E[|\tilde{x}[n]|^2] = 1$, $|\mathcal{S}| = L$.
- Normalized inverse DFT matrix $D \in \mathbb{C}^{N \times N}$ with $\|Dz\|_2 = \|z\|_2, \forall z \in \mathbb{C}^N$. Noise $E[|w[m]|^2] = \sigma^2$.
- Information of each symbol is spread over the whole time domain.

Downsampling Matrix

- The time symbols are then *randomly punctured* by block processing of N to M time symbols with Φ .
- One realization is (each row of Φ contains exactly one element with a one):

$$\Phi = \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 & 0 \\ 0 & 0 & 1 & \cdots & 0 & 0 \\ \vdots & \cdots & \cdots & \ddots & \vdots & \vdots \\ 0 & \cdots & \cdots & \cdots & 1 & 0 \end{bmatrix}. \quad (1)$$

- This gives the *downsampling factor*

$$\kappa = \frac{M}{N}. \quad (2)$$

Signal-to-noise Ratio

- The signal-to-noise-ratio (SNR) is given by

$$\frac{E_s}{N_0} = \frac{E[|x[m]|^2]}{E[|w[m]|^2]} = \frac{1}{\sigma^2}. \quad (3)$$

- The SNR per information bit is given by

$$\frac{E_b}{N_0} = \frac{E_s}{N_0} \frac{1}{R} = \frac{\kappa}{\sigma^2 \log_2(L)}, \quad R = \frac{\log_2(L)}{\kappa}. \quad (4)$$

- The rate R both depends on the constellation size L as well as the downsampling factor, such that the energy per bit is reduced by the factor κ .

Detection Problem

- The maximum likelihood detection problem for $\Phi = I$ is

$$\hat{\tilde{x}}_{\text{ML}} = \underset{\tilde{x} \in \mathcal{S}^N}{\text{argmin}} \|D\tilde{x} - y\|_2 = \underset{\tilde{x} \in \mathcal{S}^N}{\text{argmin}} \|\tilde{x} - \tilde{y}\|_2 = h(\tilde{y}) \quad (5)$$

- $\tilde{y} = D^H y$, $\tilde{x} = [\tilde{x}[n'], \dots, \tilde{x}[n' + N - 1]]^T$, and the other symbols are formed in a similar way due to the block processing.
- The maximum likelihood detector for the downsampled signal is

$$\hat{\tilde{x}}_{\text{ML}} = \underset{\tilde{x} \in \mathcal{S}^N}{\text{argmin}} \|\Phi D\tilde{x} - y\|_2 \quad (6)$$

- In general this is NP-hard (Verdú 1989).
- How to form relaxations and analyze these?

Structured Description

- Consider so-called *s-simple* descriptions (Donoho & Tanner 2010a).
- Vectors $z \in [0, 1]^J$ with $J - s$ elements equal to exactly 0 or 1
- Let $A \in \mathbb{R}^{H \times J}$, $H \leq J$
 $b = Az$. (7)

- We can then reconstruct z with the convex feasibility problem

$$\hat{z} = \underset{Az=b, 0 \leq z_i \leq 1, i=1, \dots, J}{\operatorname{argmin}} 0. \quad (8)$$

- Then $\hat{z} = z$ with high probability for certain settings of the triplet (s, H, J) and A (Donoho & Tanner 2010a).
- Note, not a sparse description.

Relation to Downsampling DFT Precoded Signals

- Consider 0-simple vectors (all elements are exactly 0 or 1)
- BPSK: $\Re(\tilde{x}) = 2z - \mathbf{1}$, $\Im(\tilde{x}) = 0$, $\mathbf{1} = [1, 1, \dots, 1]^T$
- 0-simple vectors have phase-transition at $\frac{H}{J} = \frac{1}{2}$ (succeeds with high probability at higher rate and fails at lower rate).
- For the noise-less case $w[m] = 0$ ($\sigma^2 = 0$) we then have
 - BPSK phase-transition at $\kappa = \frac{M}{N} = \frac{1}{4}$
 - QPSK phase-transition at $\kappa = \frac{M}{N} = \frac{1}{2}$

Detection via Convex Relaxation

- Consider the following ML estimation of the model $b = Az + e$ with e *i.i.d.* Gaussian noise

$$\hat{z}_{\text{ML}} = \underset{z_i \in \{0,1\}, i=1, \dots, J}{\operatorname{argmin}} \|Az - b\|_2. \quad (9)$$

- Convex relaxation

$$\hat{z}_{\text{ML-CR}} = \underset{0 \leq z_i \leq 1, i=1, \dots, J}{\operatorname{argmin}} \|Az - b\|_2. \quad (10)$$

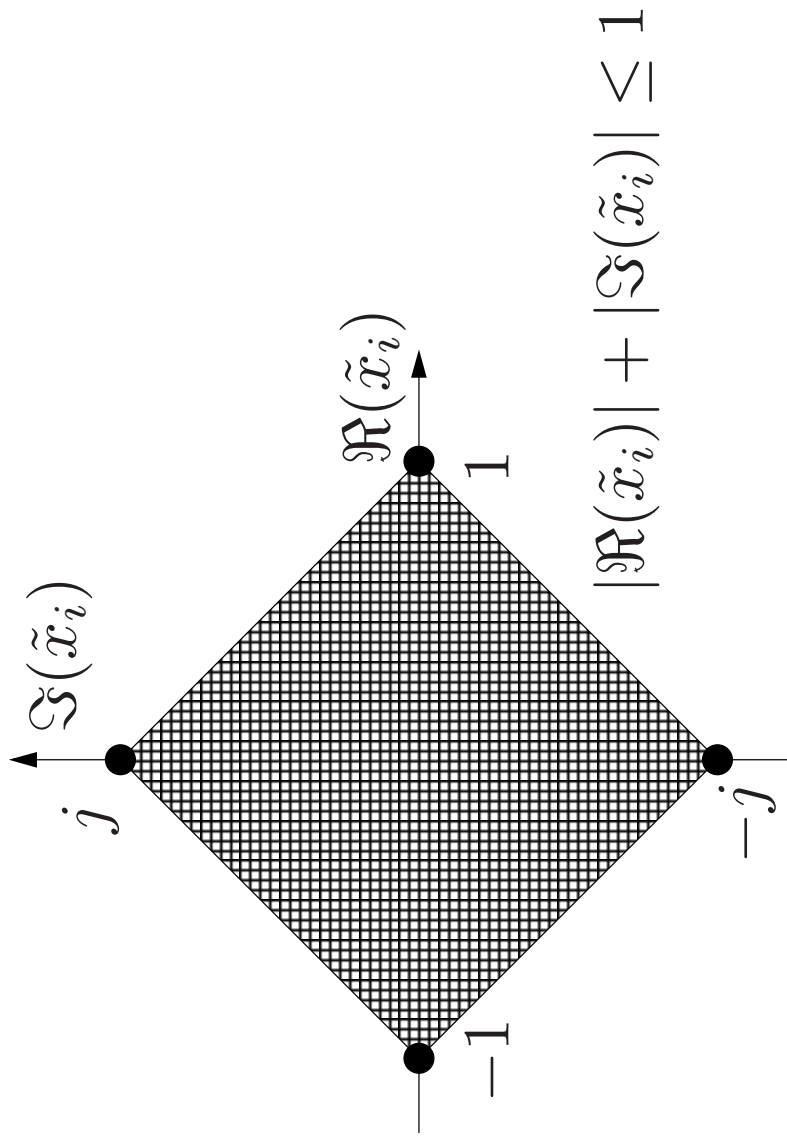
- BPSK detection is then

$$\hat{\tilde{x}}_{\text{ML-CR}} = \underset{-1 \leq \mathfrak{R}(\tilde{x}_i) \leq 1, \Im(\tilde{x}_i) = 0, i=1, \dots, N}{\operatorname{argmin}} \|\Phi D \tilde{x} - y\|_2. \quad (11)$$

Interpretation of the Convex Relaxation

- QPSK detection is then

$$\hat{\tilde{x}}_{\text{ML-CR}} = \underset{|\Re(\tilde{x}_i)| + |\Im(\tilde{x}_i)| \leq 1, i=1, \dots, N}{\text{argmin}} \|\Phi D \tilde{x} - y\|_2. \quad (12)$$



Detection via Semidefinite Relaxation

- QPSK detection can be written as the quadratically constrained quadratic program

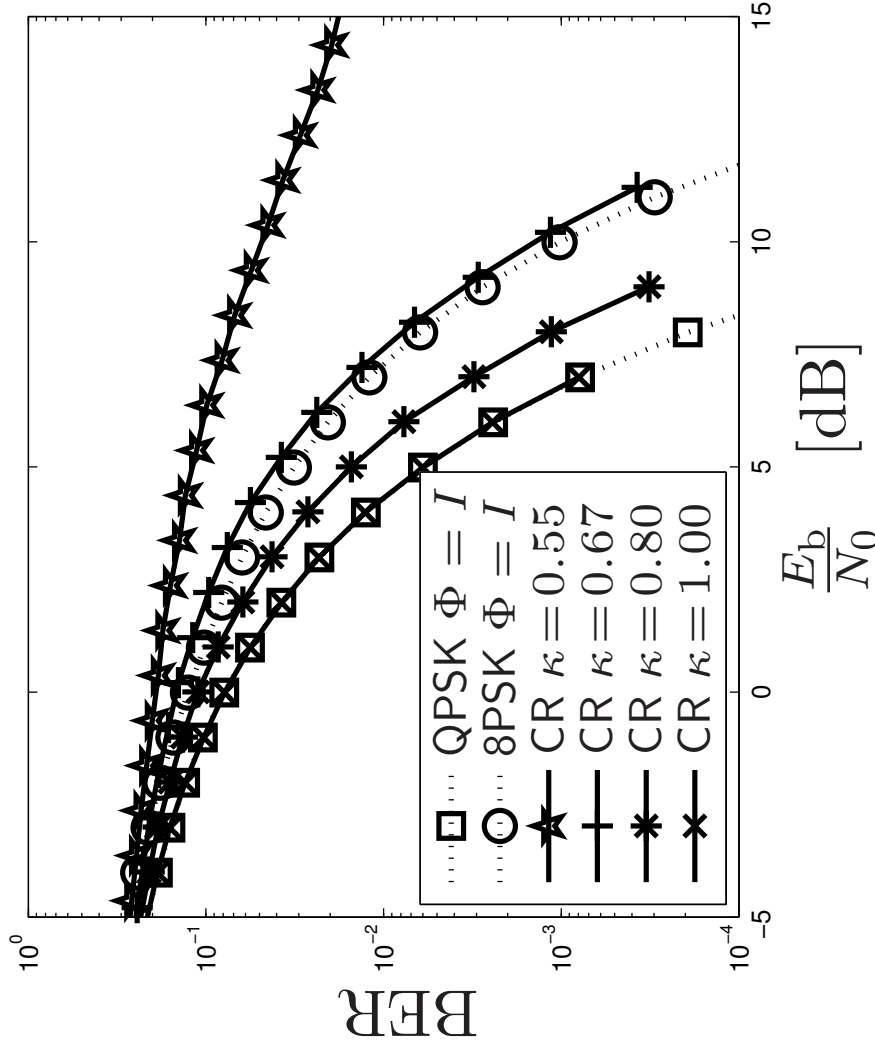
$$\begin{aligned} & \text{minimize} && \|\Phi D\tilde{x} - y\|_2^2 \\ & \text{subject to} && \Re(\tilde{x}_i)^2 + \Im(\tilde{x}_i)^2 = 1, \forall i = 1, \dots, N \\ & && \Re(\tilde{x}_i)\Im(\tilde{x}_i) = 0, \forall i = 1, \dots, N. \end{aligned} \quad (13)$$

- We then form a standard semidefinite relaxation, see *e.g.*, (Luo, Ma, So, Ye & Zhang 2010), $C \in \mathbb{R}^{2N+1 \times 2N+1}$, $X \in \mathbb{R}^{2N+1 \times 2N+1}$

$$\begin{aligned} & \text{minimize} && \text{tr}(CX) \\ & \text{subject to} && X_{i,i} + X_{i+N,i+N} = 1, \forall i = 1, \dots, N \\ & && X_{i,i+N} = 0, \forall i = 1, \dots, N \\ & && X_{2N+1,2N+1} = 1 \\ & && X \succeq 0 \end{aligned} \quad (14)$$

Simulations – BER – Convex Relaxation

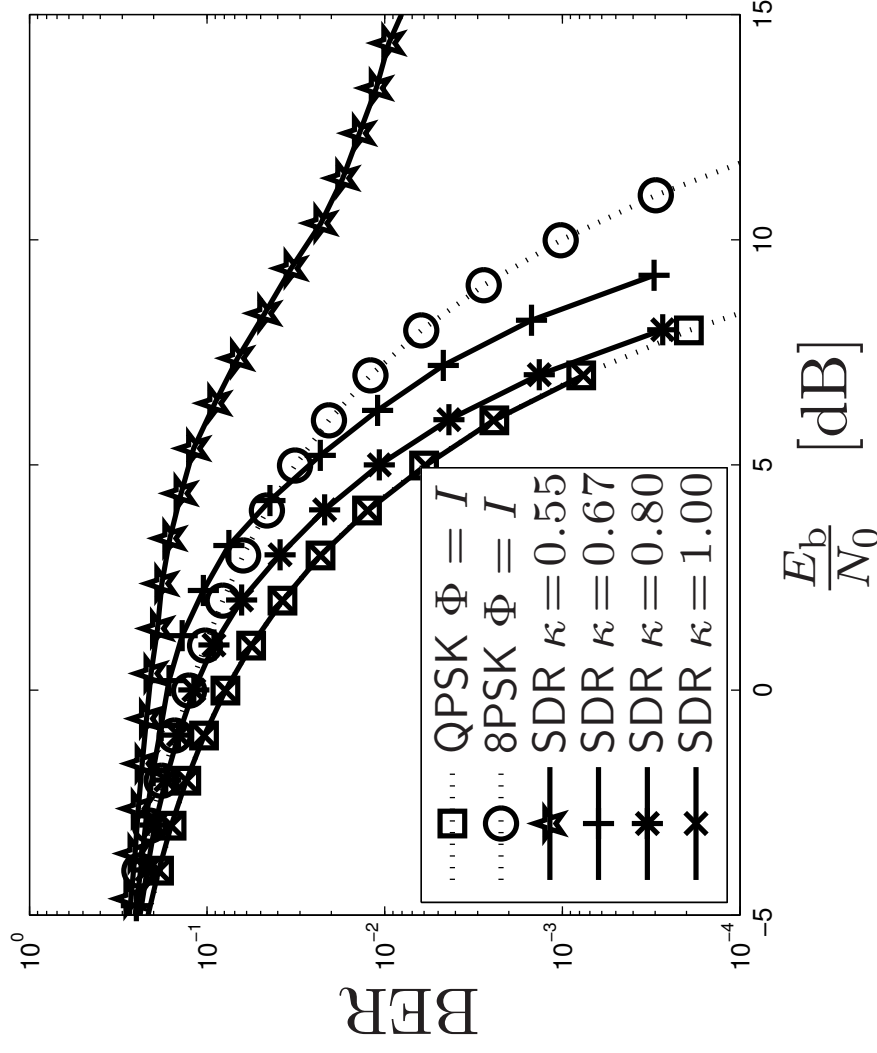
- Uncoded BER *i)* QPSK, 8PSK using $\Phi = I$ and optimal detection, *ii)* QPSK based CR detectors and downsampling factor κ .



- $\kappa = 0.67$ gives the same number of bits per symbol as 8PSK.

Simulations – BER – Semidefinite Relaxation

- Uncoded BER *i)* QPSK, 8PSK using $\Phi = I$ and optimal detection, *ii)* QPSK based SDR detectors and downsampling factor κ .



- BER $\approx 10^{-3}$: improves 8PSK with 1.8 dB (suboptimal detection).

Undersampling

- Place Φ (or ΦD) at the receiver instead

$$y = \Phi(Dx + w) = \Phi Dx + \tilde{w}, \quad \tilde{w} = \Phi w. \quad (15)$$

- Then $E[\tilde{w}\tilde{w}^H] = E[\Phi w w^H \Phi^H] = \sigma^2 I$, *i.e.*, the noise is still *i.i.d.* Gaussian.
- Goal: reduce sampling rate of the ADC.
- Using semidefinite relaxation:
 - Undersample $\kappa = 0.67$ with an SNR penalty of 3.5 dB.
 - Seems as a high penalty. Only exploit in case of excessive SNR.

Summary and Discussion

- Showed how to use structured descriptions to describe downsampled/undersampled detection problems.
- It is possible to form a more error-resilient signal than standard 8PSK using a downsampled DFT precoded QPSK signal with semidefinite based detection.
- The resulting detection problem is more computationally demanding but still polynomial-time.
- Future work:
 - How can the setup be used with other constellation schemes?
 - How efficiently can the detection problem be solved?

References

- Candès, E., Romberg, J. & Tao, T. (2006), 'Robust uncertainty principles: Exact signal reconstruction from highly incomplete frequency information', *IEEE Trans. Inf. Theory* **52**(2), 489–509.
- Davenport, M. A., Boufounos, P. T., Wakin, M. B. & Baraniuk, R. G. (2010), 'Signal processing with compressive measurements', *IEEE J. Sel. Topics Signal Process.* **4**(2), 445–460.
- Donoho, D. (2006), 'Compressed sensing', *IEEE Trans. Inf. Theory* **52**(4), 1289–1306.

- Donoho, D. L. & Tanner, J. (2010a), ‘Counting the faces of randomly-projected hypercubes and orthants, with application’, *Discrete Comput. Geom.* **43**(3), 522–541.
- Donoho, D. L. & Tanner, J. (2010b), ‘Precise undersampling theorems’, *Proc. of the IEEE* **98**(6), 913–924.
- Luo, Z.-Q., Ma, W.-K., So, A. M.-C., Ye, Y. & Zhang, S. (2010), ‘Semidefinite relaxation of quadratic optimization problems’, *IEEE Signal Process. Mag.*, *Special issue: Advances in Convex Optimization* **27**(3), 20 – 34.
- Verdú, S. (1989), ‘Computational complexity of optimum multiuser detection’, *Algorithmica* **4**(1-4), 303–312.